Multivariate analysis techniques and machine learning algorithms

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DESY Summer School, Zeuthen, 08.08.2018

HELMHOLTZ RESEARCH FOR GRAND CHALLENGES

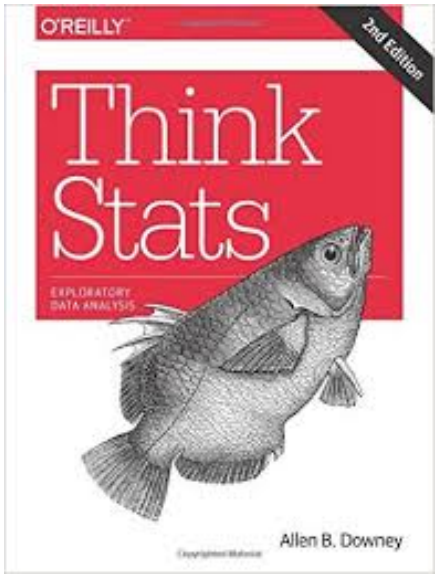
DESY.

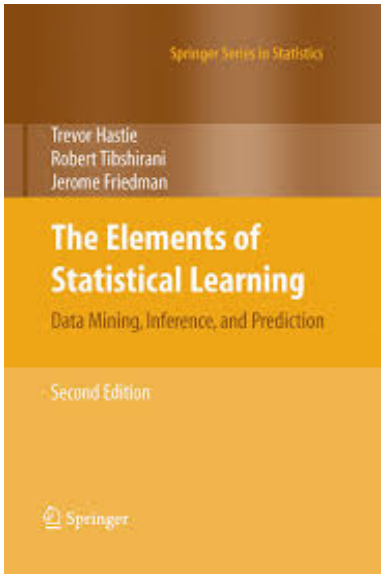
Outline

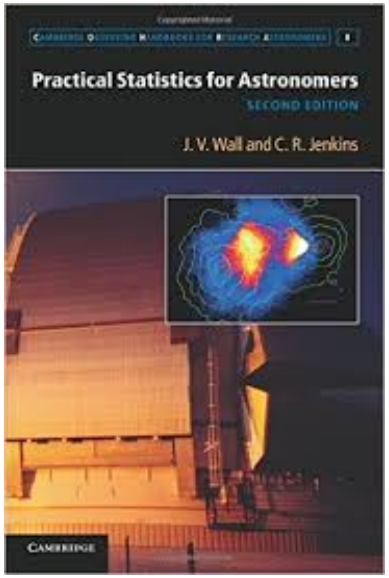
- What this lecture is *not*
  - a math and statistics class, a programming course
- What this lecture tries to be
  - an “experimental astroparticle physicists approach to data”
- PART 1 (~25 minutes)
  - Data Science: the bigger picture, or, what we are all facing sooner or later
  - Machine learning: The basic basics
- PART 2 (~45 minutes)
  - Multivariate analysis (MVA) techniques: decision trees, neural networks, deep learning
  - Real-life examples: Boosted Decision Trees in γ-ray astronomy
- Also see lectures by Orel
- If anything is unclear just ask

Literature and Sources

- Many of the slides are inspired by these books and lecture notes
  - Think Stats: Exploratory Data Analysis in Python, A.B. Downey, Green Tea Press, 2014
  - The Elements of Statistical Learning: Data Mining, Interference, and Prediction, Hasti, Tibshirani, Friedman, 2009, Springer Series in Statistics
  - Data Science from Scratch: Joel Grus, O'Reilly, 2015
  - Practical Statistics for Astronomers, Jasper Wall (http://www.astro.ubc.ca/people/jvw/ASTROSTATS/)
  - Other references given throughout the presentation and at the end







Example for up-to-date review of MVAs in particle physics

REVIEW

https://doi.org/10.1038/s41586-018-0361-2

Machine learning at the energy and intensity frontiers of particle physics

Alexander Radovic[1]*, Mike Williams[2]*, David Rousseau[3], Michael Kagan[4], Daniele Bonacorsi[5,6], Alexander Himmel[7], Adam Aurisano[8], Kazuhiro Terao[4] & Taritree Wongjirad[9]

Our knowledge of the fundamental particles of nature and their interactions is summarized by the standard model of particle physics. Advancing our understanding in this field has required experiments that operate at ever higher energies and intensities, which produce extremely large and information-rich data samples. The use of machine-learning techniques is revolutionizing how we interpret these data samples, greatly increasing the discovery potential of present and future experiments. Here we summarize the challenges and opportunities that come with the use of machine learning at the frontiers of particle physics.

Calorimetry with BDTs @ CMS

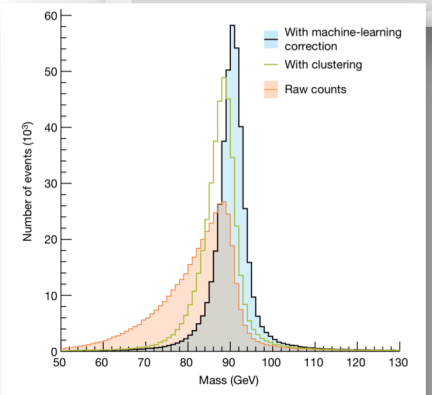


Fig. 1 | Machine learning for calorimetry at CMS. The mass distribution of Z bosons that decay to electron–positron pairs ($Z \rightarrow e^+e^-$), as measured in the central part of the CMS detector and binned into 1-GeV bins, is shown for three cases: using only the raw information from the detector (orange), after clustering the data (green) and after applying the machine-learning-based corrections discussed in the text (blue). The true position of the peak for this decay is 91 GeV. Image adapted from ref. [101] under a CC BY 4.0 license, copyright CERN, reused with permission.

