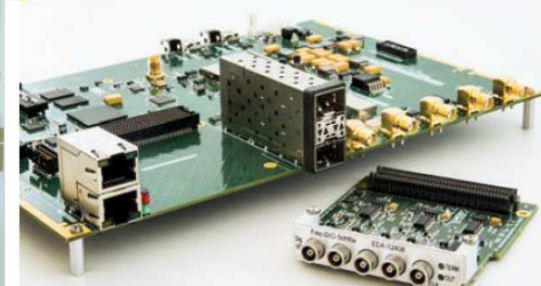
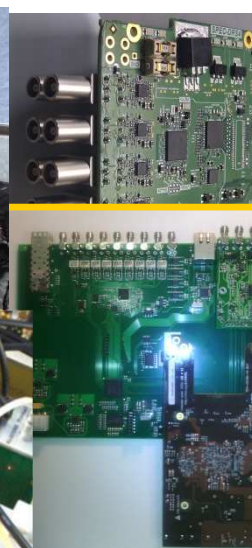
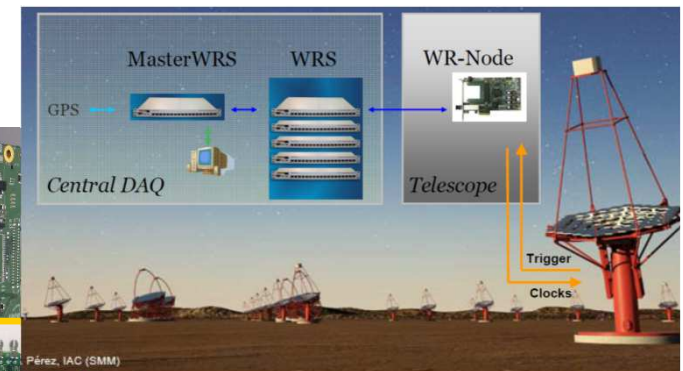


# Timing Systems for Particle and Astroparticle Physics

Ralf Wischnewski (DESY)

TorVergata/Rome, 21.3.2016



# “ ... Timing Systems for Particle and Astroparticle Physics ... ”

## Disclaimer

- **This talk is strongly biased by my recent experience**  
( after working with other “custom” timing systems in the past )
- **Executive summary:**  
**“There is One and only One Timing System for APP “.**
- **Focus is on Astroparticle. Particle physics may survive the old way.**
- **Accelerator applications will be briefly mentioned.**



# Outline

- **Precision timing in Astroparticle and Particle Physics Experiments**
  - Requirements, design principles
  - Avoid custom systems by using a “standard technique” ?
  
- **White Rabbit : an new technology for time-transfer**
  - Basics
  - Pro's and Pro's ( and no Con's )
  
- **White Rabbit in operation: experience with Tunka-HiSCORE**
  - Experience over 2012—2015
  - (some) conclusions for upcoming projects
  - Recent WR developments
  
- **Conclusions**

For more details see:

WR-HiSCORE: ICRC2013 (RW #1146, #1158, #1164)

ICRC2015 (RW PoS (1041) )

9<sup>th</sup> WR Workshop, Amsterdam, March 2016, RW

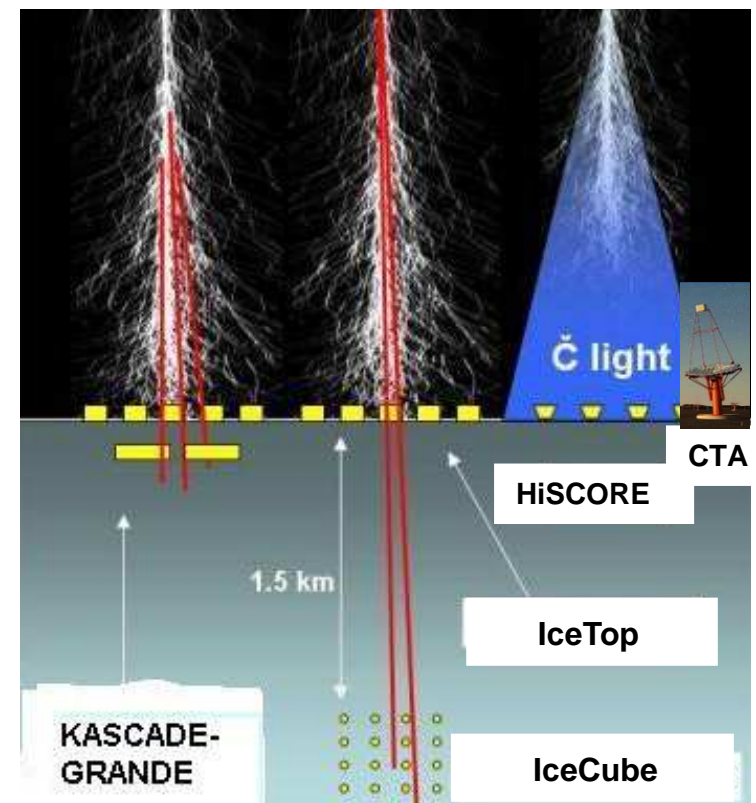
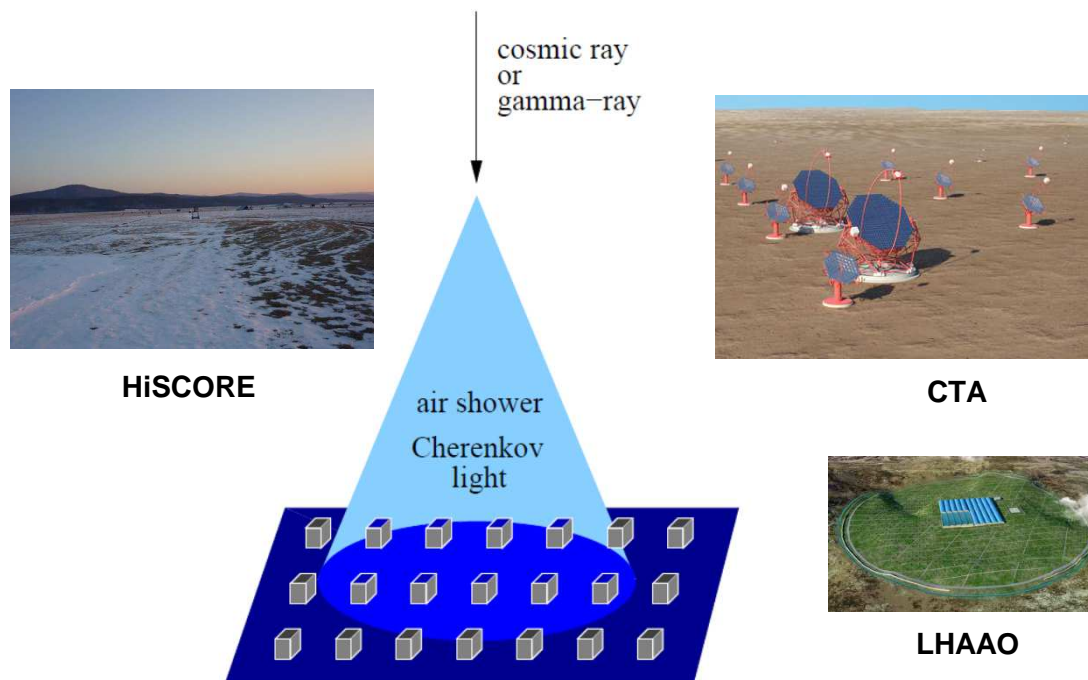
CERN-WR: <http://www.ohwr.org/projects/white-rabbit>

Thanks to my collaborators

M. Brueckner (PSI), A.Porelli (DESY)

# Large-scale Astroparticle Experiments ...

- > Are made of detector elements, distributed over large areas - like Sensor stations, Cerenkov Telescopes, Water-Tanks, Ice Tanks, PMTs in pressure housings
- > Need to measure spatial / temporal arrival pattern of light-/radio-flashes/particles...
  - Examples: Km3Net, Ice3, CTA, HiSCORE, IceCube, HAWC, LHAASO
- > Area:  $\text{km}^2 \dots 100\text{km}^2 \dots$
- > Timing precision: governs data quality !  
(sub-) nanosecond precision (sensor, media)



# ... and Timing (Trigger) concepts

## Centralized Arrays

In large-scale AP experiments it is still common to (like in compact accelerator experiments) to

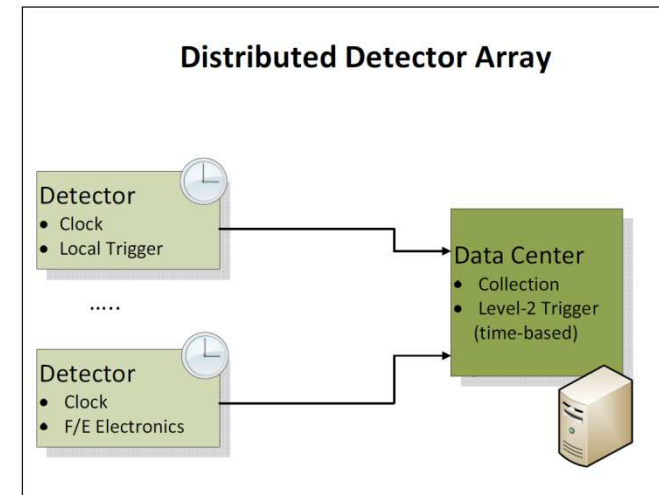
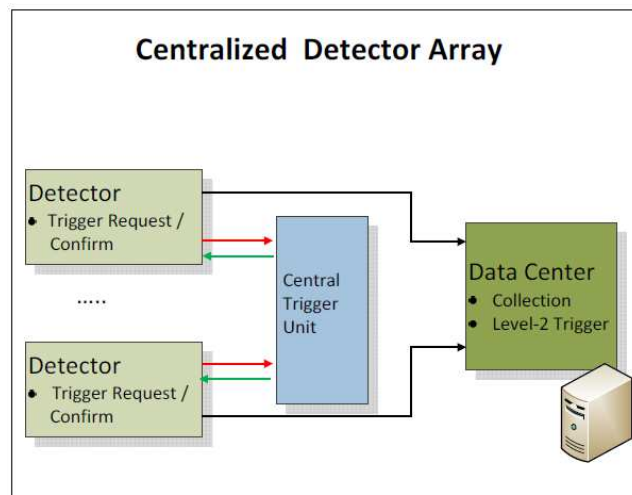
- (1) measure times against a central reference signal (eg. *common stop*)
- (2) trigger at a central place (confirming the detector trigger-request signals).

This “central triggering” can contribute to large dead-times, and analog-buffer depths.

## Distributed Arrays

Instead - with a **precision clock** in each detector, locally triggered sub-events can be send to a digital central processing unit (bandwidth and trigger-selectivity permitting). This allows for complex array-triggering procedures, and low dead-times.

→ Clock reliability and precision is a system-critical parameter.



Each detector has a precision clock.

# ... and Timing (Trigger) concepts

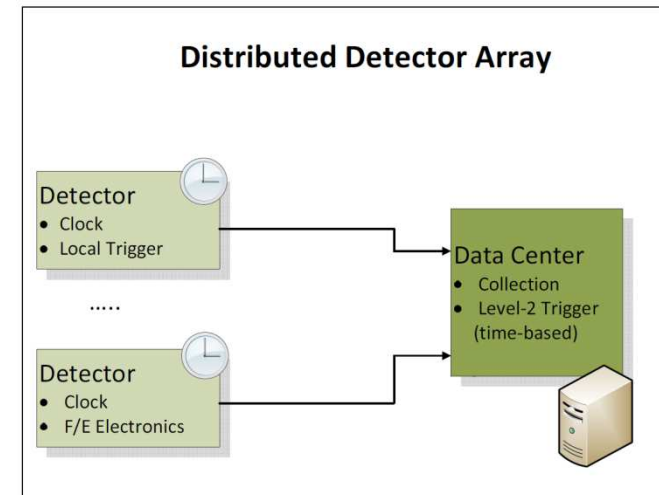
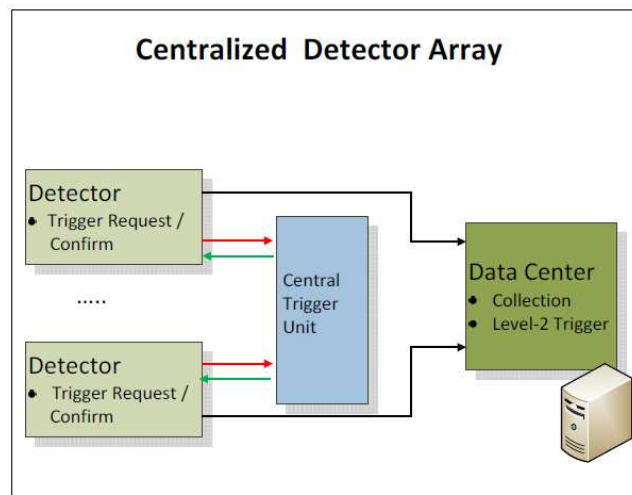
Examples:

## **Centralized Arrays**

- Amanda, Baikal Neutrino telescopes (1990-2005)
- Fixed target detectors

## **Distributed Arrays**

- IceCube (5000 clocks under-ice; over copper wires)
- Antares, NEMO (clock on fiber)
- AUGER (GPS)



Each detector has a precision clock.

# ... and Timing : Using Distributed Clocks

Which Technologies to distribute nsec-precision clocks to each detector exist?

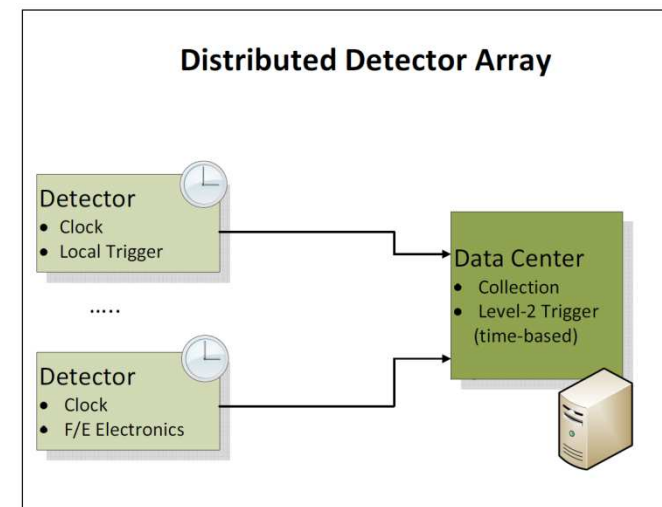
- > Custom made systems build over 20++ years for nsec-precision ☹️

For next generation projects: is there a “standard nsec-timing technique” ?

- > A new technique developed: “ White Rabbit “ → worth investigating 😊

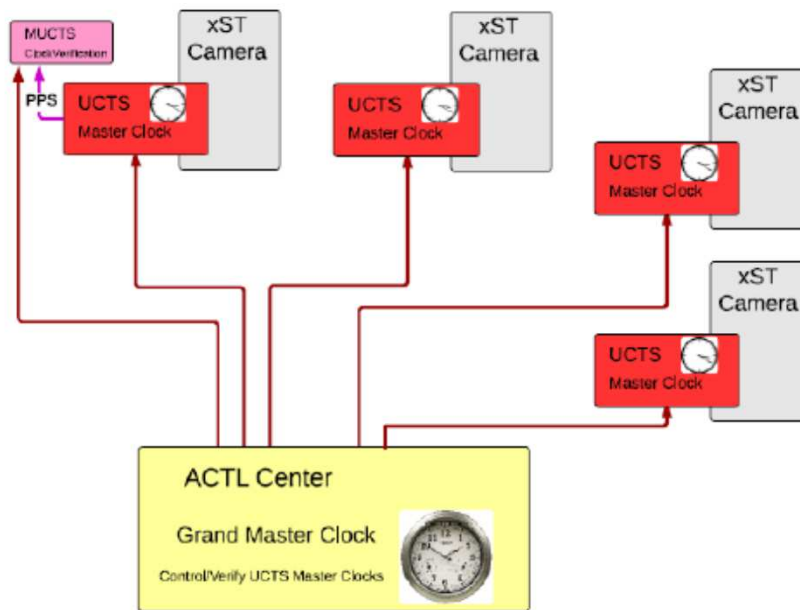
Note: Existing timing tools are not a generic solution

- > GPS: precision (o(20-50ns)), reliability, price, availability
- > NTP (network time protocol): ms-scale over LAN/WLAN network
- > PTP “precision time protocol”: ~usec-scale



# Timing : Distributed Clocks

- Generic example: Array of CTA-cameras (or any other detectors)
- Each Camera has a precision clock, located on a Timing Card (UCTS).
- All clocks are autonomously synchronizing with the GrandMasterClock.
- Inter-Clock deviations are of  $o(200\text{ps})$  rms  $\rightarrow$  perfect for CTA-purposes



- $\rightarrow$  The array acts like a time machine, ie. must be able at each camera to either
- (A) measure (timestamp) an “event occurring”, or to
  - (B) generate an “calibration event”, ie. issue a clock-driven timesignal to camera.



# Technical Realization: White Rabbit



WR is a fully deterministic Ethernet based network for data transfer and synchronization.

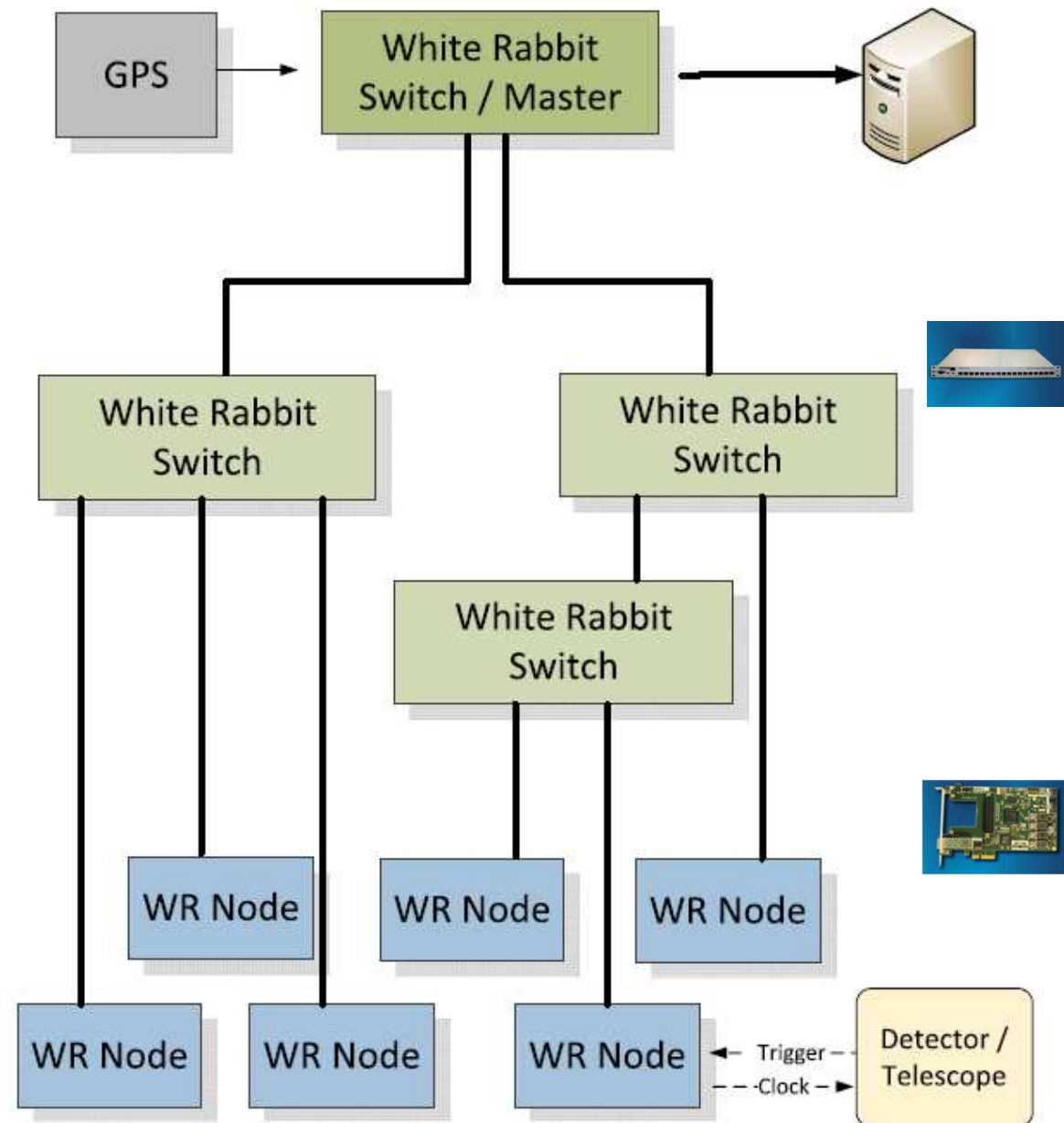
Extension of PTP. Uses proven 1GbE fiber technology.