Decomposing CNN response in NOvA experiment

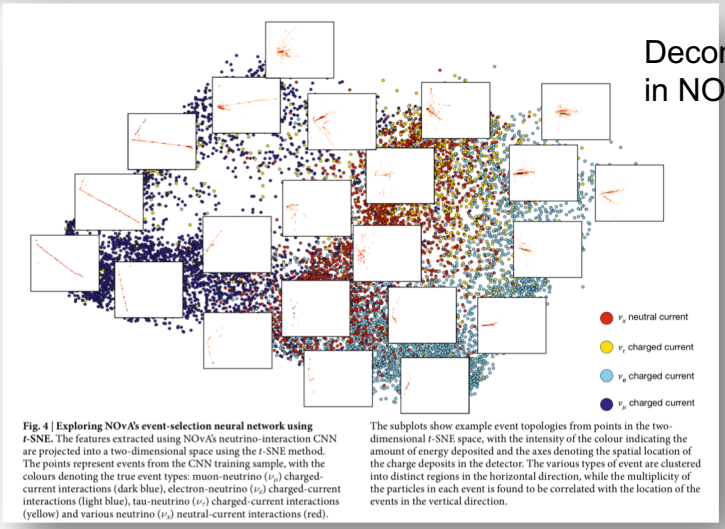
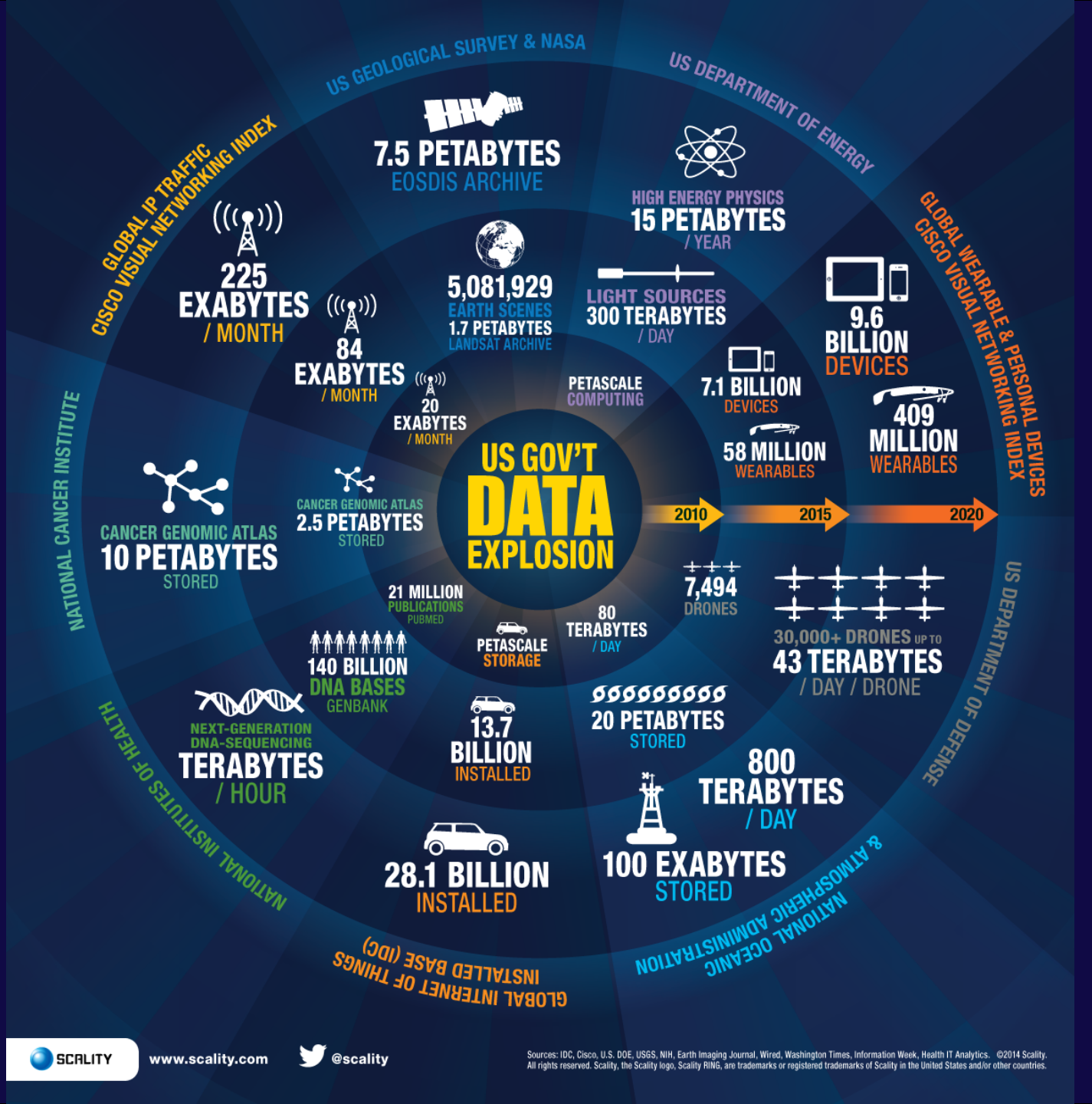