A WR network is made of

- ClockMaster (MasterSwitch+GPS)
- WR-Switch network
- WR-nodes with synchronized clock
- Standard GbE fiber connections.

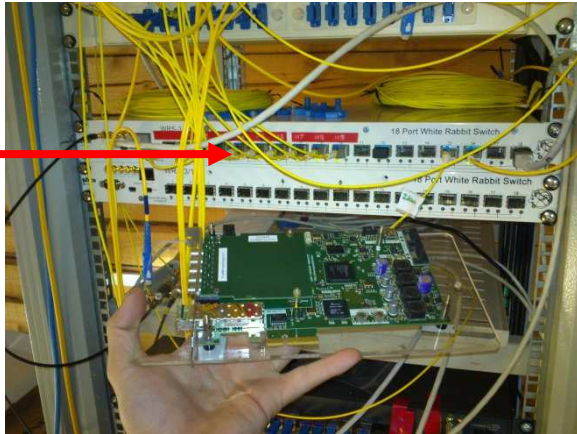
Parameter:

- Accuracy <math><1\text{ns}</math>, Precision ~20ps
- Fiber links of 10km ..... 60-80km.
- >1000 nodes.



# White Rabbit: The Hardware Components

## WR Master: WR Switch



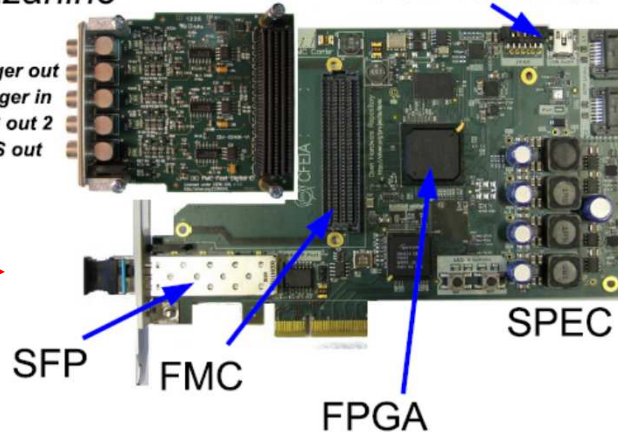
1Gbit fiber

FMC DIO  
mezzanine

Trigger out  
Trigger in  
PPS out 2  
PPS out

## WR-Node: SPEC card

USB terminal



SFP

FMC

FPGA

SPEC

## The WR Switch:

The synchronization master,  
connects to up to 17 WR-Nodes.

## A WR-Node: SPEC

( "Simple PCI FMC Carrier" )

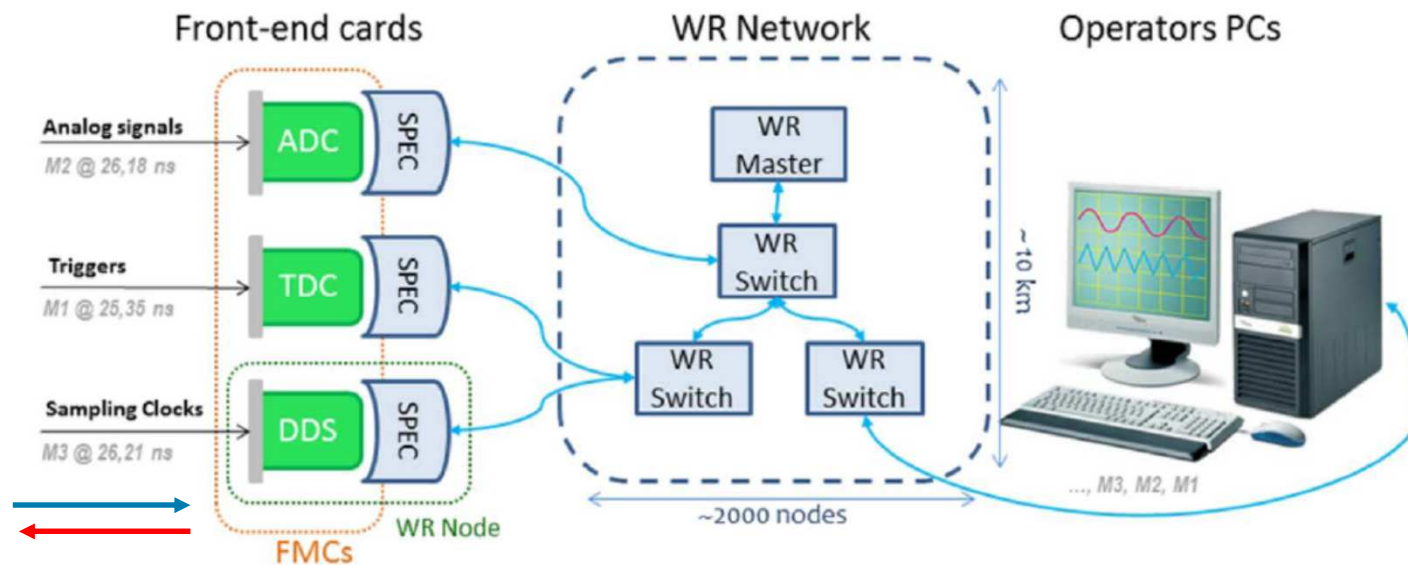
Spartan-6 based PCI-size card  
1x FMC (Mezzanine)  
1x SFP (WR fiber)

(the WR-Node workhorse since 2011)

# White Rabbit - Application



Example - a distributed DAQ system.  
Sensors located over a wide area, eg. accelerator.



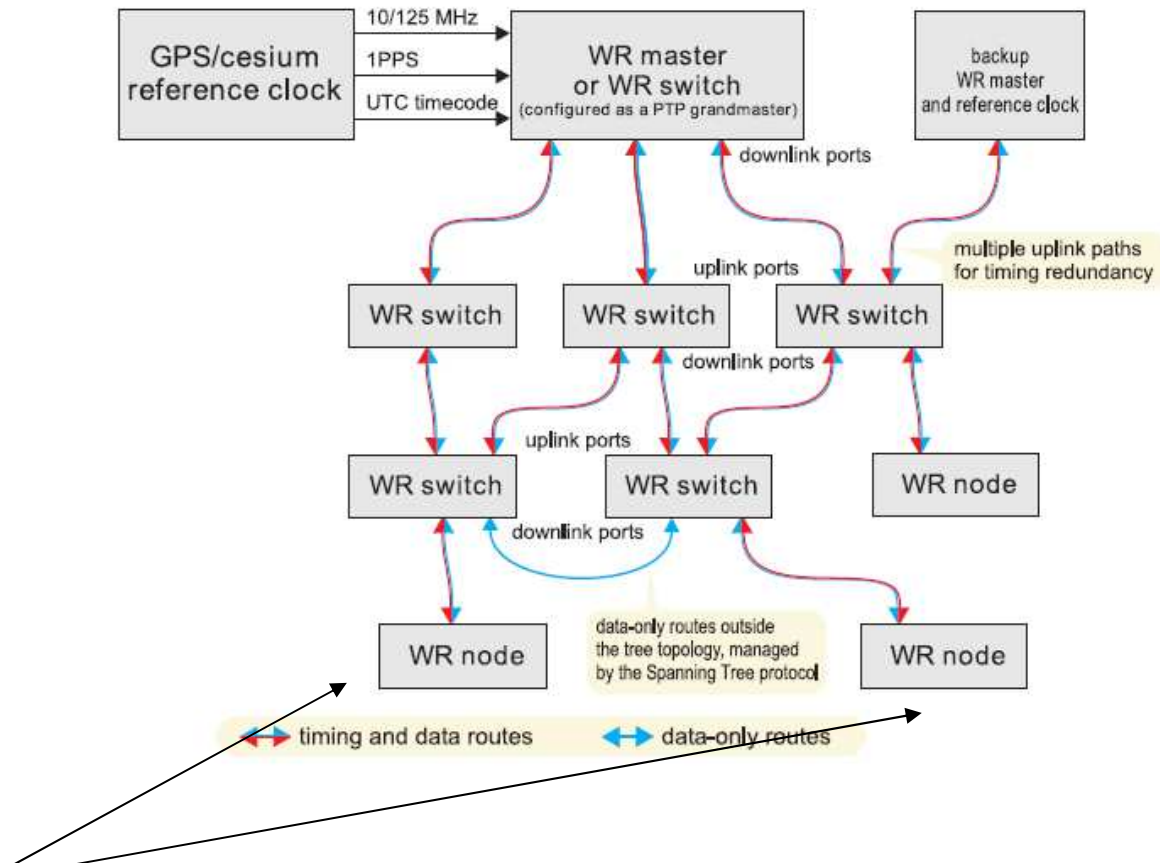
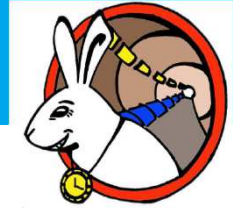
Functionality:

Measure \*\*AND\*\* Control ( In / Out ),

by the same node with the clock-driven precision.

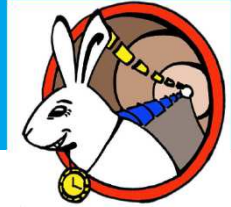
(see also pg.19)

# White Rabbit - Network topology



- > **WR-Node = User modules with local clocks**
- > **WR-Nodes are synchronized over the WR-network to the Master-switch (WRS).**
- > **Master-WRS is connected to a reference clock (GPS/Caesium).**

# White Rabbit - How does it work ?



➤ Sub-nsec synchronization reached by 3 ingredients

1. Clock is distributed from master via fiber cable to all nodes (Synchronous Ethernet), including switches

2. Slave bounces back the clock  
Master monitors phase of bounced-back clocks (DDMTD)

3. Master transmits absolute time and phase difference to Slave (Precision Time Protocol, IEEE1588)  
→ Slave compensates link delay

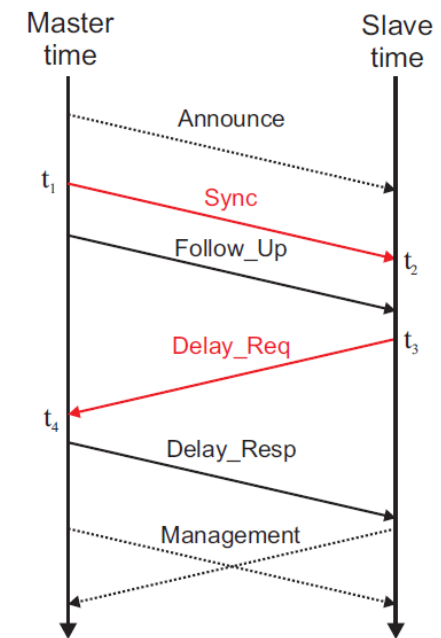
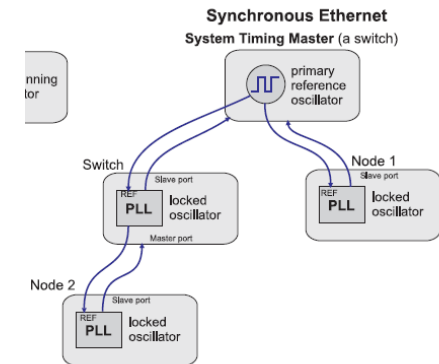
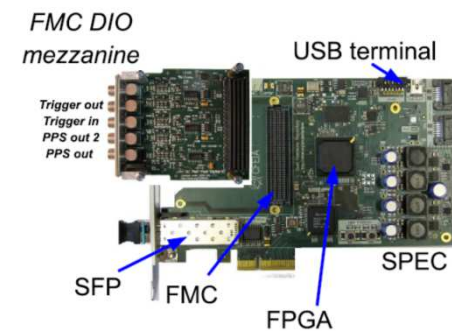
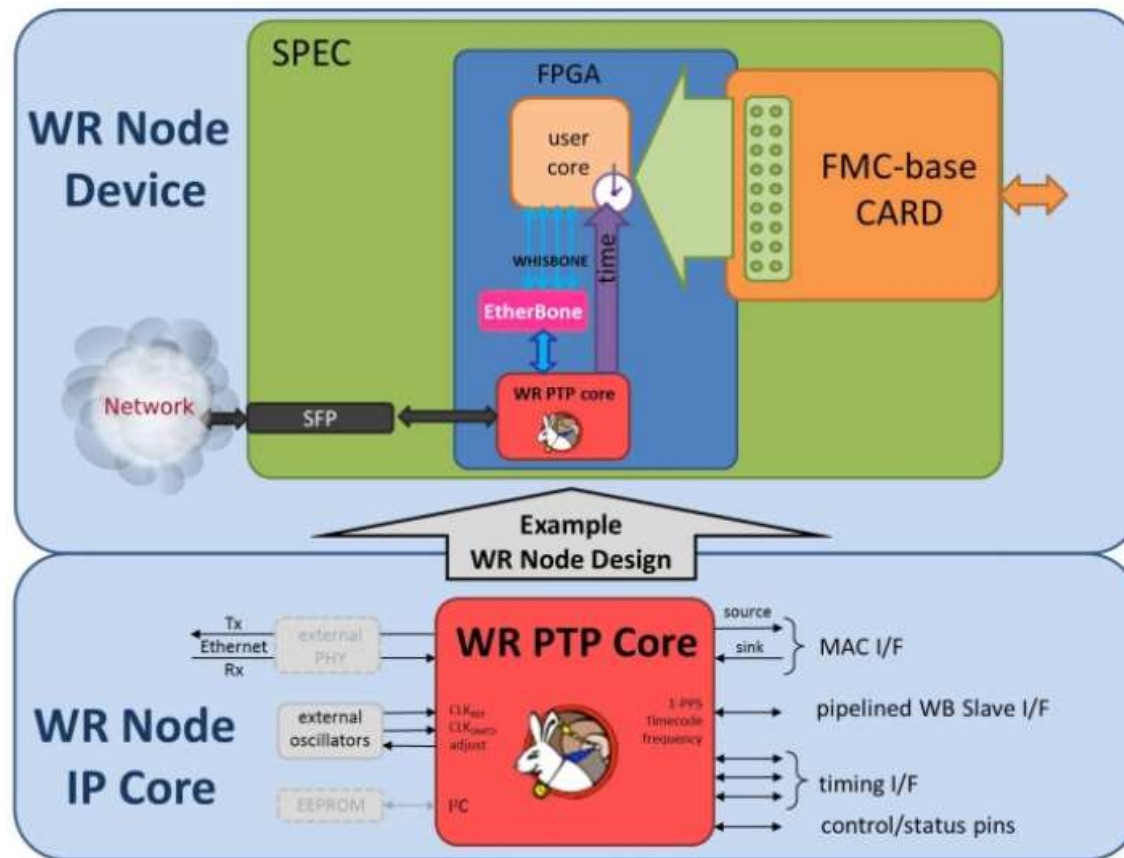


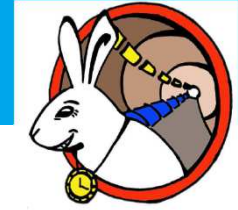
Figure 2: Simplified PTP message exchange di

# An example WR-Node



( SPEC Board)

# White Rabbit - Why is it attractive ?



WR is

- Supported by an active core-team @CERN,
- Planned for the LHC accelerator upgrade
- Growing participation from industry.

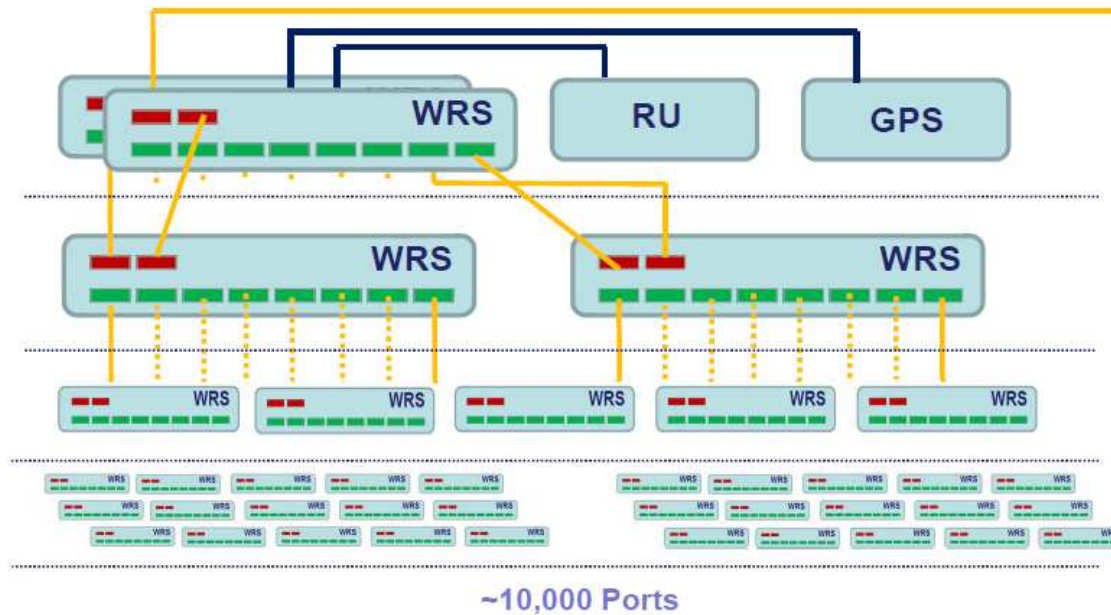
First astroparticle applications (“reference”) are underway now (e.g. LHAASO, HiSCORE). Results are very encouraging.

## Advantages :

- > Development for CERN & GSI accelerator complex; much external interest
- > Open Hardware & SW Project; peer reviewed; fully transparent to the user. Adapting to a use-case is easy and supported.
- > Hardware is commercially available (growing #companies),
- > WR Standardization is planned for Eth-PTP (IEEE1588...) in 2018
- > A guaranteed large user community: it will be a well debugged system ... !

# WR - Application : LHAASO

LHAASO : ~10000 nodes to be synchronized.  
Test setups running.