Fig. 4 | Exploring NOvA's event-selection neural network using *t*-SNE. The features extracted using NOvA's neutrino-interaction CNN are projected into a two-dimensional space using the *t*-SNE method. The points represent events from the CNN training sample, with the colours denoting the true event types: muon-neutrino (ν_μ) charged-current interactions (dark blue), electron-neutrino (ν_e) charged-current interactions (light blue), tau-neutrino (ν_τ) charged-current interactions (yellow) and various neutrino (ν_x) neutral-current interactions (red). The subplots show example event topologies from points in the two-dimensional *t*-SNE space, with the intensity of the colour indicating the amount of energy deposited and the axes denoting the spatial location of the charge deposits in the detector. The various types of event are clustered into distinct regions in the horizontal direction, while the multiplicity of the particles in each event is found to be correlated with the location of the events in the vertical direction.

Data Science and the basics about Machine Learning

DATA EXPLOSION

- in science
- in industry
- in every-day life



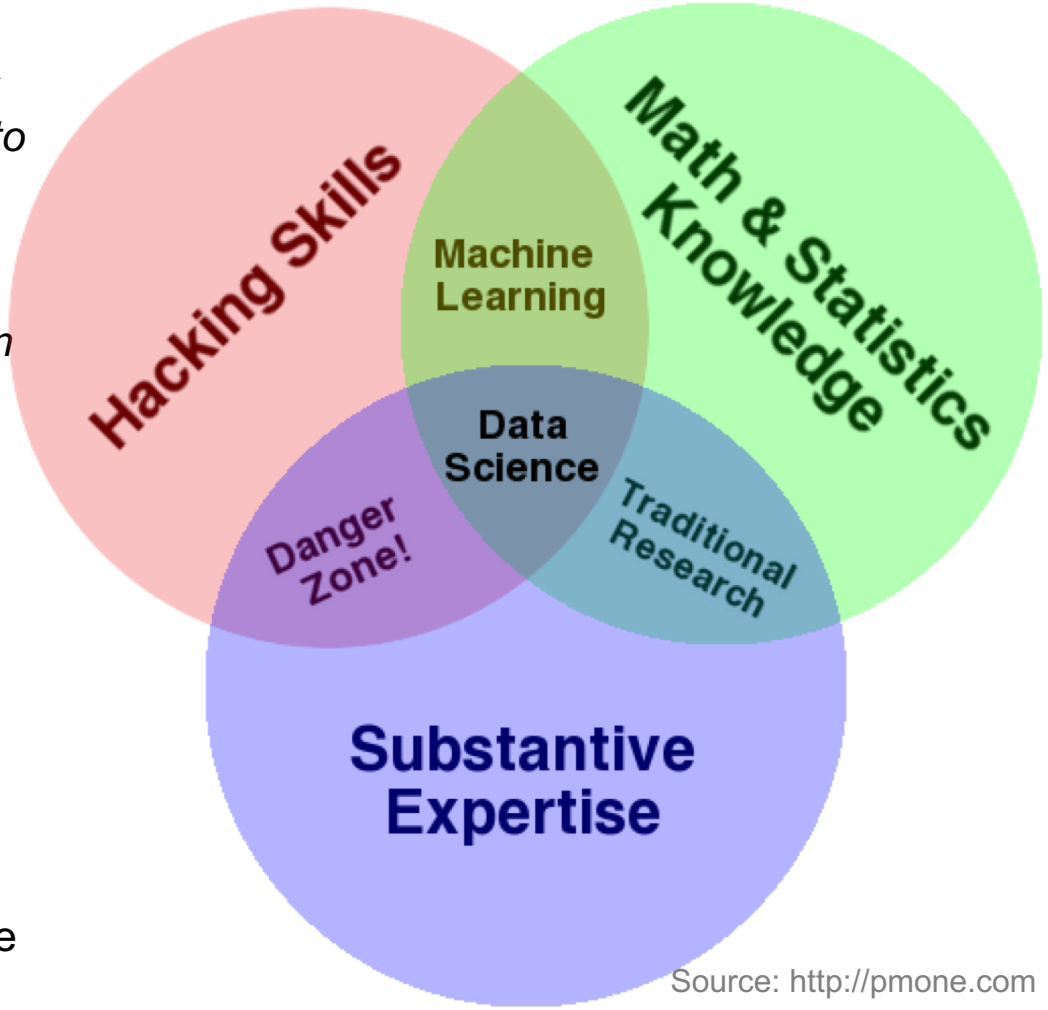
SCALITY www.scality.com @scality

Sources: IDC, Cisco, U.S. DOE, USGS, NIH, Earth Imaging Journal, Wired, Washington Times, Information Week, Health IT Analytics.