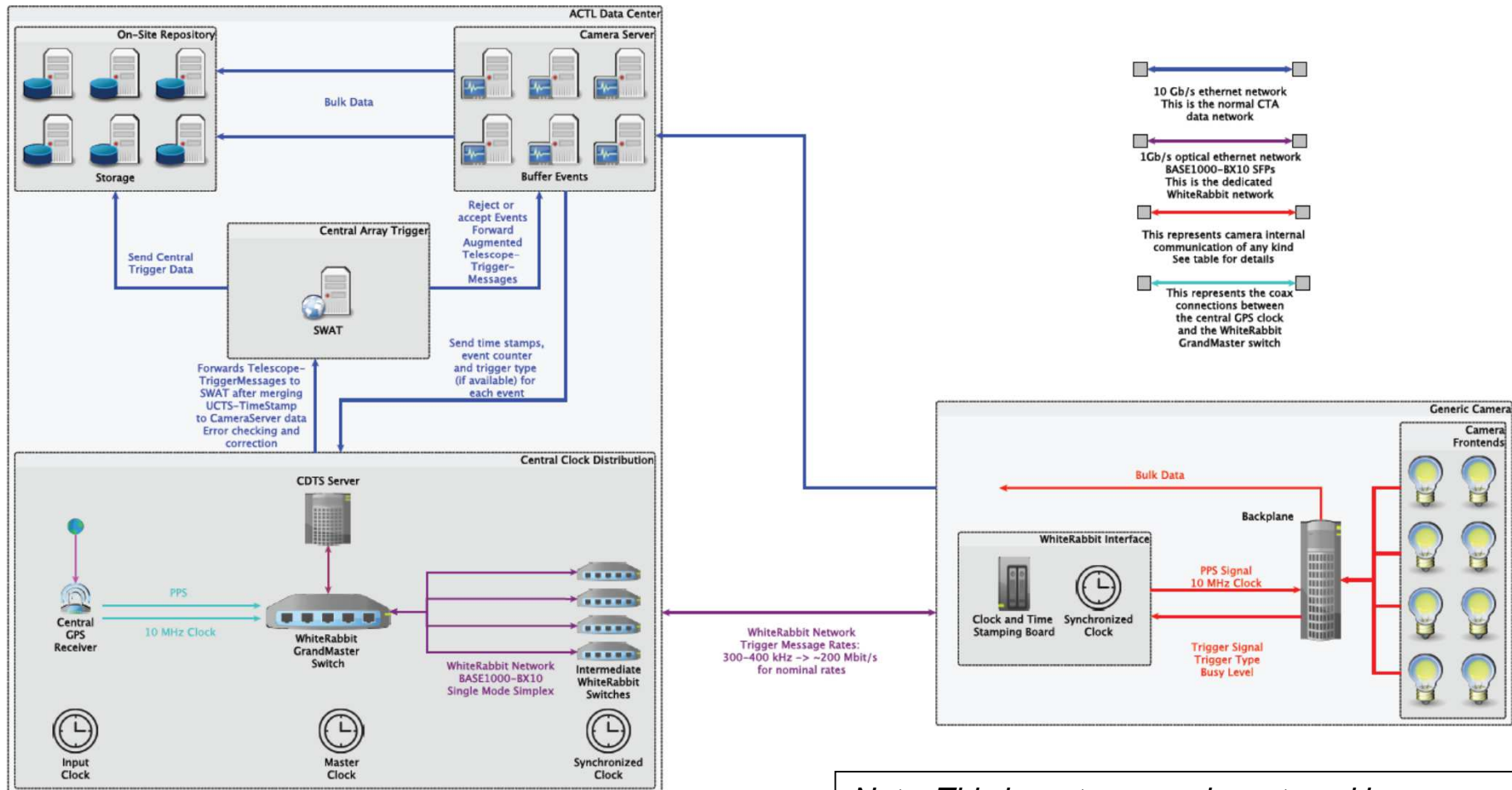


PC FARM

G.Gong, ICALEPCS, 2011,  
ICRC2015, ....



# WR – Application / Plan : CTA Telescope Timing



*Note: This is a strawman-layout, and by no means final.*

*CTA is discussing the data-flow concept and network architectures; since 2013.*



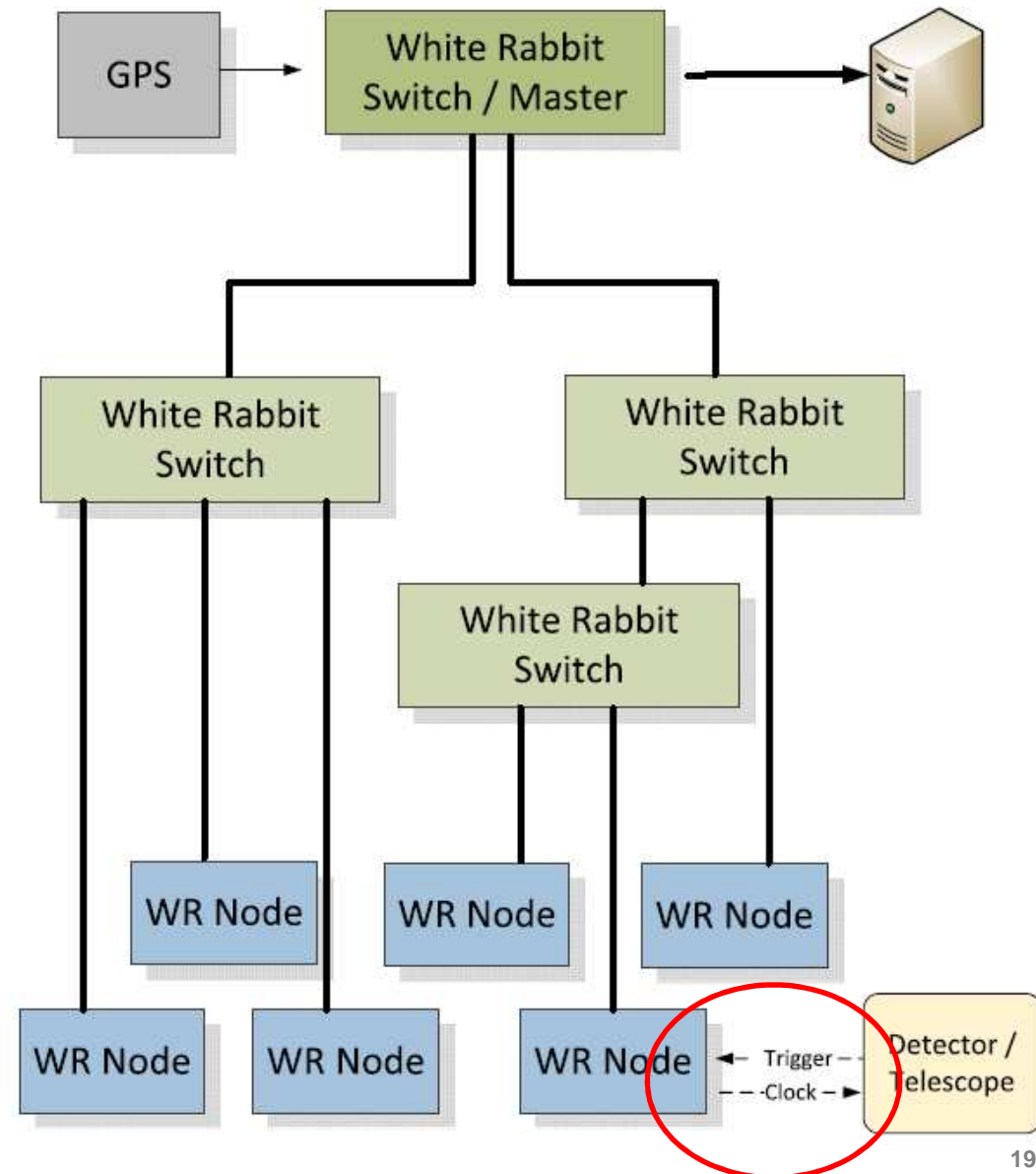
▪

# ... and Timing : Using Distributed Clocks

AP experiments must act like a time machine, ie. at each detector being able

- (A) to measure (ie. timestamp) a “local event occurring”, or
- (B) to generate an event, by issuing a synchronous (to all detectors) signal.

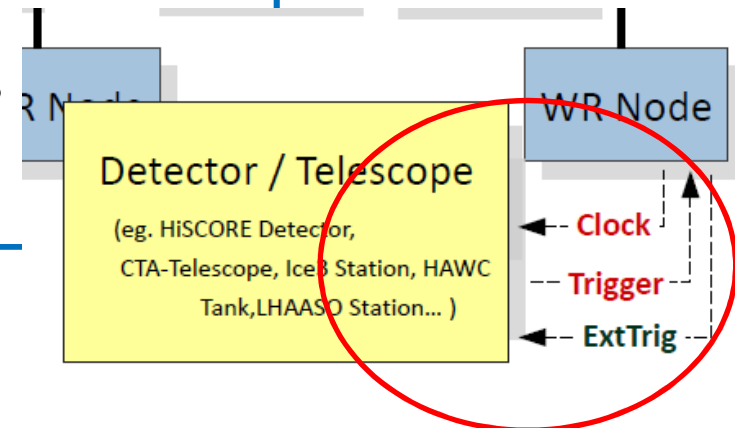
→ WR is a natural technique to be used for this.



# Detector and WR-Node : Baseline Interface

For each detector in the array it is required :

- WR-Node → Detector : Clocks ( PPS / 10MHz )
- Detector → WR-Node : Trigger ( edge )
- WR-Node → Detector : External Trig Pulses
- ( plus : auxiliary data ... )



Comments.

(1) TriggerTimes are generated both on detector and WR-Node for each event.

This (time/counter) redundancy can be used to verify clock stabilities and data integrity: **“DoubleClock/DoubleTimeStamping architecture”**

(2) Another request : Is in-situ verification of clock-correctness possible ?

Allow for operation of a **Monitoring-WR-Node** at each detector, that cross-stamps the PPS. Cheap&sufficient; can be limited to verification and debugging phases.

# HiSCORE - Experience with White Rabbit

# HiSCORE - Experience with White Rabbit

HiSCORE in Tunka, started 2012.

Since 2015 within the “TAIGA Collaboration”

TAIGA =

Tunka **A**dvanced **I**nstrument for **G**amma **A**stronomy and Cosmic Rays

# TAIGA - HiSCORE : Concept

(Hundred\**i* Square-km Cosmic Origin Explorer)

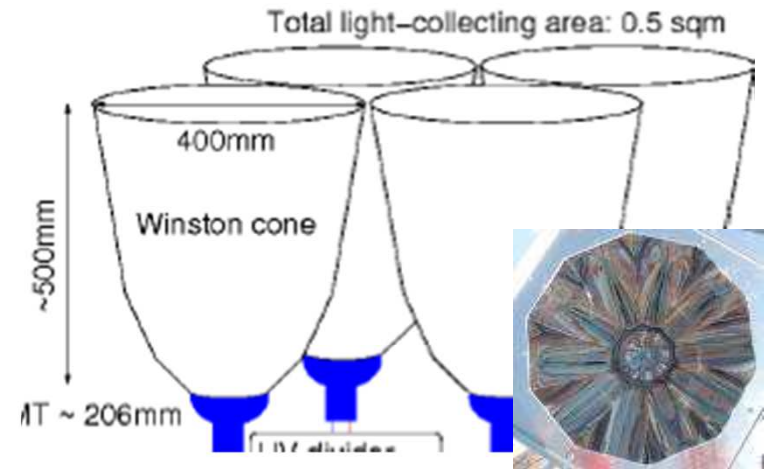
Non-imaging Air Cherenkov Array

Angular resolution :  $\sim 0.1$  deg

Large Field of view (FOV):  $\sim 0.6$  sr

Area:  $0.25 \text{ km}^2 \Rightarrow 5 \text{ km}^2$

Station spacing:  $100\text{-}200\text{m}$  Cosmic-ray / gamma-ray  
 $\sim 140$  channels /  $\text{km}^2$ .



4 large PMTs per station.

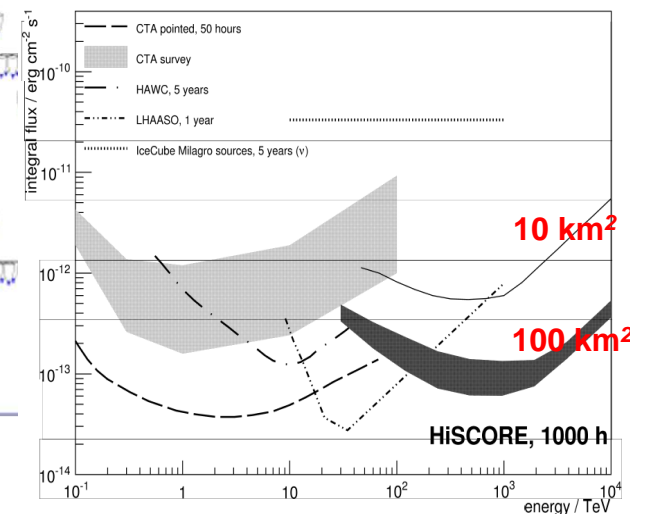
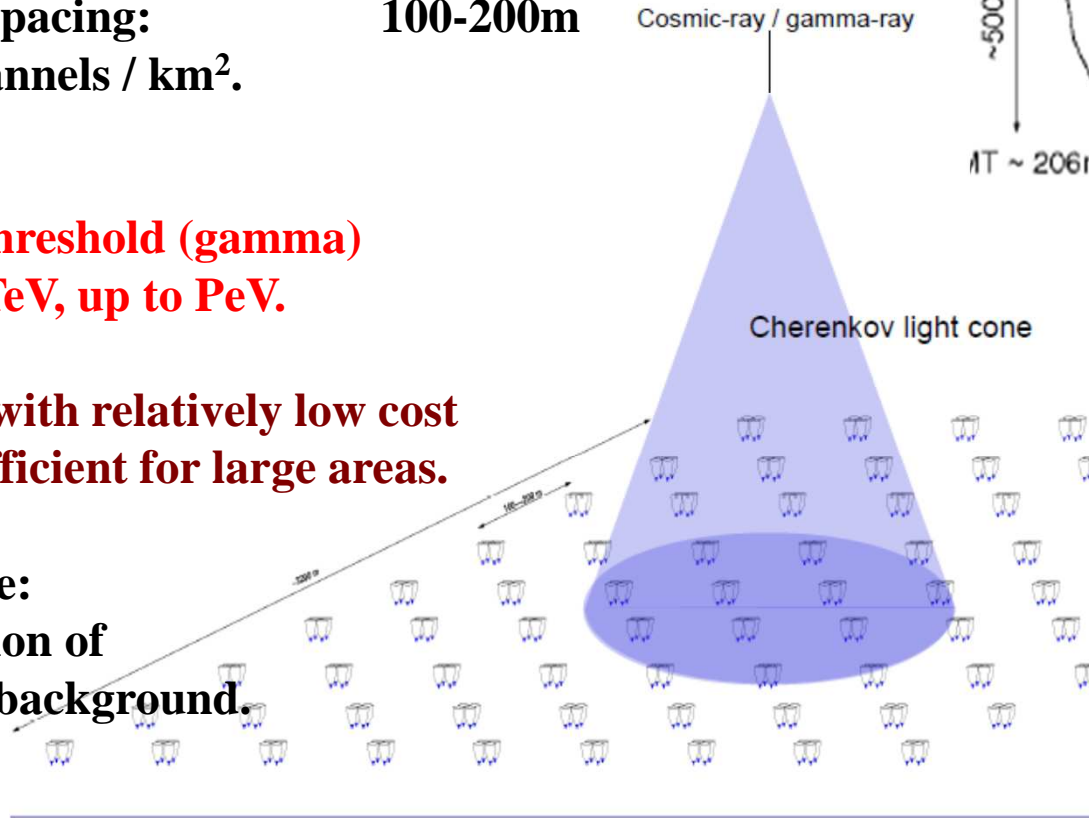
Energy threshold (gamma)

$E_\gamma > 30 \text{ TeV}$ , up to PeV.

Stations with relatively low cost

$\rightarrow$  cost efficient for large areas.

Challenge:  
 suppression of  
 of CRay background.



# TAIGA: a Hybrid Gamma Observatory @ Tunka



## TAIGA-HiSCORE

- 500 wide-angle Cerenkov stations on 5 km<sup>2</sup>
- E<sub>th</sub> = 30 TeV

Cost: ~ 8 M\$

## TAIGA-IACT

- 16 IACT Telescopes with mirror area 10 m<sup>2</sup>
- E<sub>th</sub> = few TeV

Cost: 0.3k\$/Telescope; 5 M\$

## TAIGA-Muon

- Muon detectors  
A<sub>total</sub> ~ 2.0 10<sup>3</sup>m<sup>2</sup>.

Cost: 3 M\$

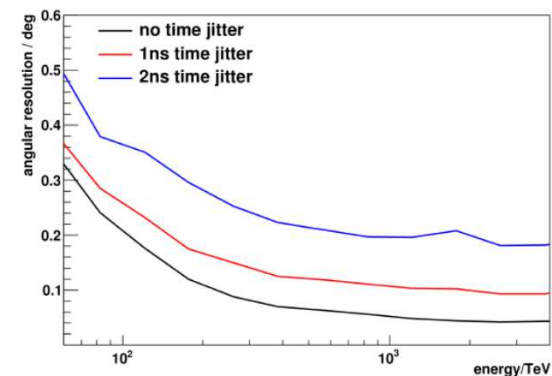


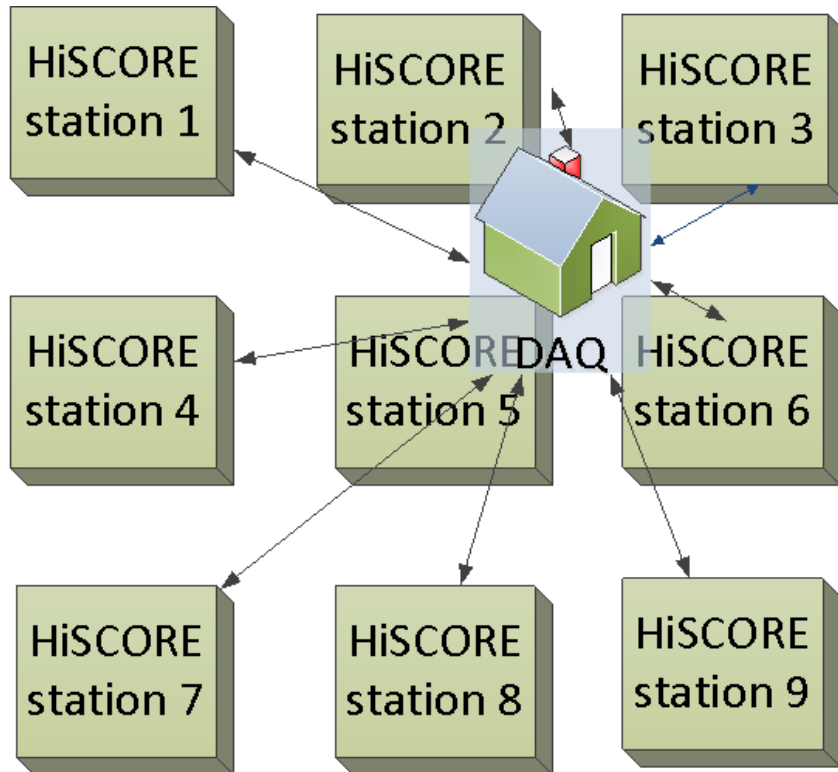
# White Rabbit in HiSCORE - Brief History

- Started in 2012 (HiSCORE)
- First WR field measurements : 04/2012
- Long duration tests : 10/2012-04/2013
- First reconstruction of cosmic ray showers (EAS) by WR-times: 04/2013
  
- HiSCORE -9 array: routine operation since 10/2013
- HiSCORE-28 array: commissioned 10/2015

Timing in HiSCORE:

**Crucial for pointing (MC):**  
**Time Synchronization to <1ns**





First prototype array: since 10/2013

$$A = 0.3 \times 0.3 \text{ km}^2$$

Each station detects Cherenkov light with 4 PMTs.



For precise shower direction reconstruction sub-nsec precision for arrival-timestamps at each station.

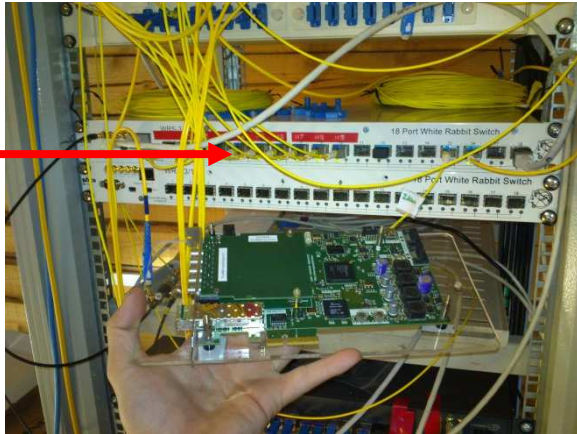
Prototyping with HiSCORE-9: Optical Stations / DAQ / Timing / ...

Main Results:

- Air-Shower reconstruction
- Timing calibration by external LED

# HiS-9 Station: The SPEC as the WR-Node

## WR Master: WR Switch

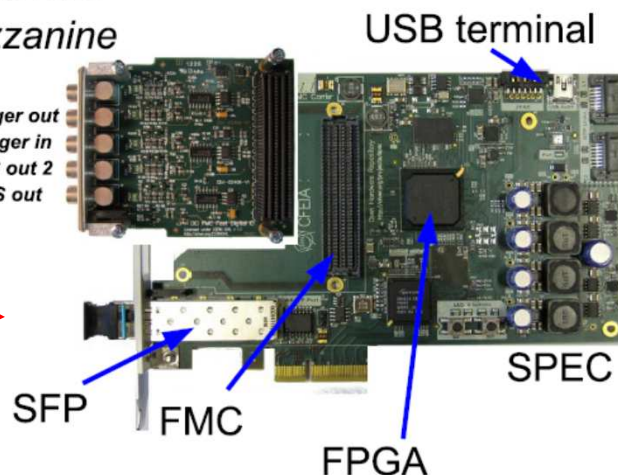


## 1Gbit fiber

FMC DIO  
mezzanine

Trigger out  
Trigger in  
PPS out 2  
PPS out

## WR-Node: SPEC card



SPEC = "Simple PCI FMC carrier"

Spartan-6 based PCI-size card  
1x FMC (Mezzanine)  
1x SFP (WR fiber)

The workhorse for WR (2011-...)

DESY adapted to CTA/HiSCORE (2012+)

- nsec-timestamping
- UDP timestamp transport
- (PPSOut/) 10MHz out
- DAQ/frontend triggering
- status monitoring, ...

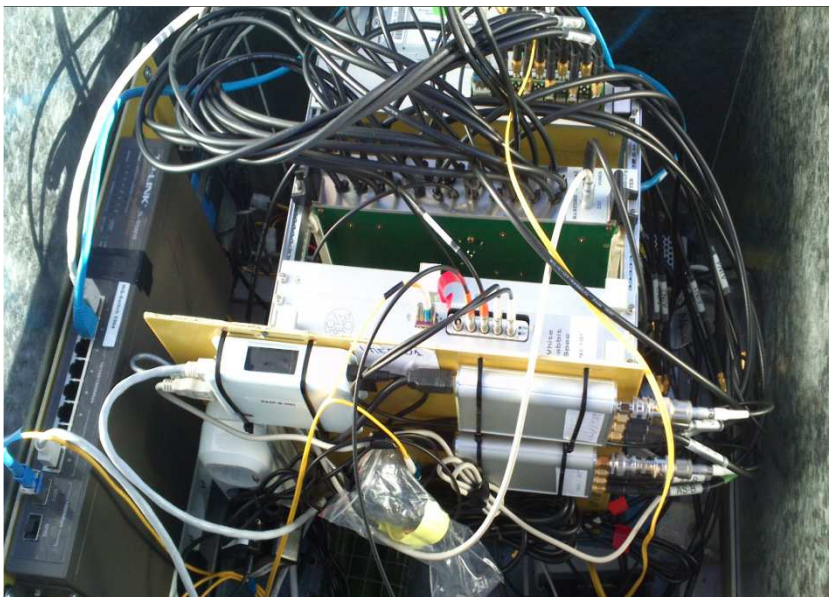
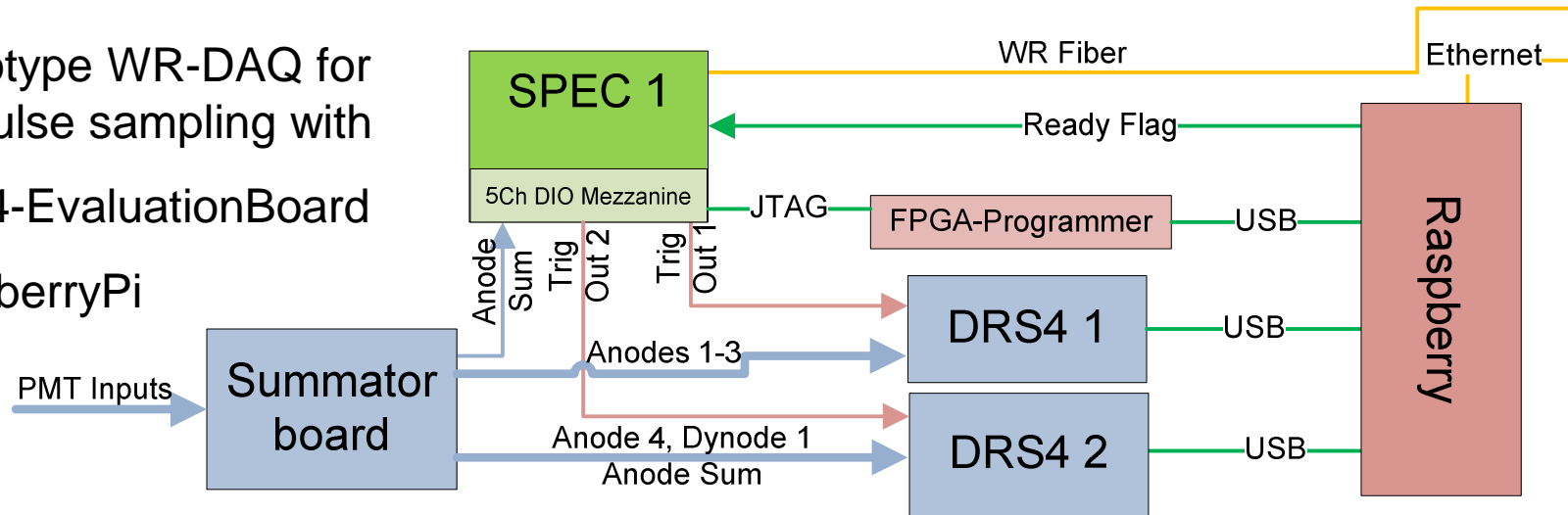
APC adapted for CTA (2015)

→ see Cedrick's talk

# HiS-9 Station : a SPEC-based mini-DAQ

A prototype WR-DAQ for GHz pulse sampling with

- DRS4-EvaluationBoard
- RaspberryPi



## SPEC card

- Runs WR clock
- Stamps trigger-times + sends over WR fiber
- Transmits WR status over Ethernet

## DRS4-EB (PSI)

- Capture analog PMT signals + WR trigger pulse

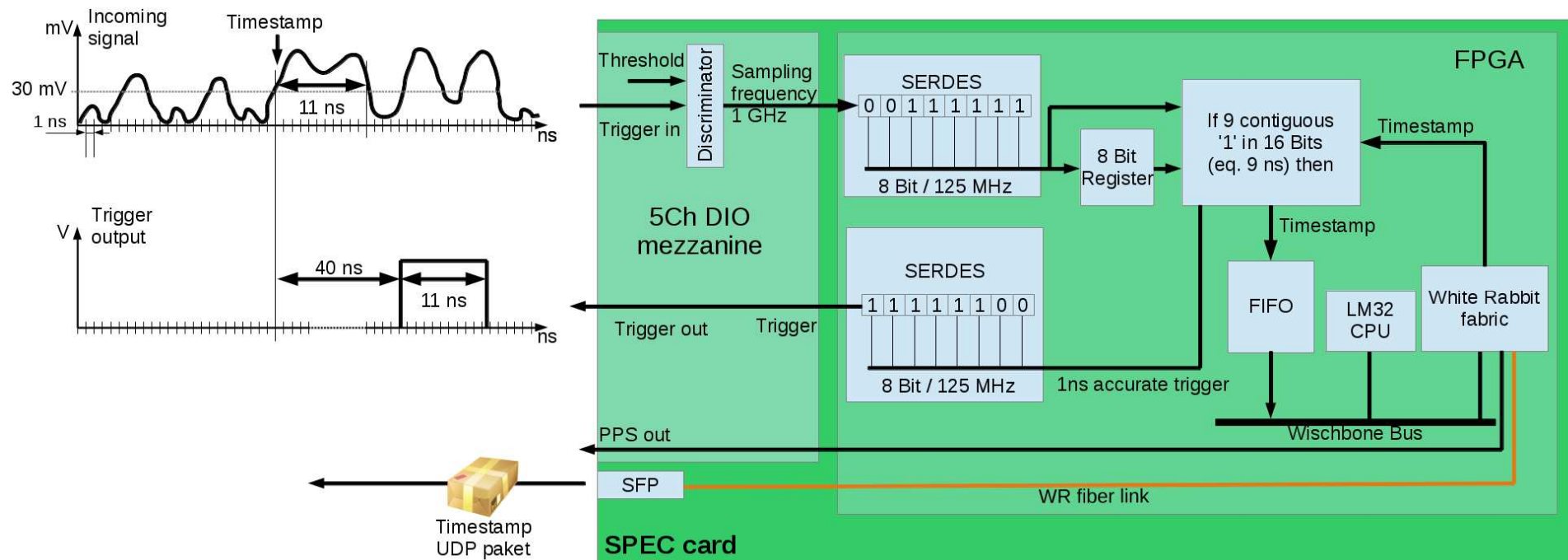
## Raspberry

- Reads out DRS/EB board on trigger
- Uploads bulk data over a second fiber
- Programs FPGA / Backup SPEC-USB

# WR Node – the HiSCORE specific design

## SPEC FPGA modifications

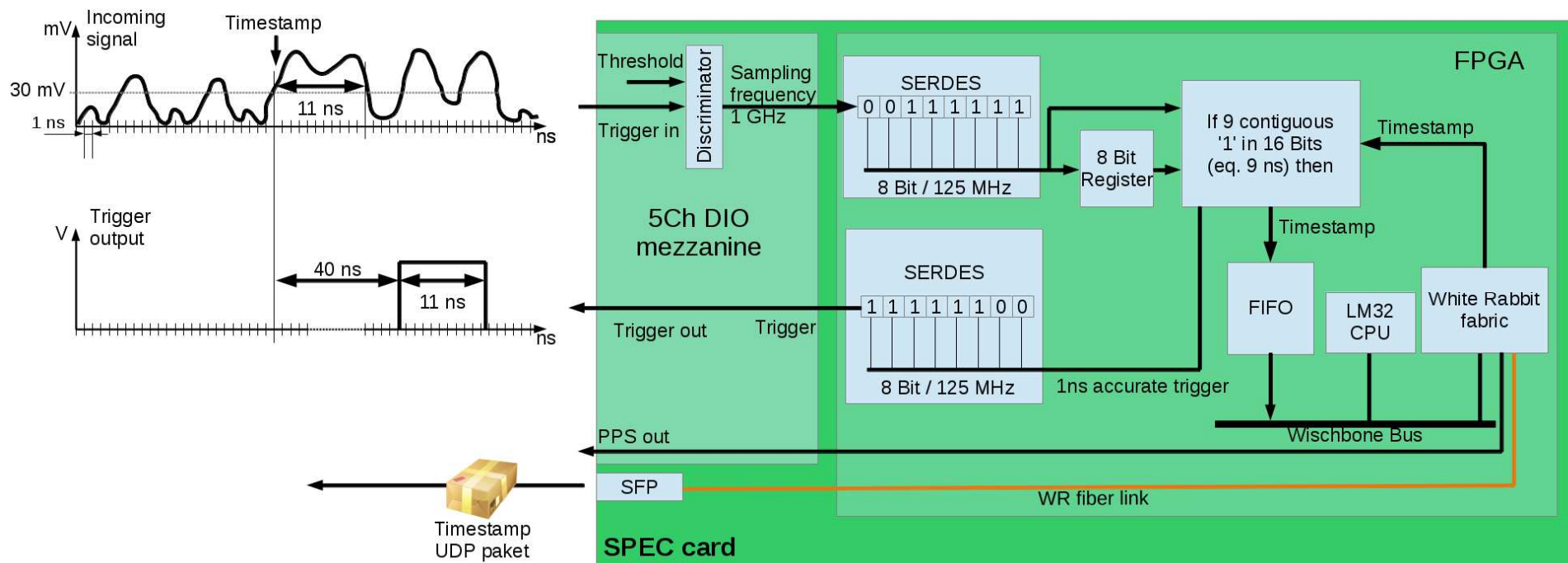
- Taking advantage of the features of the 5Ch DIO card
  - Configure some signals as input for the analog signal
  - Configure some signals as DRS4 trigger and handle Raspberry ready flag
  - Setting a threshold for incoming signals
- Using Spartan 6 SERDES blocks for deserialization



# WR node – the HiSCORE specific design (2)

## SPEC FPGA modifications

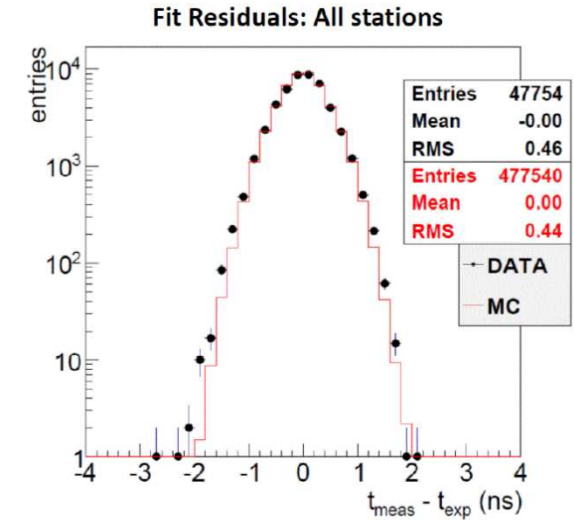
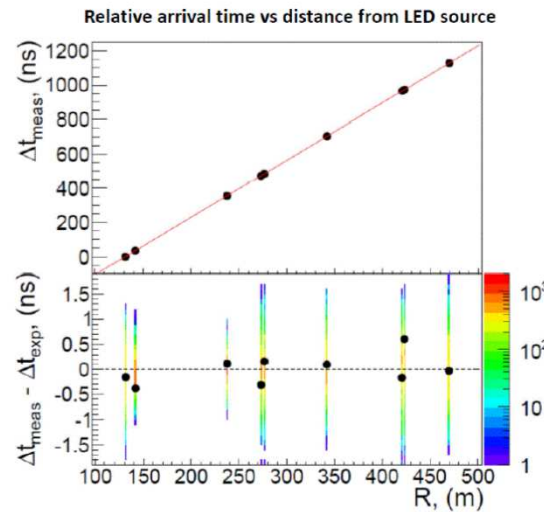
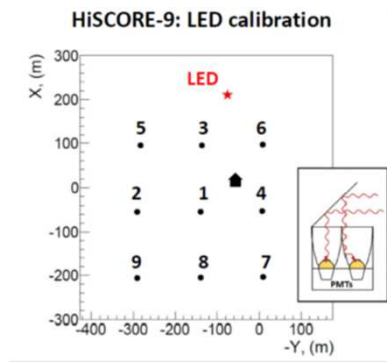
- Filter out signals shorter than 9 nsec (configurable)
- Timestamp the trigger arrival time
- Send timestamps over WR link to DAQ center (software)
- Introduce a command to adjust threshold over USB-UART



# HiSCORE-9 WR Data: Timing with LED and Air Shower

## > External LED-Calibration

Fit-Resid  $\sim 0.44\text{ns}$



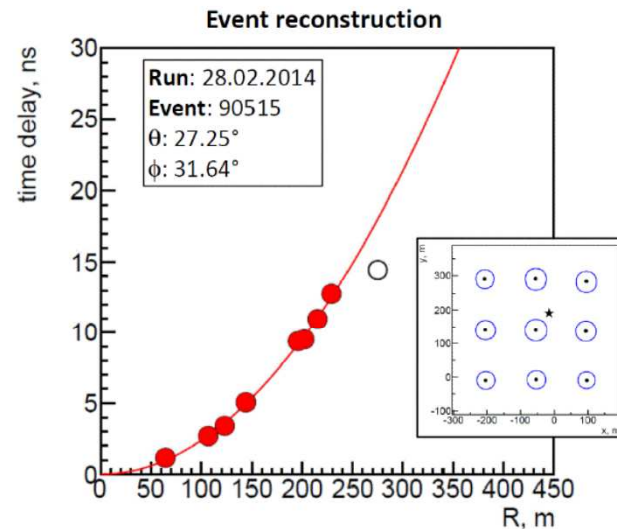
(a)

(b)

## > Cosmic Air Shower Reconstruction

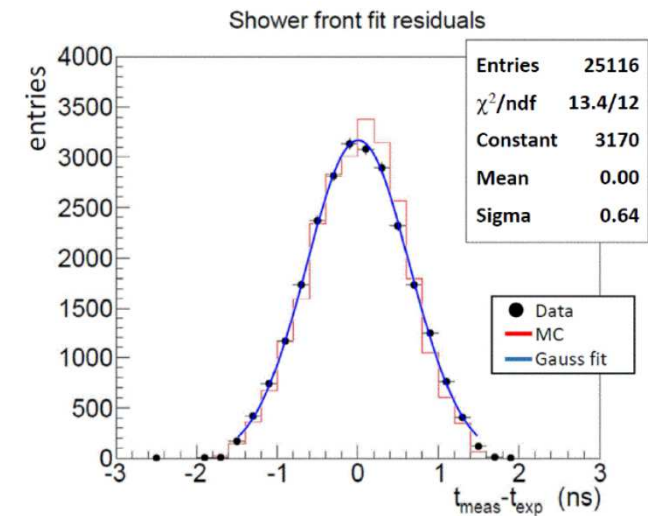
Fit-Resid  $\sim 0.6\text{ns}$

(left) Shower front: time-delay vs. radius



(a)