Big Data & Data Science

- According to Wikipedia
  - *"Data Science is an interdisciplinary field about processes and systems to extract knowledge or insights from large volumes of data in various forms, either structured or unstructured, which is a continuation of some of the data analysis fields such as data mining and predictive analytics, as well as knowledge discovery in databases"*

- Venn Diagram
  - Physicists and astronomers are the definition of Data Scientists
  - Fulfill all requirements and are developers of widely applicable code
  - Beware of the Danger Zone!



Source: http://pmone.com

How does machine learning fit in?

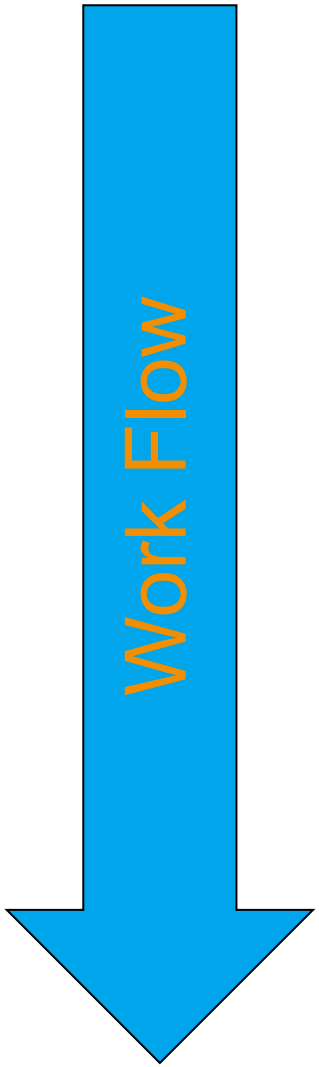
- Data Science covers techniques from different fields
  - signal processing, probability models, **machine learning**, statistical learning, data mining, database, data engineering, pattern recognition and learning, visualization, predictive analytics, uncertainty modeling, […], high performance computing
- Difficult to talk about machine learning without talking about data
- A few examples
  - *Facebook* uses hometown and current location to identify global migration patterns
  - *Target* tracks purchases and interactions to predict which of its customers is pregnant
  - *2012 US election* – Obama employed hundreds of data scientists to identify potential voters
- Data Science for social good (http://dssg.uchicago.edu)
  - Improve government
  - Help homeless people
  - Improve health care

Data analysis

> How to get data and what to do with it?

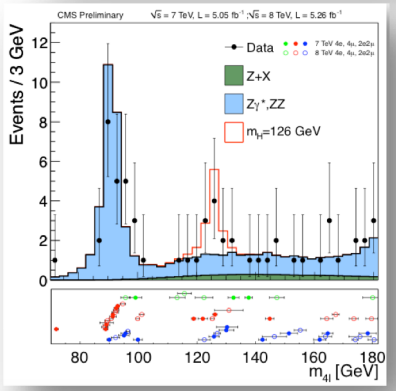
1. Data retrieval
   - from experiments
   - generate your own data
   - from internet or an Application Programming Interface (API)
2. Data preparation
   - calibrate raw data
   - remove outliers or noise
3. Data pre-processing
   - Identify parameters with valuable information in calibrated data (signal/background classification, pattern recognition)
   - First-level selection cuts and data reduction (“outliers”)
4. Data Mining (Machine Learning with multivariate analysis techniques)

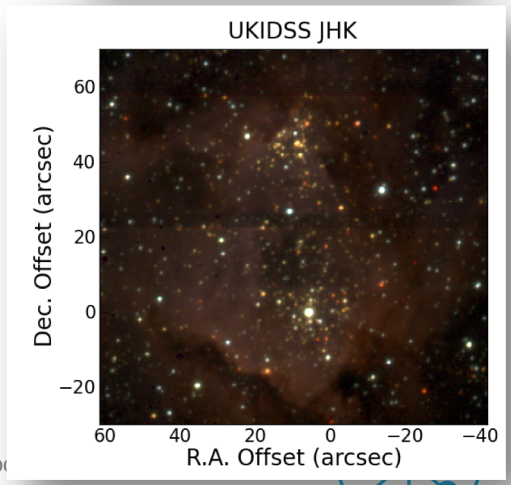
→ *What are the tools to do that?*



The toolkits

- ROOT
  - Mostly used in particle physics
  - Adapted in astronomy and astroparticle physics
  - C++, object-oriented
  - Higgs-discovery plots produced with ROOT
- IDL, MATLAB, R, ds9, …
  - many statistics features and numerical methods
  - standard in different fields for many years, now being replaced by python
- Python
  - the new standard in industry and science