(right) fit-residuals all stations



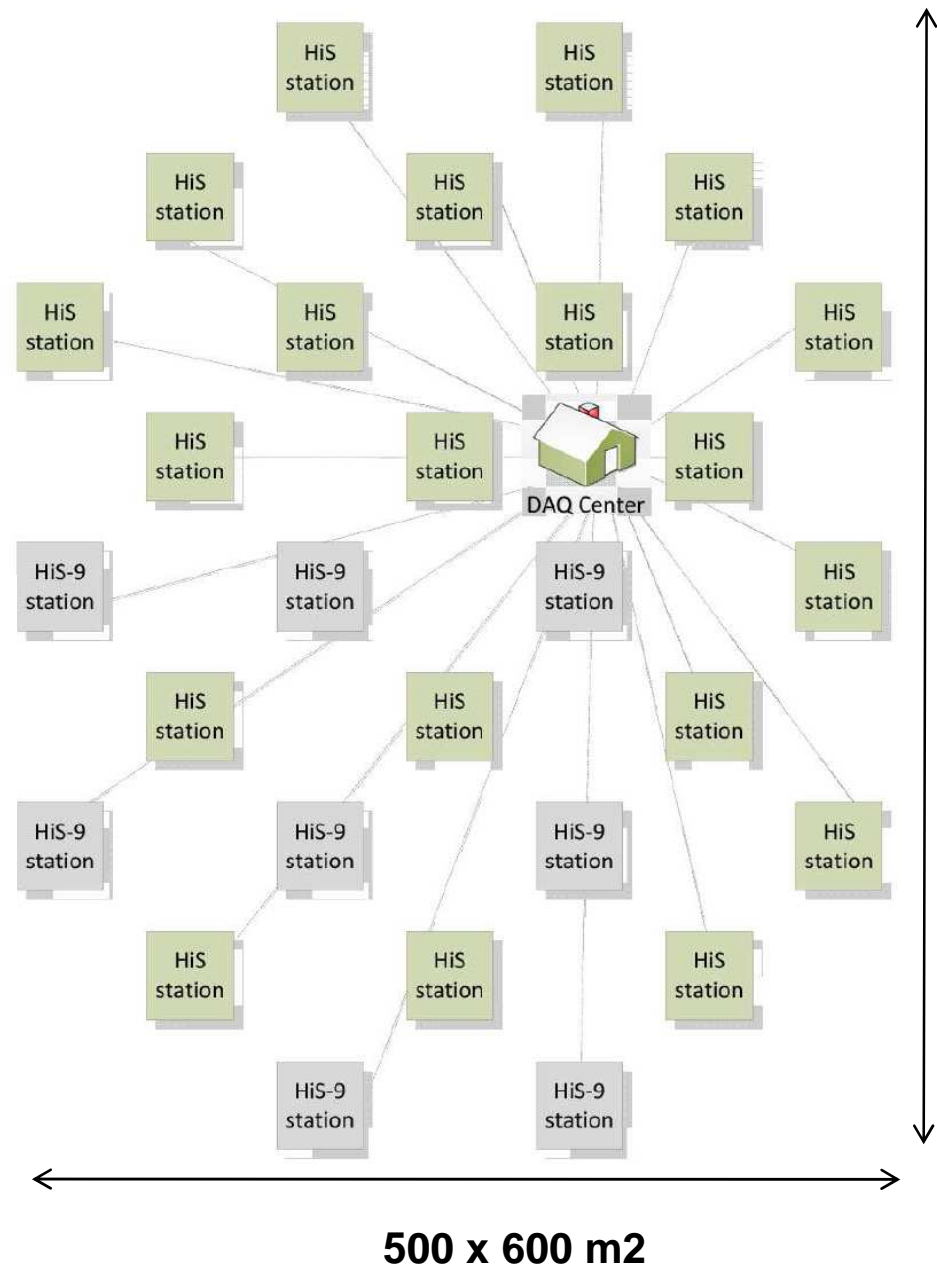
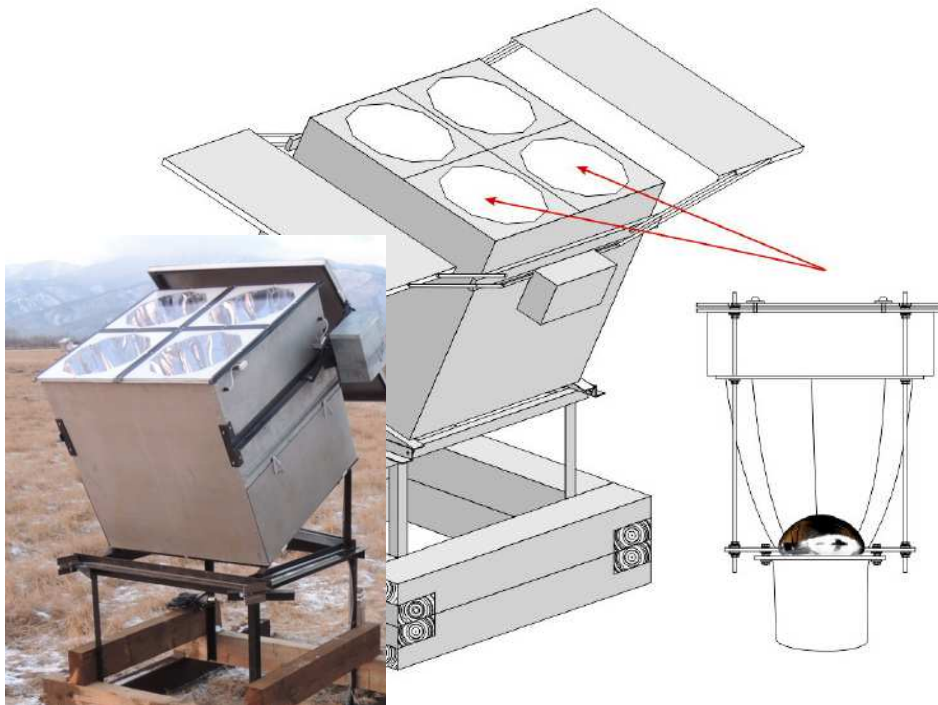
(b)

Figure 9: EAS shower reconstruction. (a) Arrival time delay vs distance; (b) Shower front fit residuals

# HiSCORE

## 28 Station Array

- 0.3 km<sup>2</sup>
- Installed: fall 2014;  
operation since 2015
- Hybrid nsec-Timing
- Modernized electronics + mechanics
- Threshold: few 10 TeV.

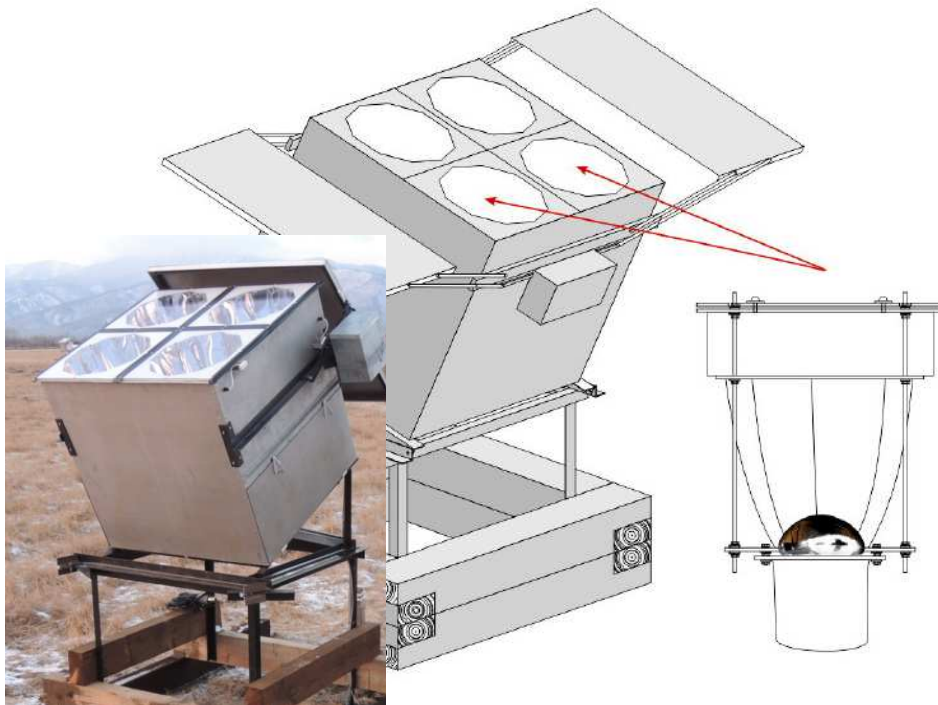




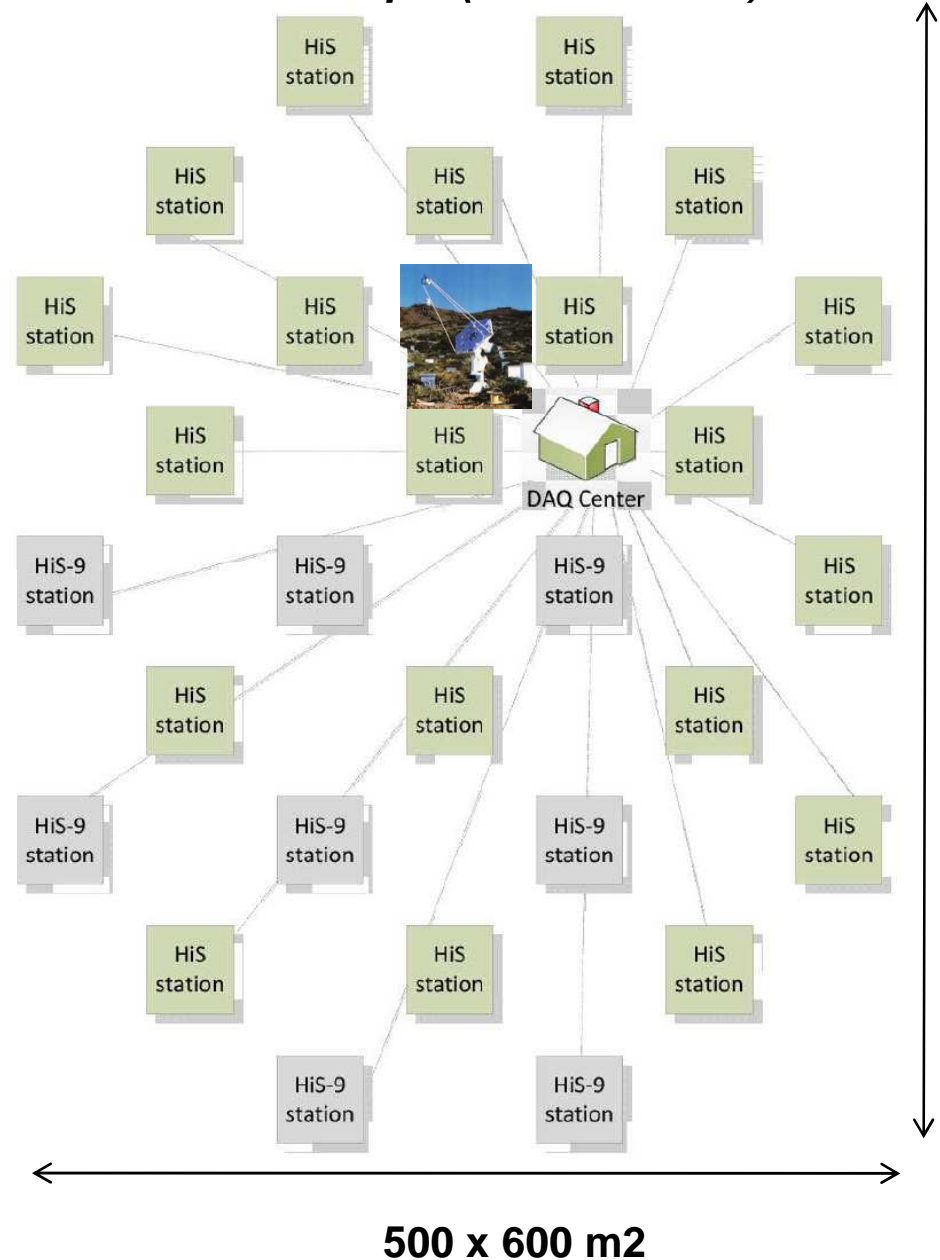
# HiSCORE

## 28 Station Array

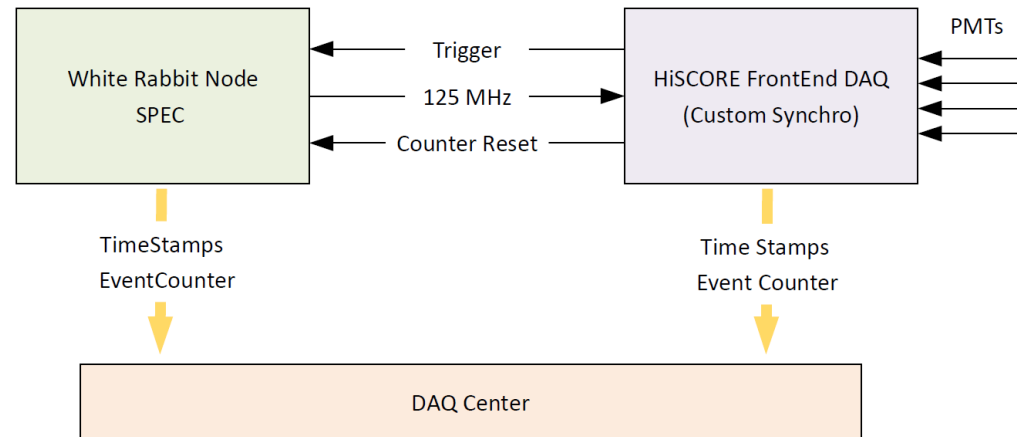
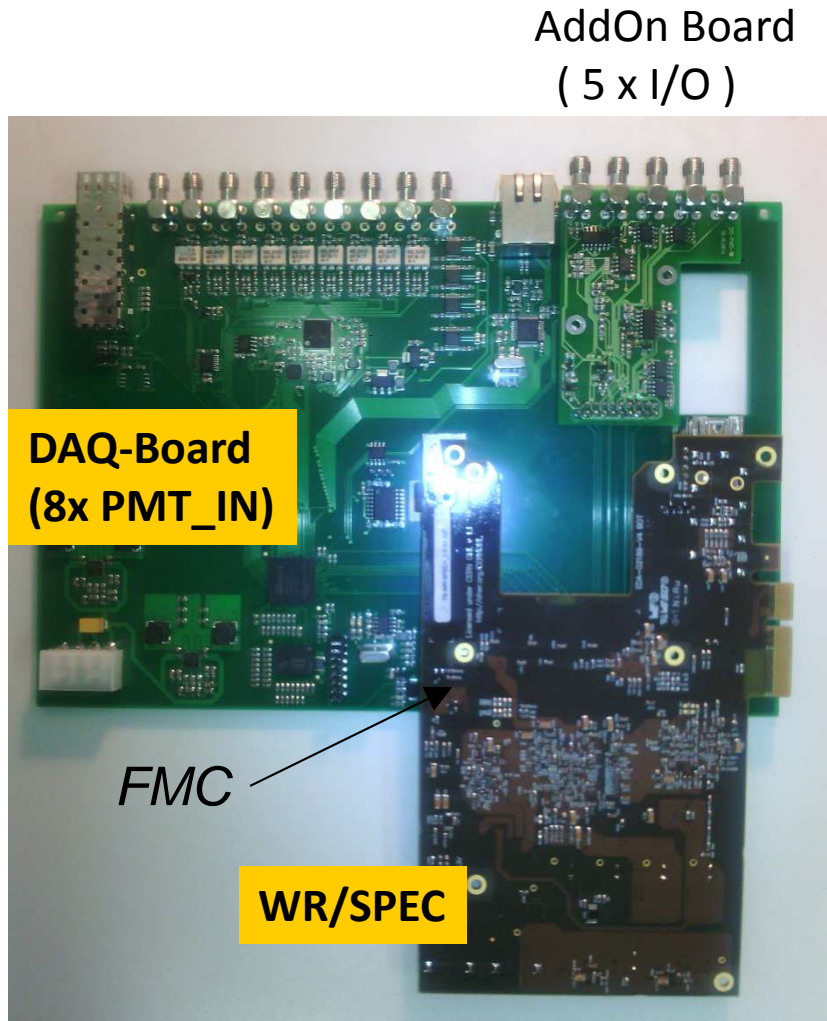
- 0.3 km<sup>2</sup>
- Installed: fall 2014;  
operation since 2015
- Hybrid nsec-Timing
- Modernized electronics + mechanics
- Threshold: few 10 TeV.



*Fall 2016: 1<sup>st</sup> Imaging Cerenkov Telescope (HEGRA-class)*



# HiS-28 : A Hybrid Timing DAQ



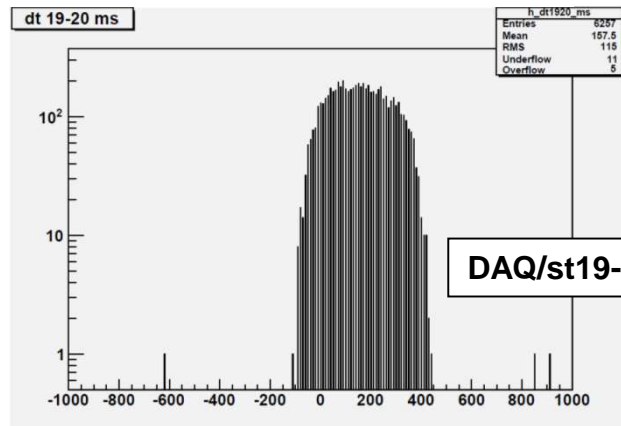
Parallel operation of two time-stamping:  
Custom timing and WR (SPEC).  
→ Verification event by event.

# HiS-28: Compare DAQ + WR Times from Cosmic Showers

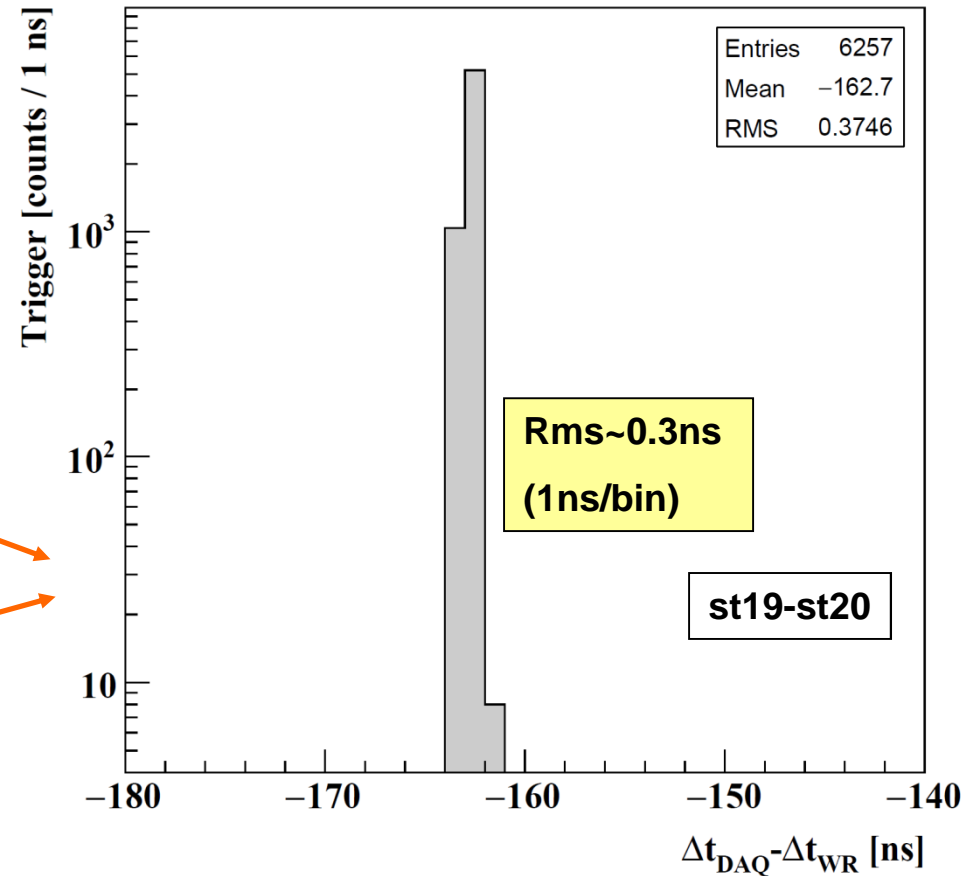
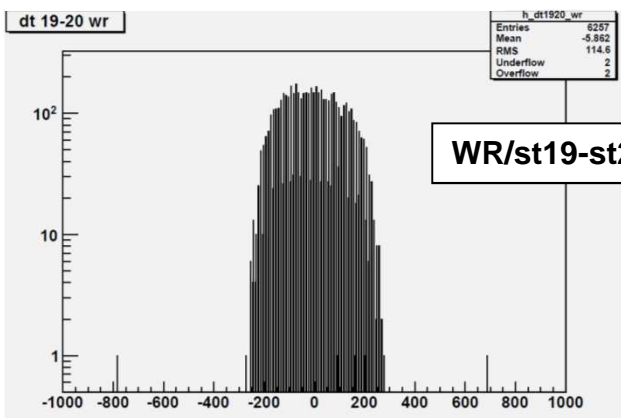
Trigger time differences from two independent clock systems (DAQ/ WR).  
(eg. Stations 19 & 20)

Timing stability: DAQBoard vs. WhiteRabbit

$dt\_daq = t\_daq\_19 - t\_daq\_20$



$dt\_wr = t\_wr\_19 - t\_wr\_20$

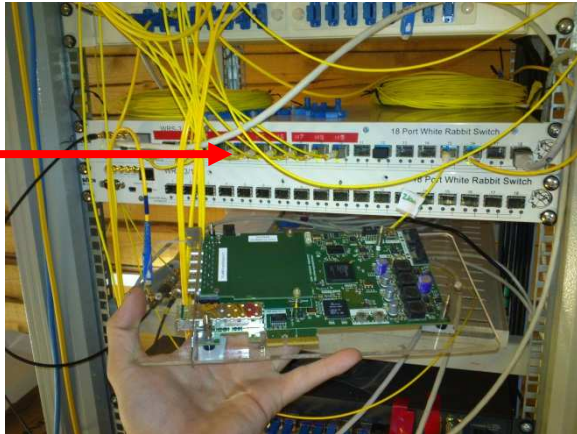


Very good long-term precision & stability. Accuracy: in progress.