ROOT vs. python

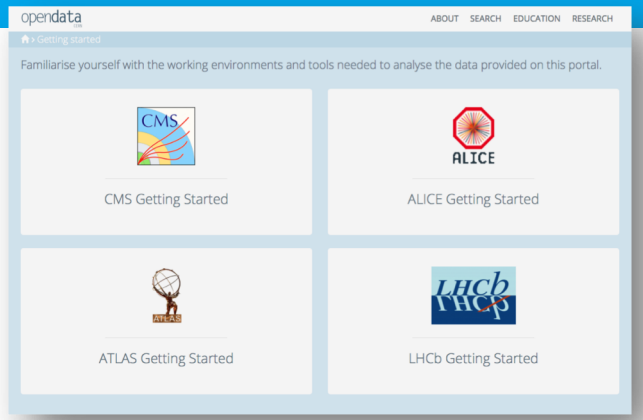
ROOT functionality	Python Equivalent
interactive interpreter	ipython, ipython notebook
TH1D,TH2D,TH3D	numpy.ndarray + numpy.histogramdd()
TProfile	numpy.ndarray
TGraph	numpy.ndarray + matplotlib plots
TTree	astropy.table or numpy.recarray
TMinuit	scipy.optimize or iminuit
2D/3D graphics	matplotlib
TMVA	scikit-learn
GUI	various (wxwidgets, Qt,gtk)
AstroROOT	astropy.io.fits or fitsio
ROOFit	astropy.modelling or lmfit
Reflex, CINT	not needed
TMatrix, etc	numpy.ndarray + scipy.linalg
TMatrixTSparse	scipy.sparse
TList	list
TArray, TObjArray	list
TMap, THashList	dict
TRandom	numpy.random + scipy.stats
Math, MathMore	numpy + scipy
Script compilation	Numba, Cython
ROOT::Math::VirtualIntegrator	scipy.integrate
–	astropy.coordinates
–	astropy.units
–	astropy.time
–	astropy.wcs (projections)
–	numpy.ndarray (n-dimensional tables)
–	scipy.interpolate.interpnd (n-dimensional interpolation)
–	scipy.signal (digital signal processing)

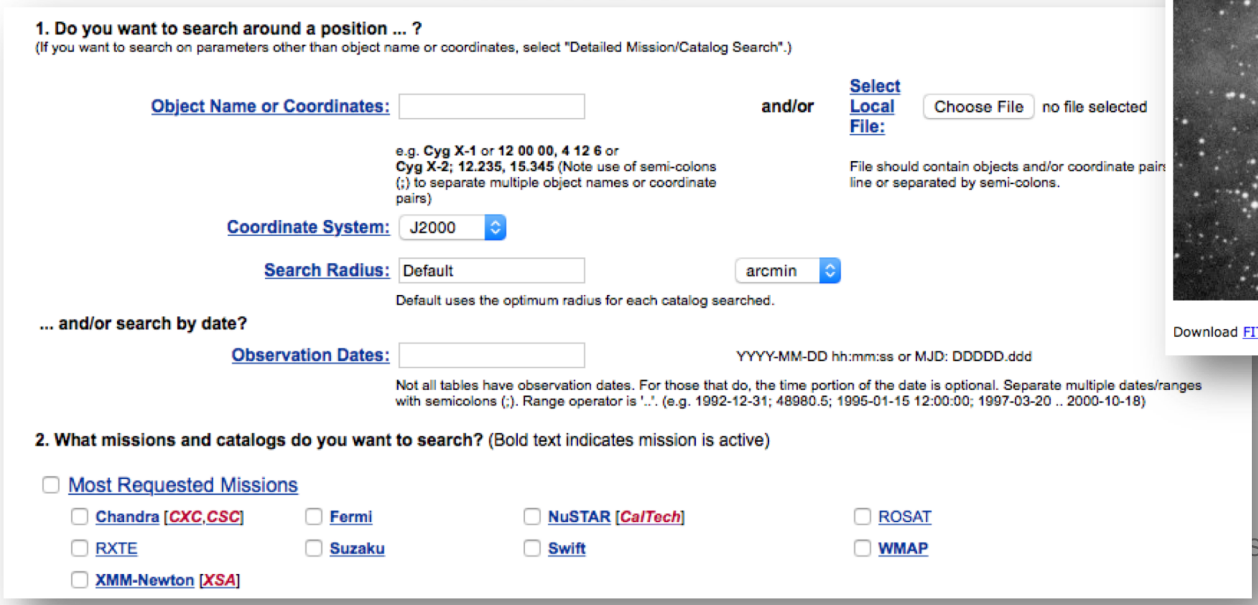
python

- provides more functionality than ROOT
- vastly more external developers
- shared by many communities (scientific and non-scientific)
- better/cleaner design
- quicker and easier to get things done
- more lightweight

Data retrieval

- Open access is the way to go
  - Astronomical observatories after proprietary time
  - Provided via webpages and online archives
  - Mostly in FITS format
  - Particle physics community is joining
  - Often via Virtual Machines
    - (Almost) no fiddling around with software versions, installations, external packages, etc.





Data retrieval

- Generate your own data
  - very useful in many circumstances
  - using random number generators
  - large-scale Monte Carlo simulations
- Monte Carlo simulations
  - most of you know those
  - for optimization, instrument characterization, …
  - drawing from probability distributions
- Application Programming Interfaces
  - Many webpages provide APIs
  - Interface to receive data in structured format (XML, JSON)
  - Examples: Amazon, Ebay, Facebook, Geopy, Google Maps, Last.fm, Rotten Tomatoes, Twitter

Generate function

```
TF1 parabola("parabola","[0]+[1]*x+[2]*x**2",0,20);
format_line(&parabola,kBlue,2);

TF1 gaussian("gaussian","[0]*TMath::Gaus(x,[1],[2])",0,20);
format_line(&gaussian,kRed,2);

TF1 gausppar("gausppar",the_gausppar,-0,20,6);
```

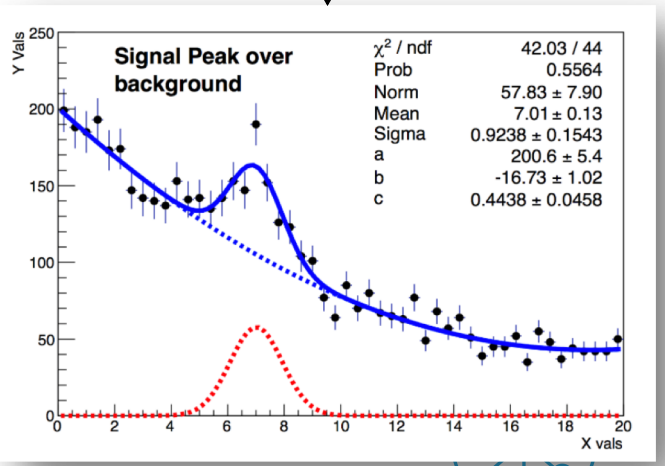
Fake data

```
// Fake the data
for (int i=1;i<=5000;++i) histo.Fill(gausppar.GetRandom());
```

Fit fake data

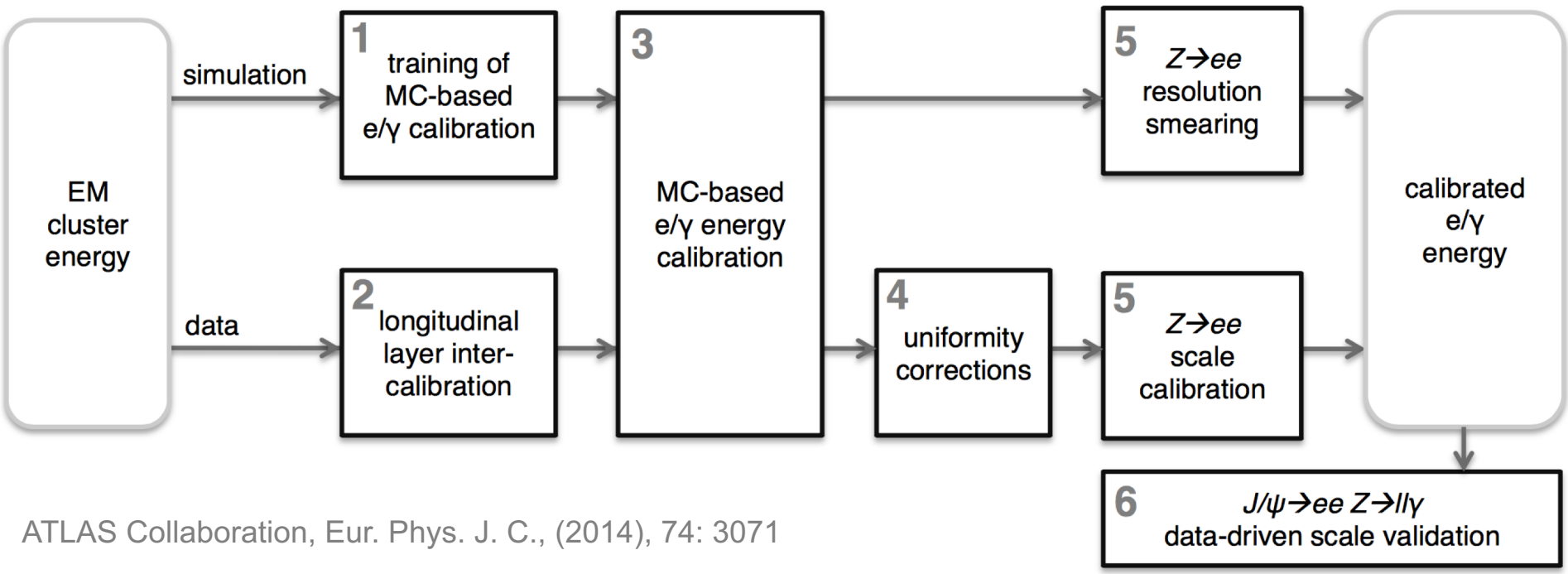
```
// perform fit ...
TFitResultPtr frp = histo.Fit(&gausppar, "S");
```

Draw everything



Data preparation

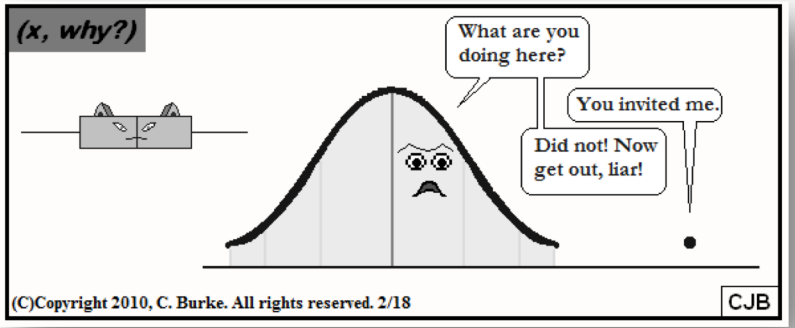
- The data you want to analyze is calibrated
  - Congratulations, someone has done the job for you
  - Don't forget to check also calibrated data
- The data you want to analyze is not calibrated
  - Lets roll up the sleeves and calibrate the data
  - Illustration of how important calibration (and simulations) are (ATLAS EM calorimeter)