# NewTechnology

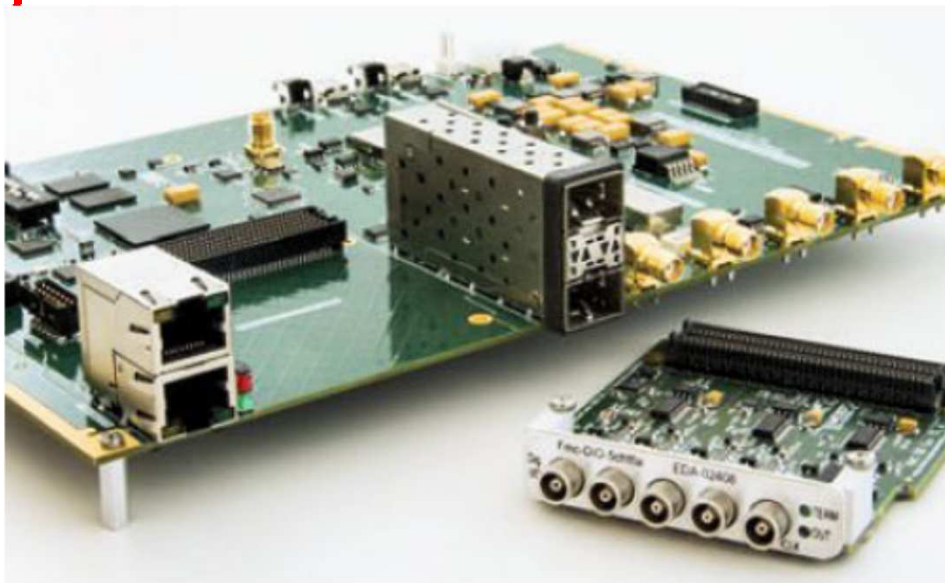
# NewTechnology: Timing with ZEN (Zynq Embedded Node)

**WR Master: WR Switch**



**1Gbit fiber**

**WR-Node: ZEN card**



## ZEN board (by SevenSols)

Xilinx Zynq Z7015 based w/ 2x ARM9  
1x FMC  
2x SFP (DaisyChain, WR redundancy)  
2x Gbit Ethernet  
Improved clock precision  
LinuxKernel

## DESY adapted for HiSCORE/CTA (2015)

- FMC-based operation (DIO, ...)
- "nsec-timestamping"
  - 2 ns now: Zynq Grade -1 (933 MHz)
  - 1 ns soon: faster Zynq by 7Sol
- TCP timestamp transport
- (( PPSOut /10MHz out ))

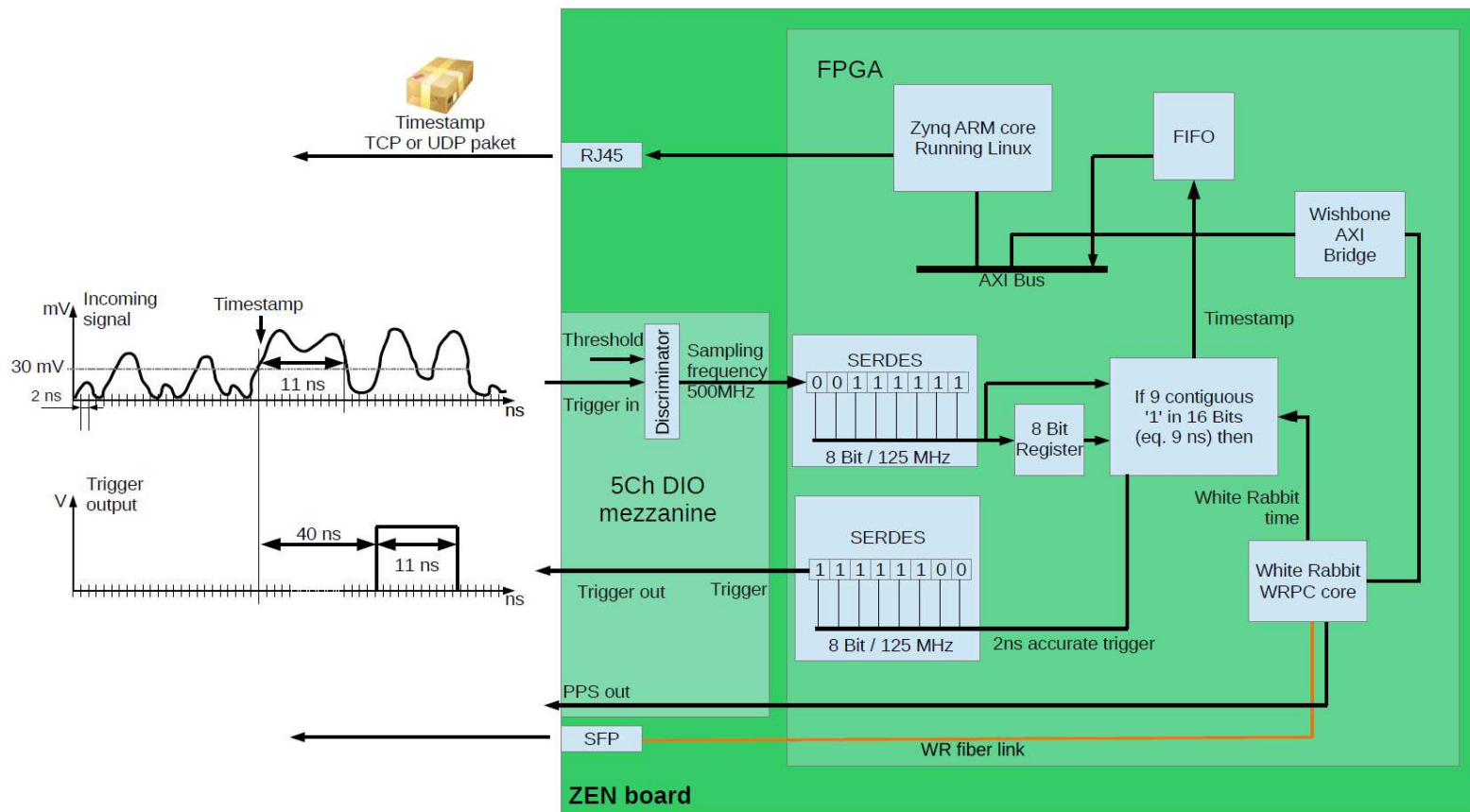
→ Performance, timing, stability, ...:  
... is excellent !

# ZEN : Timestamp with Standard TDC

> ZEN with time-stamping 2ns ( $\rightarrow$  1ns with grade -3)

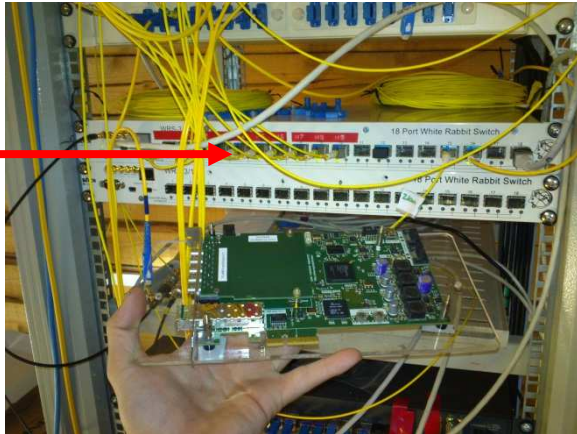
Implementation similar to our TDC on the SPEC

(w/ INPUT signal analysis, TRIGOut for local DAQ)



# ZEN : Timestamp Test

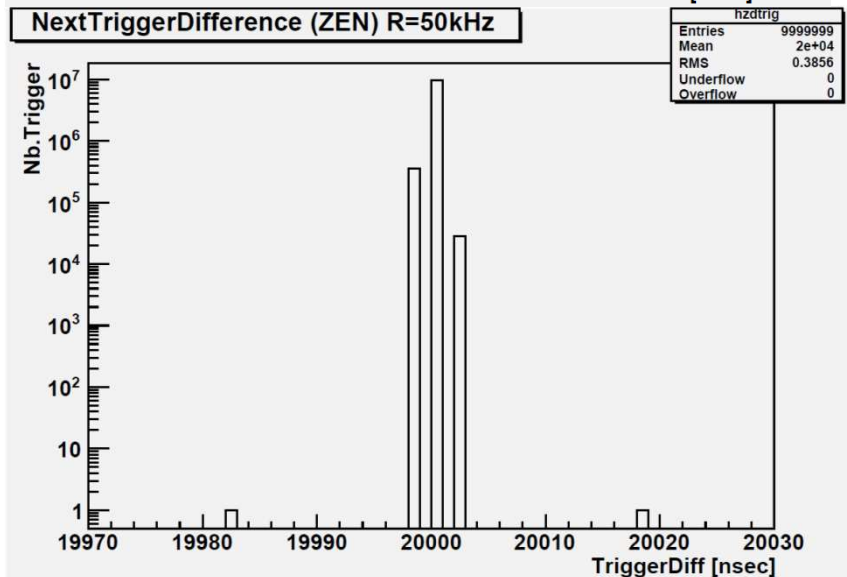
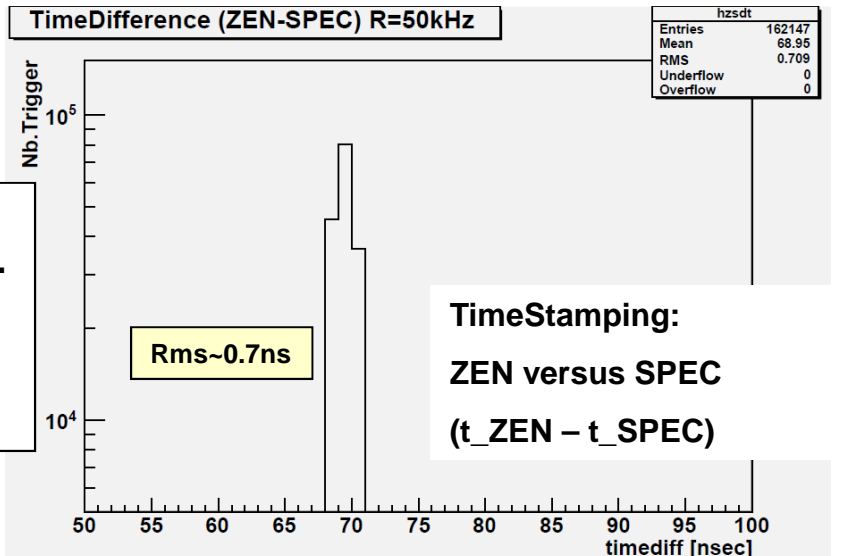
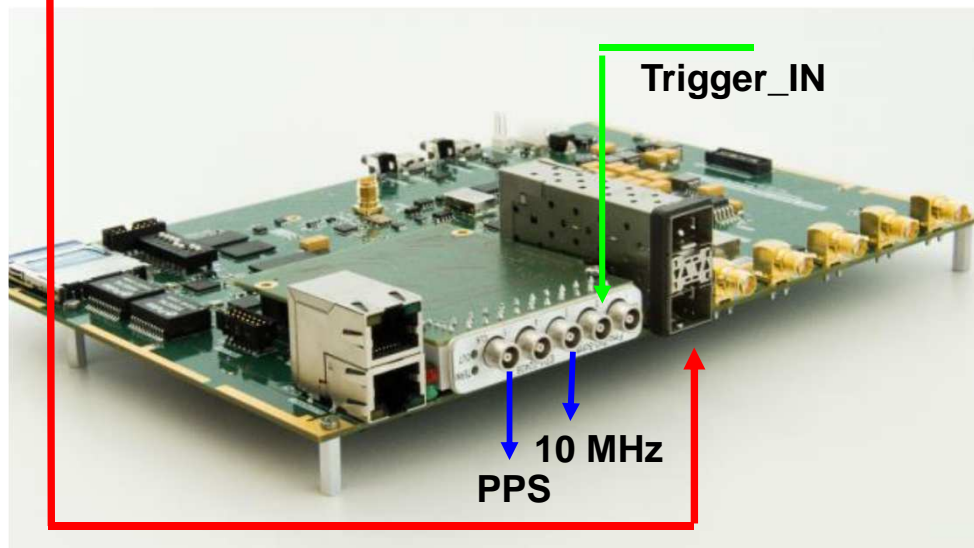
**WR Master: WR Switch**



ZEN: verifying the time-stamping (2ns).  
High trigger rate proven. ~500kHz is realistic.

**1Gbit fiber**

**WR-Node: ZEN card**



ZEN-only test: NextTrigger Time-difference with nsec (very stable pulser).





# Conclusions



# Conclusions ( 1 )



- > **White Rabbit is a new standard for Clock and Frequency Transfer over Ethernet**
  
- > **A number of large-scale AstroParticle experiments need sub-ns-timing ...**
  
- > **.... White Rabbit (WR) perfectly fits their requirements**
  - **Clock distribution**
  - **Trigger time stamping**
  - **Active calibration ('ext. trigger')**
  - **In-situ-verification ( data or/and hardware redundancy )**
  - **10-20 Picosecond-scale precision, still improving**
  
- > **WR allows to avoid custom solutions per experiment , that are**
  - **expensive, hard to maintain**
  - **less reliable and precise**
  - **hard to precisely calibrate , .....**

# Conclusions ( 2 )

## > WR

- based on standard GbE (Ethernet technology)
- as an open hardware / software project it offers good user-support
- commercial support (>3 companies), which are well debugged
- documented calibration / verification procedures
- works almost “out of the box”

> WR is considered for future projects: LHAASO, CTA, ICE3-Gen2, ...

> WR was implemented, and is operating in the HiSCORE Prototype

- Time-stamping
- Operating as expected: precision, accuracy ... first physics EAS results  
( ‘end-to-end test by shower‘ )
- Long-term cross-checks (since 2013...)
- Bonus: a fully WR-based GHz prototype DAQ, ready for >km<sup>2</sup>-scale
- Timing-solution is generic – and easily adapted to other applications

# Conclusions ( 3 ) - Technicalities

## > Time-stamping with $\mathcal{O}(1 \text{ nsec})$

- SPEC : '1 nsec' by now >2 implementations on SPEC (DESY, APC/Paris, ...)
- ZEN : 2 nsec ok  $\rightarrow$  1 nsec next week 😊 (DESY)
- In preparation: resolution < 1 ns.....

## > Accumulated WR-experience shapes design of CTA + ...

- Basics methods
- Intrinsic data-redundancy (!)
- Optional self-verification (!)

## > Next: exploit the system-aspects, intrinsic to complex, WR-driven DAQ's.

## > Impressive progress over last few years

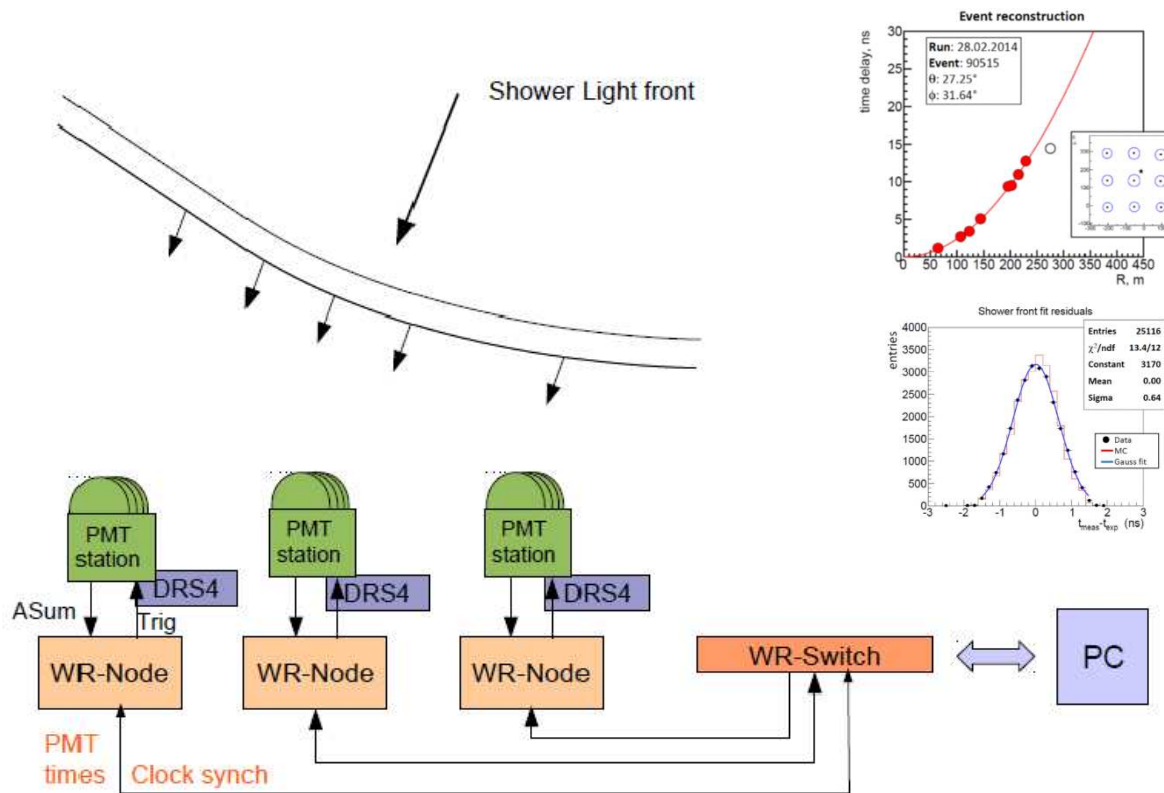
- new WR-devices, improved precision and services
- new users / applications

## > Finally: Many thanks to the excellent work & support by the WR-team, and by the companies 7Sols, CreoTech.



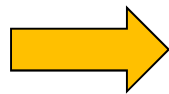
Thank you.