ATLAS Collaboration, Eur. Phys. J. C., (2014), 74: 3071

Data pre-processing

- Identify outliers during data preparation
- Outliers
  1. Occur during data collection, i.e. human errors
  2. Malicious act (e.g. in questionnaires)
  3. Noise in data (temporal, spatial, etc.)
  4. Incorrect assumptions when looking at data or building model



- Importance
  - 1 & 2 very important in social sciences, medical studies
  - 3 & 4 very important in fields where data is collected with ‘instruments’ (e.g. physics, astronomy, geo-sciences)
- If kept
  - 1 & 2 may influence statistical analyses and outcome of statistical test (e.g. correlations)
  - 3 & 4 can fake signal, wrong understanding of background

Where are we now?

- We retrieved some data
  - from an instrument or from elsewhere
- We calibrated the data
  - or got calibrated data
- We inspected the data
  - identified outliers/features and removed them,
  - or know where they come from and include them in our model
- Building a model and interpreting the data

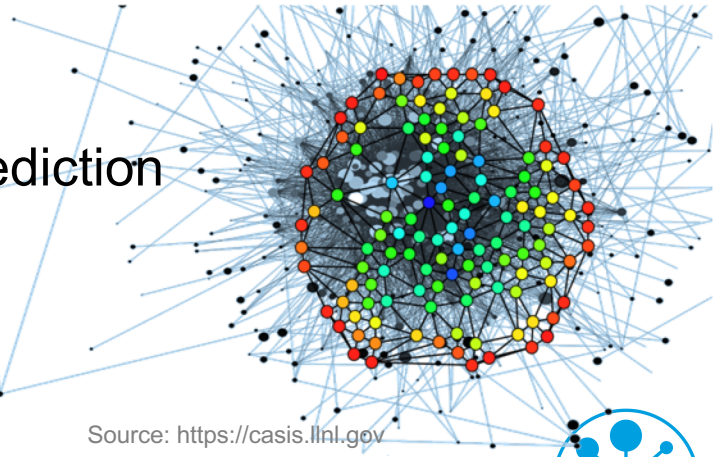
→ Dive a bit into Machine Learning Basics

Machine Learning

- What is Machine Learning?
  - Wikipedia: "*…is a subfield of computer science, evolved from the study of pattern recognition and computational learning theory in artificial intelligence. Machine Learning explores the study and construction of algorithms that can learn from and make predictions on data. Such algorithms operate by building a model from example inputs in order to make data-driven predictions or decisions, rather than following strictly static program instructions.*"

- Algorithms are the tools that perform the learning
- Algorithms are building the model, not the user
- Learn from, and make predictions on data
- The better the input data, the better the prediction

→ *What are these algorithms?*



Source: https://casis.llnl.gov

Machine Learning Categories

- Categorize, based on nature of the learning “signal” or “feedback” available to the system
- Supervised learning
  - algorithm is provided with example input and class labels (the desired output)
  - algorithm tries to find a rule that maps inputs to outputs
- Unsupervised learning
  - algorithm is provided with example input data and no class labels
  - algorithm has to find structure in input
  - E.g. discover hidden patterns in data, search for correlations
  - Learn at a specific task (find features) and learn the features themselves
- Reinforcement learning
  - Constant interaction of algorithm with dynamical environment to perform goal (e.g. drive car, don’t crash it).
  - Learn the rules of a game by playing it (goal: win game)

Machine Learning Categories

- Categorize, based on the desired output
- Classification
  - inputs are divided in two or more classes; produce model to map input to classes
  - Examples: spam filtering, signal/background classification, particle type
- Regression
  - the output is continuous rather than discrete as for classification
  - Example: What is the energy of an event with properties x,y,z
- Clustering
  - input data is to be divided into groups, which are not known beforehand
  - Where do sports-team supporters live and what is their typical age?
- Density estimation
  - finds the distributions of inputs
- Dimensionality reduction

Other types of tasks and problems

- Learning to learn
  - learns its own inductive bias based on past experience (frequent change of properties necessary to map input to output)
- Developmental learning
  - takes it one step further and generates own sequences of learning situations to acquire skill set
  - employing active learning, maturation, motor synergies, and imitation
- Relation to other fields
  - **ML** focuses on predicting, based on *known* properties – **data mining** focuses on discovering, based on *unknown* properties
  - **ML** and **Statistics** are closely related fields, now also with interdisciplinary approaches (Statistical Learning)
  - **Statistics** and ML now more or less combined in **Data Science**

PART 1

> Summary

- Data explosion is here
- Data is the bread and butter for physicists/scientists, but they also bring the skill set to do data science
- Data needs to be retrieved, prepared and cleaned before usage
- Data needs to be parameterized (e.g. PDFs) for generalization
- Plenty of toolkits available to do analysis – some with more focus on statistical methods than others
- Machine Learning algorithms build model, learn from data & make predictions on data
- Different classes of algorithms are used for different tasks (e.g. supervised vs. unsupervised learning)