# BonusSlide. Build your own nsec-DAQ



## Ingredients:

- N stations (scintillator / PMT)
- 1x SPEC per station
- Fiber cable to WRSwitch

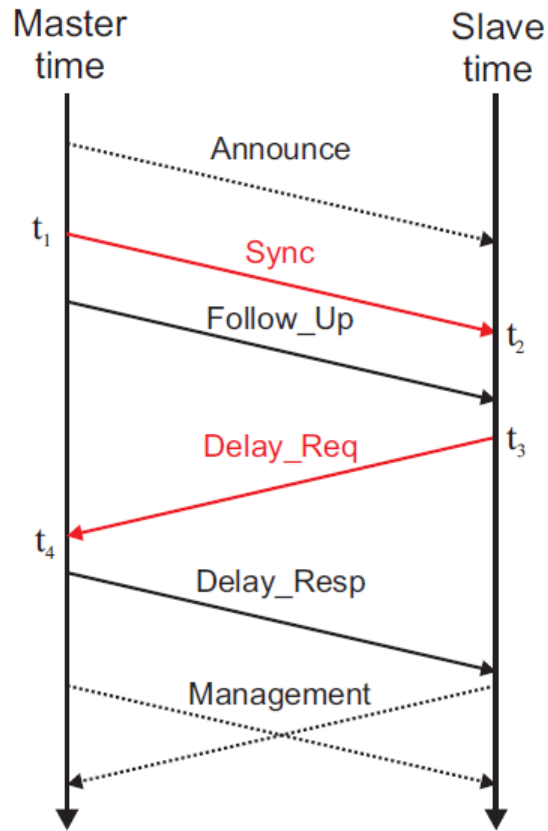


- Collect nsec-timestamps on your Laptop/PC
  - Reconstruct EAS wavefront ...
- (Optional: use DRS4/EB boards for pulse-sampling )



.... Backup slides ....

# WR basics....



Simplified PTP message exchange diagram.

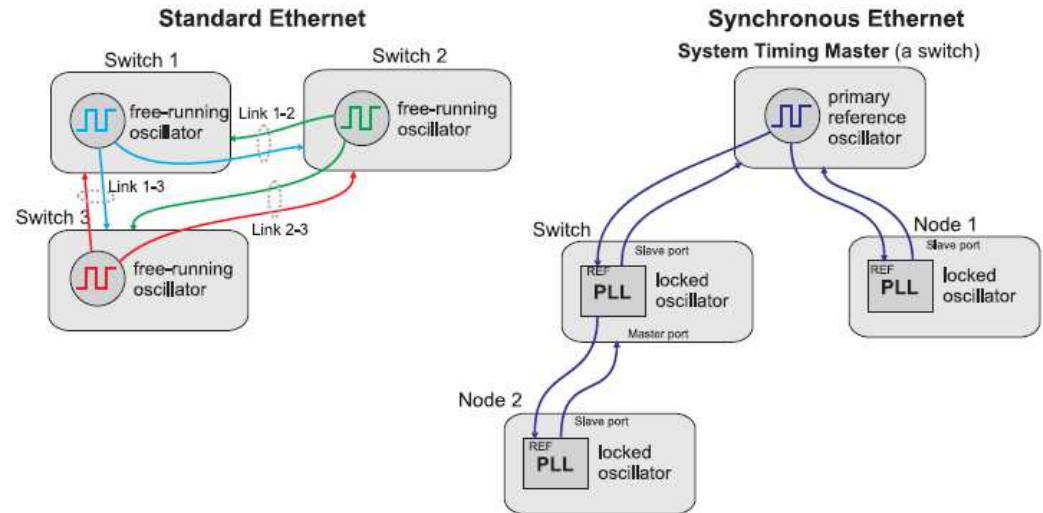


Figure 3: Simple illustration of layer-1 syntonization.

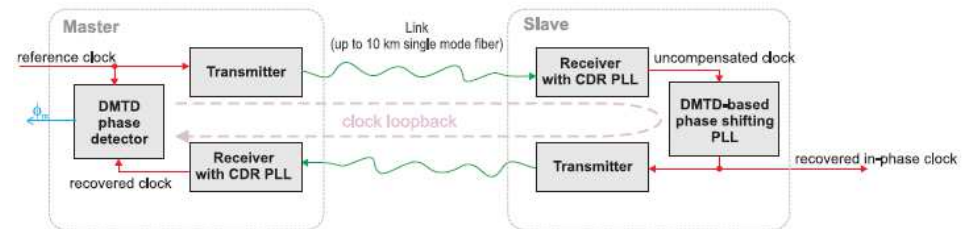
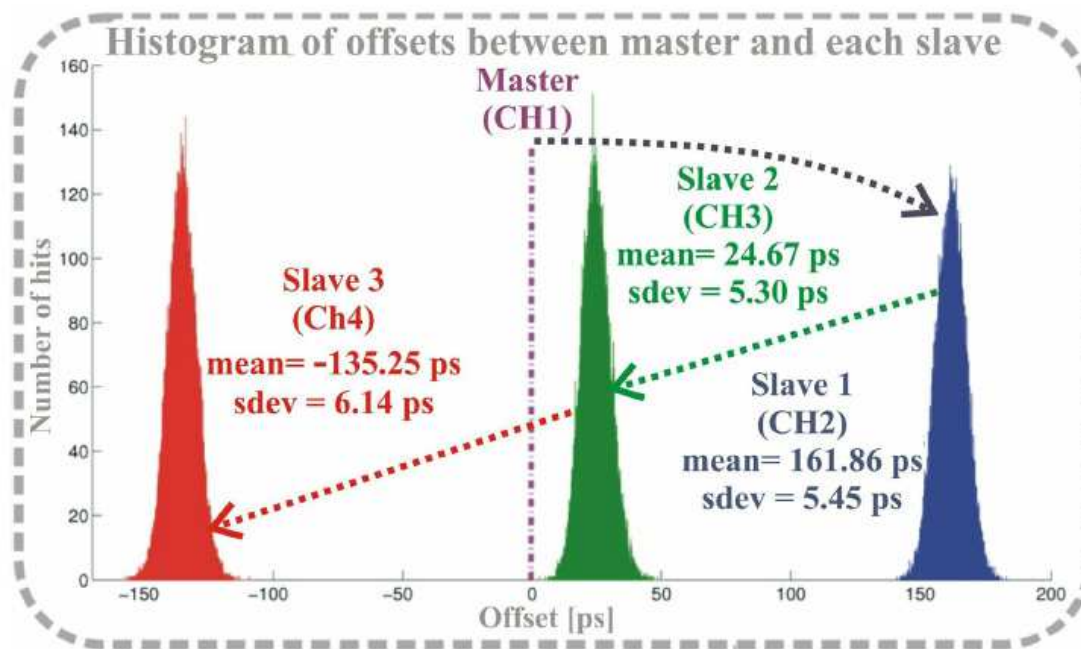


Figure 4: Phase tracking block diagram.





.. Figure 8: Histograms of PPS output offsets of three cascaded WR switches with respect to the PPS pulse output in the master switch.

# An example WR-Node

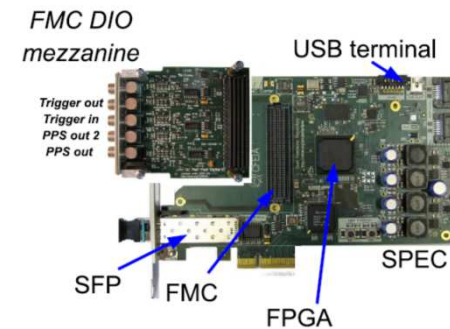
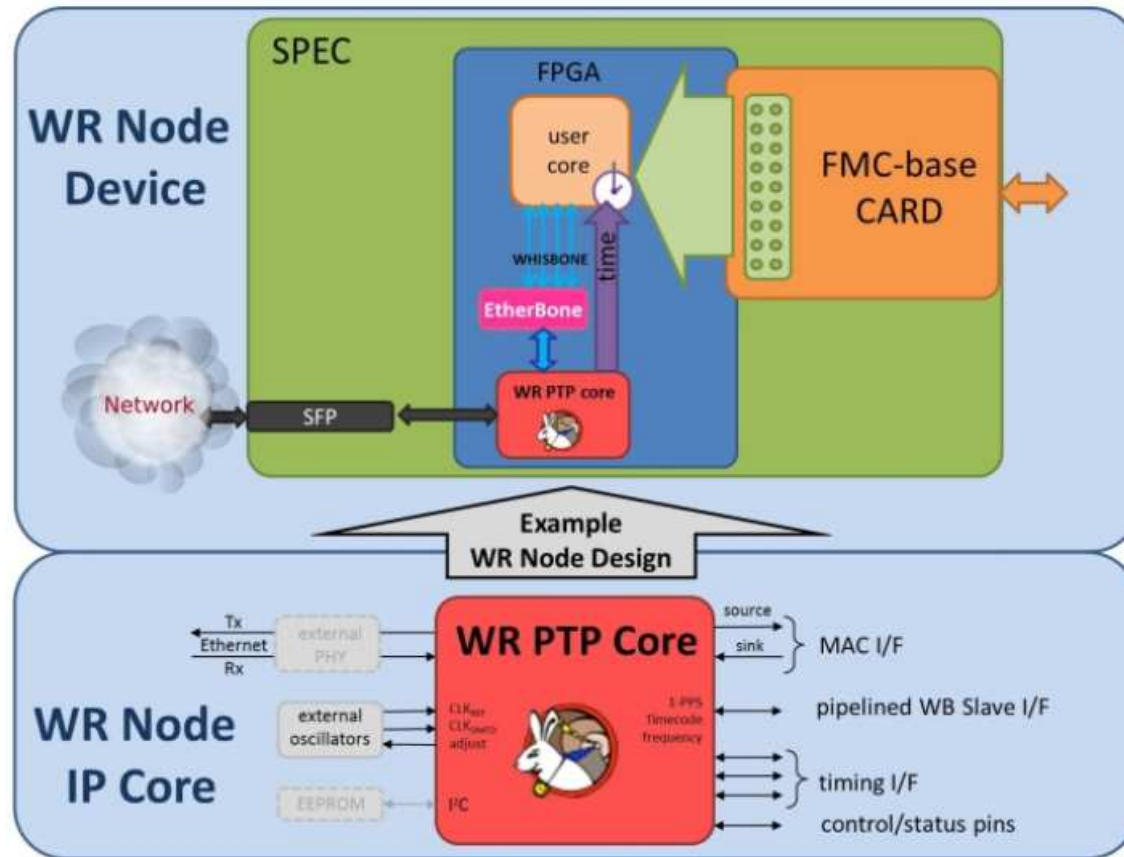
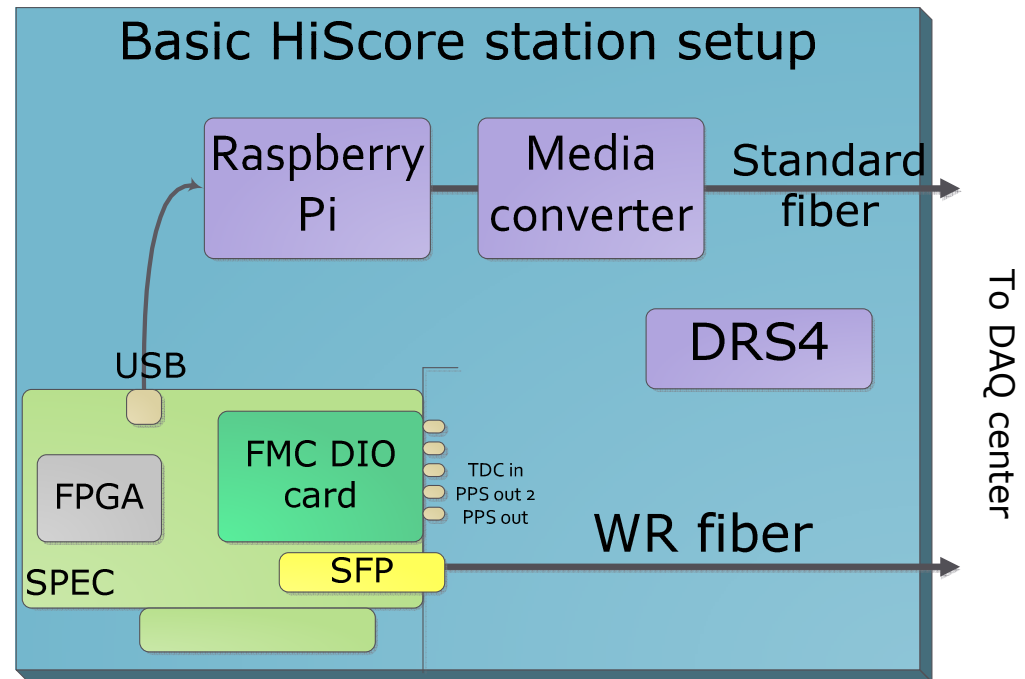
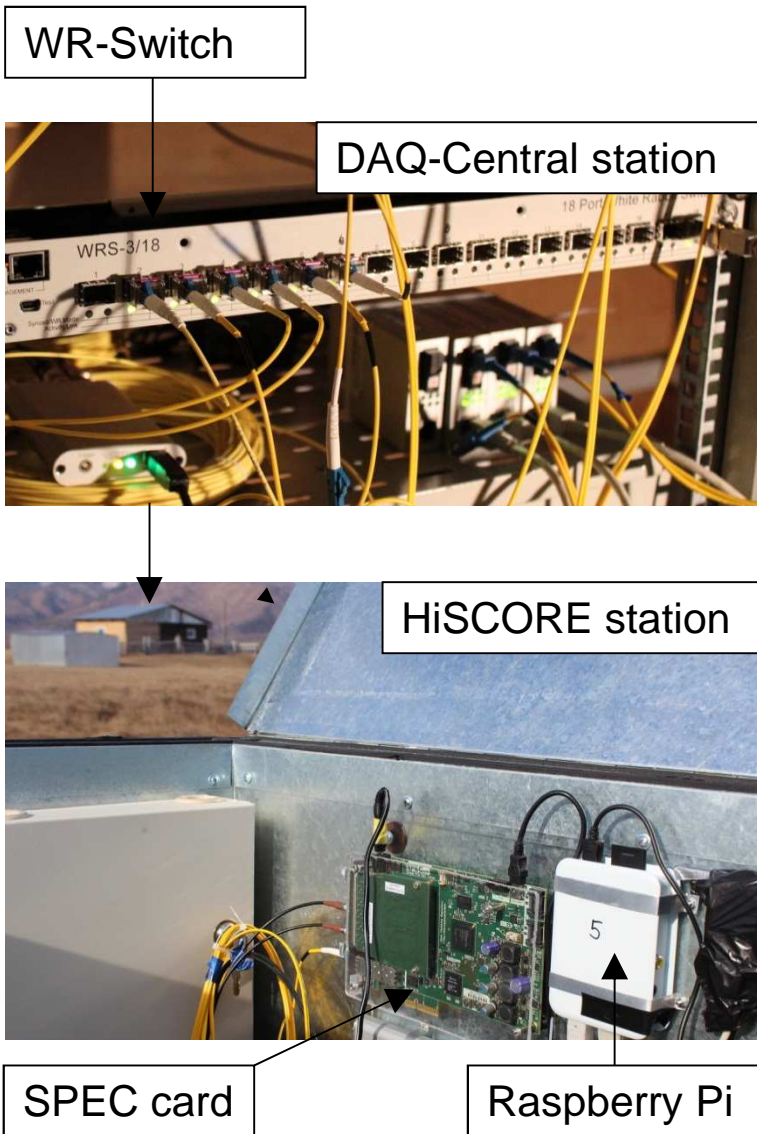


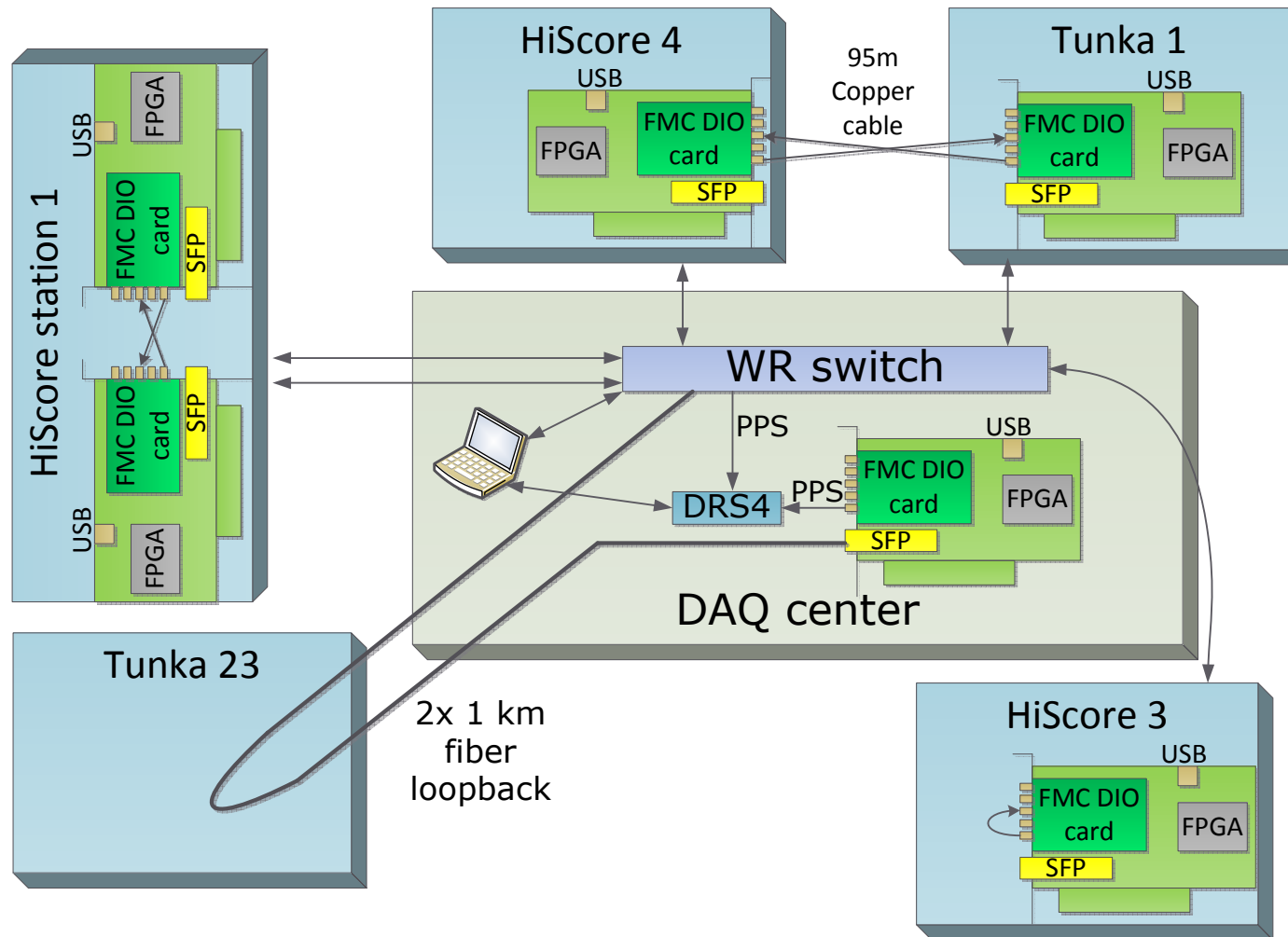
Figure 9: An example WR node.

# HiSCORE setup overview



- DRS4 as 5 GHz “digital scope”
- Raspberry Pi transports
  - USB Terminal
  - DRS4 (Domino Ring Sampler)
  - Temperature sensor
  - ...

# HiSCORE : WR Test-Setup 2012

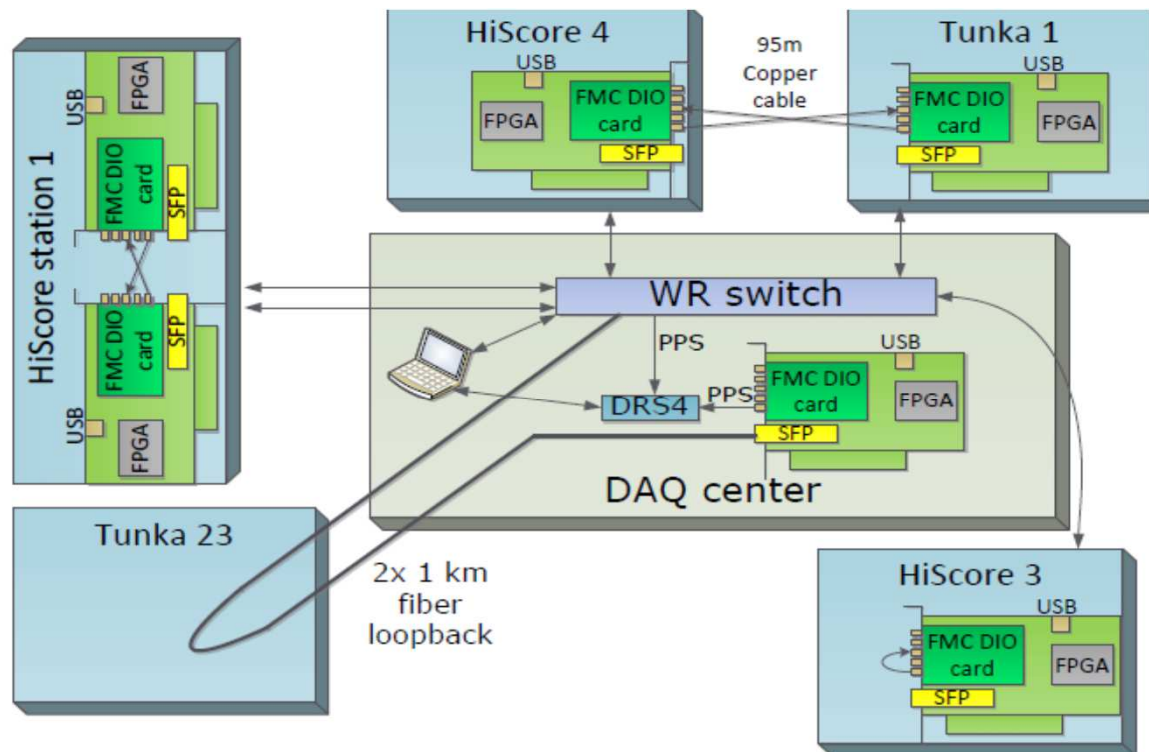


PPS signals (DIO output 1) connected to TDC-inputs (DIO input 3)

# WR – setup in Tunka

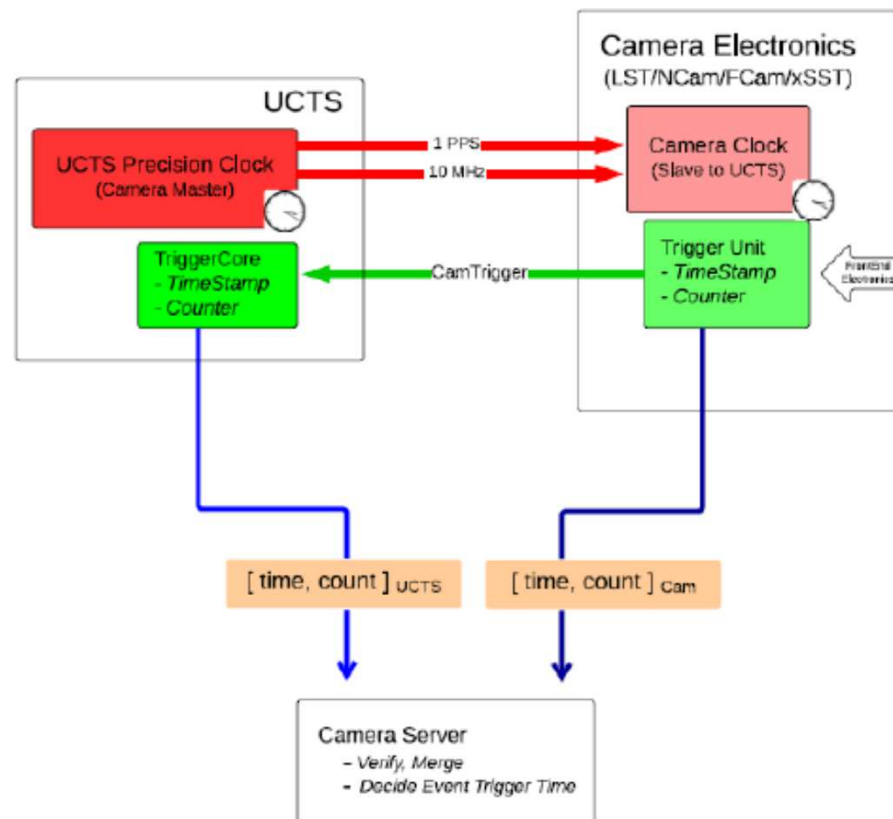
**White Rabbit Installation with a maximum of redundant cross-calibration options (October 2012 - today):**

- > 2km loopback fiber cable connected to DRS4 to compare WRS and SPEC (2km) PPS clocks
- > Crosswise PPS->TDC connection to test TDC and White Rabbit
  - 2x SPEC within HiS1 station
  - 2x SPEC in 2 stations (HiS4 + Tunka-1)
- > Loopback PPS connection to test TDC performance (HiS 3)



# CTA Timing (zoomed) : UCTS-Card and Cameras

- UCTS = “Unified ClockDistribution & TimeStamping Card” at each Camera



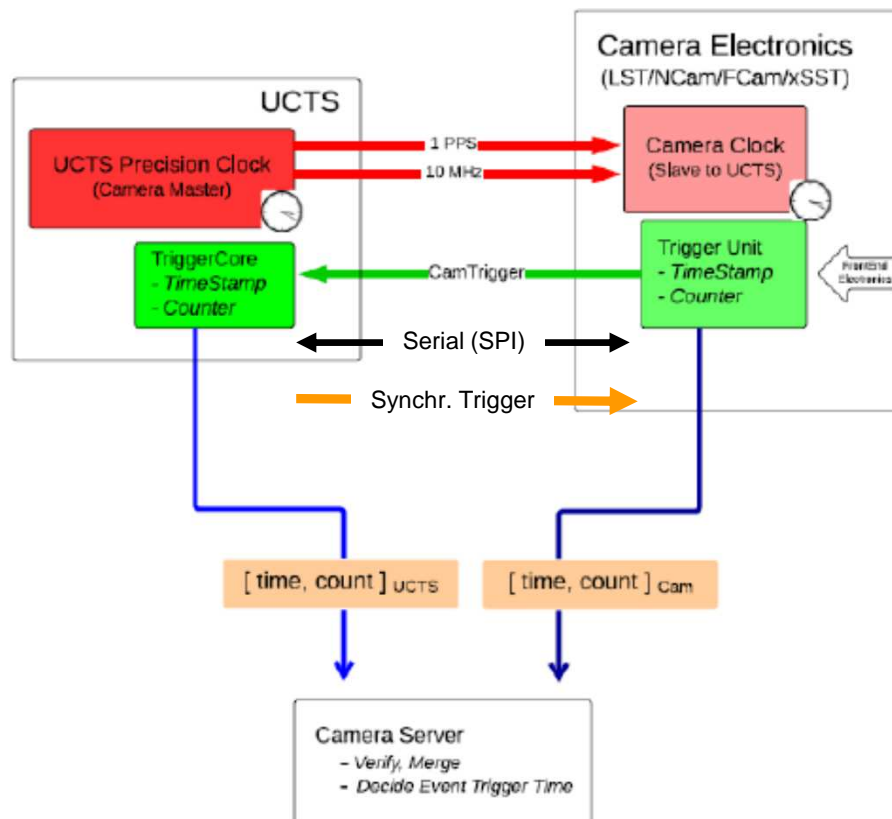
- UCTS Interface w/ Camera:**
1. Receive CamTrigger
  2. Send Clock (PPS/10MHz)

**Figure 1:** Layout of the Double-Clock/Double-Timestamping architecture using a generic camera and the UCTS-Board. Both UCTS-Board and camera electronics generate a trigger message  $[t, count]$  including a time stamp  $t$  and an event counter  $count$ . The camera server verifies the integrity of event counter and time stamp.

*Details of data flow still to be decided (CServ,...)*

# CTA Timing (zoomed) : UCTS-Card and Cameras

- UCTS = “Unified ClockDistribution & TimeStamping Card” at each Camera



## UCTS Interface w/ Camera:

1. Receive CamTrigger
2. Send Clock (PPS/10MHz)
3. Serial line (aux.info // bidir.)
4. Send Synchron. Trigger

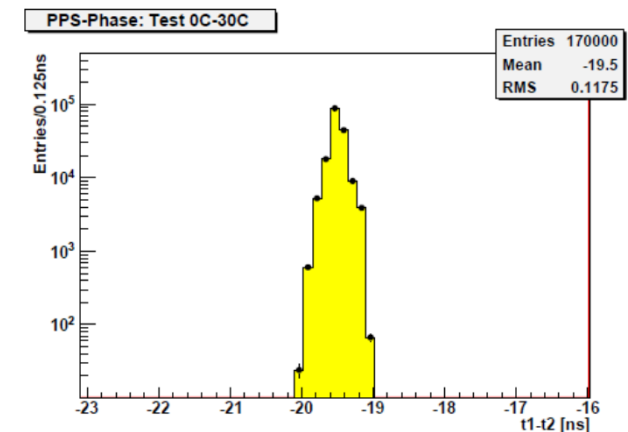
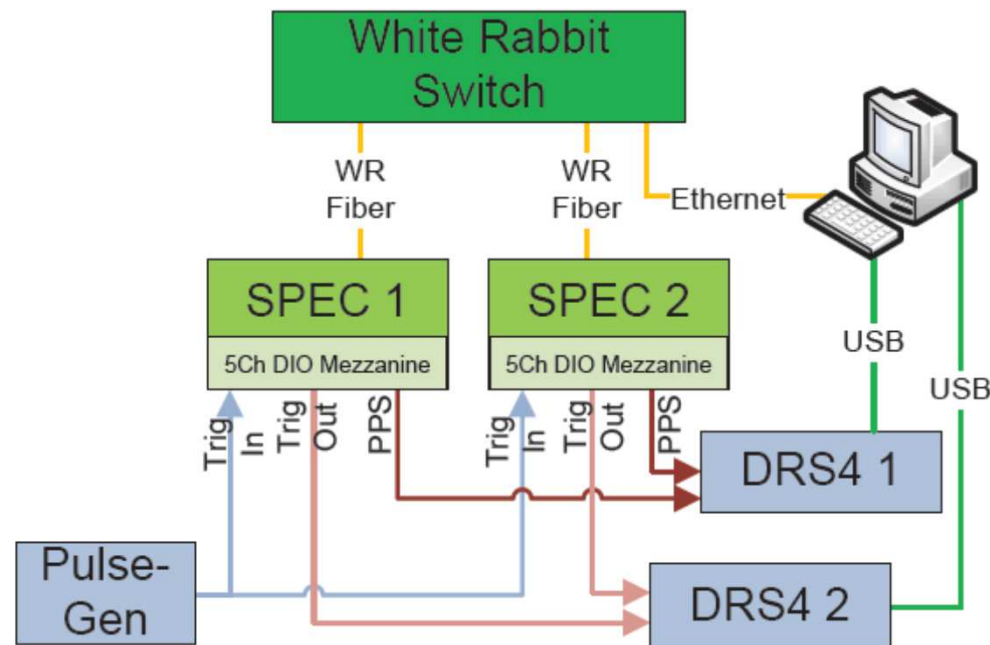
Note: A synchronous trigger is pre-programmed, and issued with ns-resolution and 200ps jitter – with respect to all cameras/ devices.

**Figure 1:** Layout of the Double-Clock/Double-Timestamping architecture using a generic camera and the UCTS-Board. Both UCTS-Board and camera electronics generate a trigger message [t, count] including a time stamp *t* and an event counter *count*. The camera server verifies the integrity of event counter and time stamp.

# White Rabbit - Executive summary (3)

## > Longterm-tests @ DESY-Environmental Chamber

- DESY environmental-chamber (CTA-mirror tests); April/May, 2013: ~10 days of tests
- Temperature -20C ... +40C 2-3 days cycles → FiberCable 500m
- 0C ... +30C 2-3 days cycles → WR-Node (the camera card)
- No measureable temperature effects observed
  - Trigger-stamps : +1ns → rms<0.5ns
  - Phase of 1 PPS-references : rms < 200ps



**Figure 4:** Experimental Setup (baseline configuration). WR fibers are 20 m long to SPEC1 and 520 m to SPEC2. For tests in the environmental chamber, the 500 m WR-fiber and/or the SPEC2 card are located in the DESY-climate chamber.



# White Rabbit - Executive summary (4)

- Network structure
- Tests-A: single WR-Switch (max. 17 Telescopes) → OK
- Tests-B: two-level WR's  $17 \times 17 = 289$  Telescopes



3x WRSwitch  
+ DRS setup  
adapted

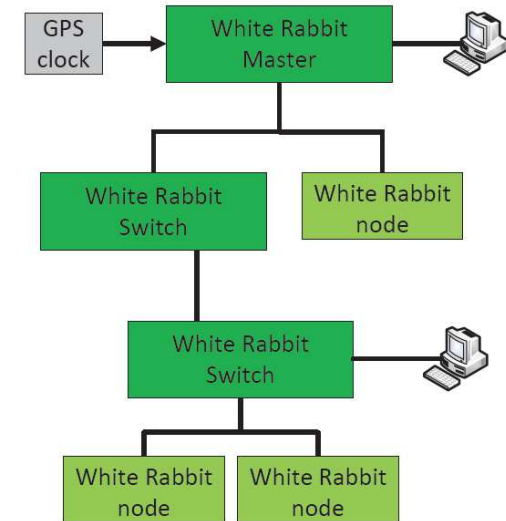
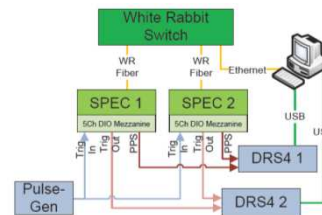
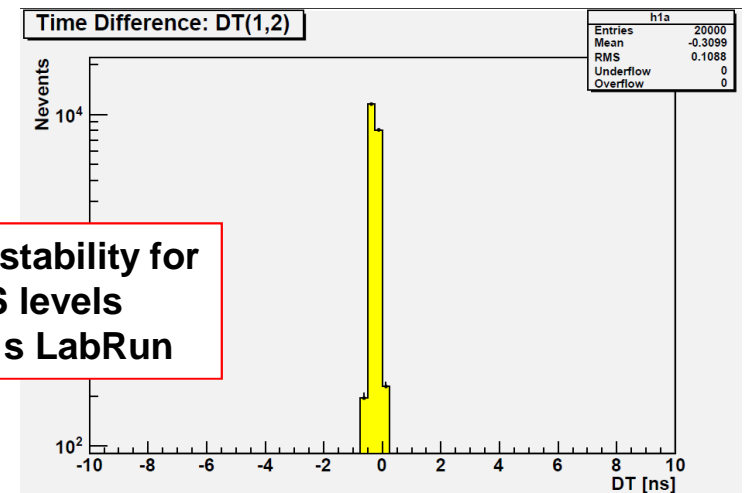


Figure 1: The White Rabbit network

- No measureable network effects observed → ~300 Telescopes are safe
  - Trigger-stamps :  $\pm 1\text{ns}$  →  $\text{rms} < 0.5\text{ns}$
  - Phase of 1 PPS-references :  $\text{rms} < 200\text{ps}$

- Do we want next step (3 levels) ?  
 $17^3 = 4913$  Telescopes

Timing stability for  
- 2 WRS levels  
- 20000 s LabRun



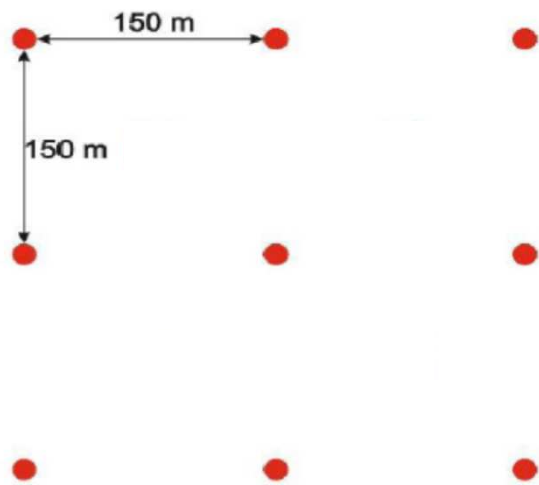
# White Rabbit - Next HiSCORE setup

Plan for October 2013:

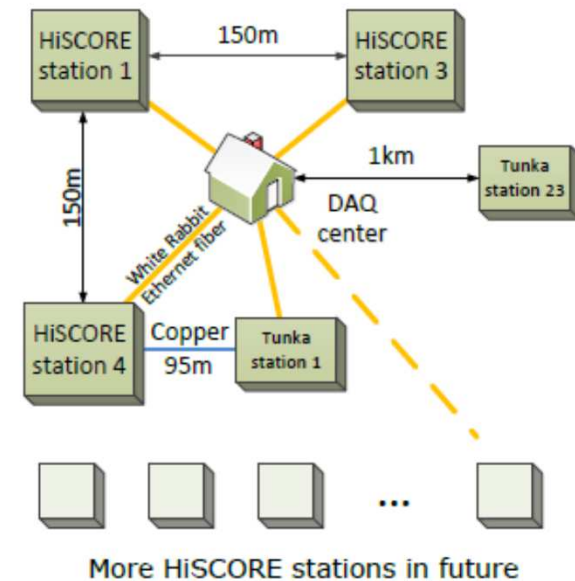
> HiSCORE array:

Install the 9 station array with WhiteRabbit (0.1 km<sup>2</sup>)

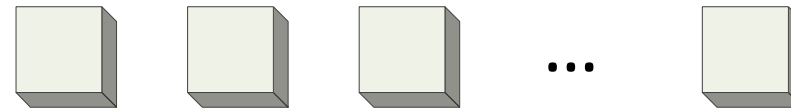
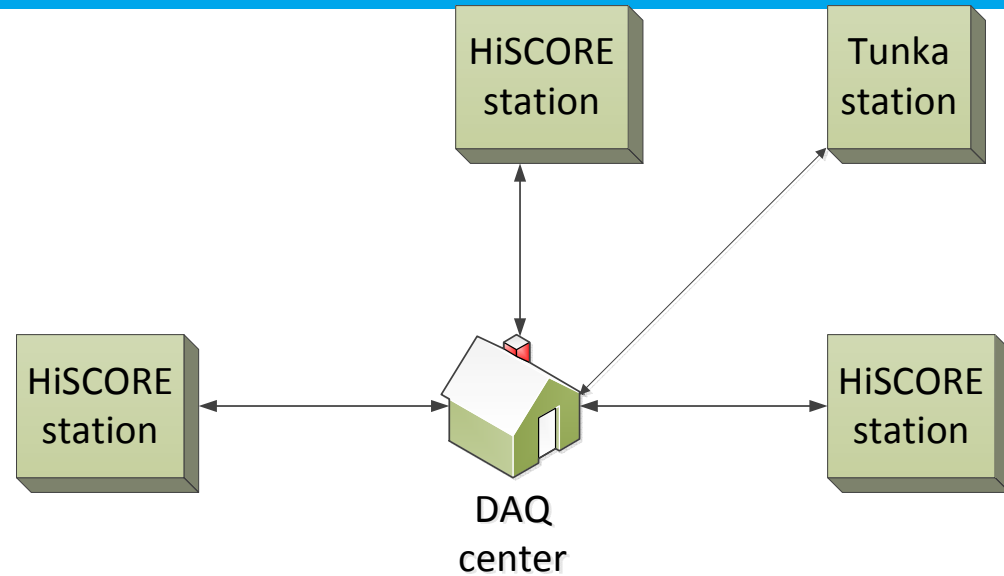
- A full-scale test (aiming at 50TeV gamma's)



The HiSCORE-2013 array: 9 stations



# HiSCORE setup overview (Oct.2012 commissioned)



More HiSCORE stations in future



- > 1 km<sup>2</sup> in 2013/14 : 20-40 stations
- > 100 km<sup>2</sup>: > 2000 stations