→ PART 2: Discuss different ML algorithms

PART 2

Machine Learning Algorithms

Outlook

1. Toolkits

2. Decision Trees

1. Artificial Neural Networks

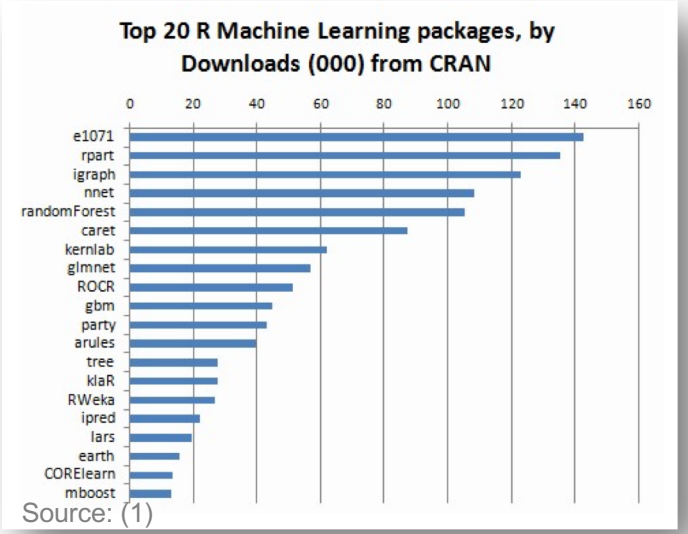
2. Deep Learning

PART 2.1

Toolkits

Toolkits

- ML algorithms
  - widely used in many programming languages
  - Fortran, C, C++, .NET, JAVA, python



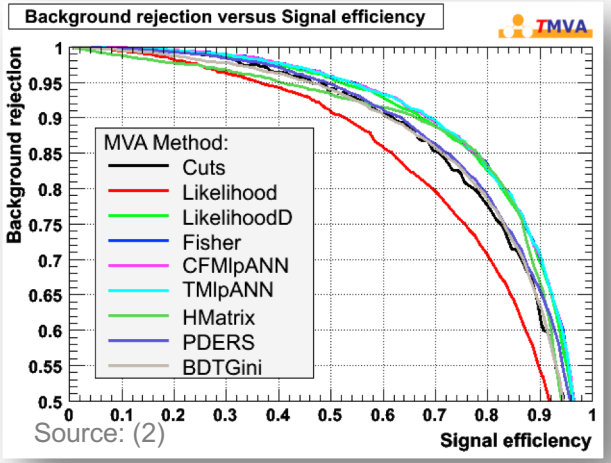
Source: (1)

- Nowadays, community is
  - moving towards toolkits
  - growing larger and larger
  - moving from science-driven to science/industry-driven development

- Here, introduce two packages
  - *T*MVA
  - scikit-learn

TMVA

- *TMVA*: Toolkit for Multivariate Data Analysis
  - built upon ROOT
  - provides framework for *supervised learning techniques*
  - provides processing, parallel evaluation and application of multivariate classification and regression methods, model selection and evaluation
- Methods
  - Rectangular cut optimization
  - Projective and multi-dimensional likelihood estimation
  - Linear and non-linear discriminant analysis
  - Neural Networks
  - Decision Trees
  - Support Vector Machines, etc.
- Usage
  - driven by the needs for high-energy physics applications
  - also applied in γ-ray astronomy (see later)

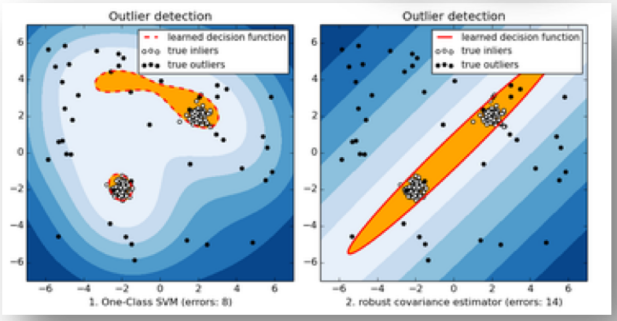


Source: (2)

scikit-learn

- Machine Learning in python
  - built upon python (fast, clean, robust, comprehensive and easy-to-use)
  - provides *supervised, semi-supervised, unsupervised* techniques,
  - additionally: dataset loading and transformations, model selection and evaluation, scaling to bigger data
- Methods
  - all of the TMVA methods, plus
  - Clustering
  - Decomposing signals in components
  - Density estimation
  - Unsupervised Neural Networks
  - Dimensionality reduction and pre-processing
- Usage
  - widely used in science and industry (Evernote, Spotify)

Source: (3)



Wissenschaftliche Artikel zu **scikit-learn machine learning in python . journal of machine learning**

Scikit-learn: **Machine learning** in **Python** - Pedrego - Zitiert von: 1902

Pylearn2: a **machine learning research** library - Goo

Orange: data mining toolbox in **Python** - Demšar - Zitiert von: 78

Scikit-learn: Machine Learning in Python

jmlr.org/papers/v12/pedregosa11a.html ▾ Diese Seite übersetzen

von F Pedregosa - Zitiert von: 1894 - Ähnliche Artikel

Scikit-learn: **Machine Learning** in **Python**. Fabian Pedregosa, Gaël Varoquaux, Alexandre Gramfort, Vincent Michel, Bertrand Thirion, Olivier Grisel, Mathieu ...

About us — scikit-learn 0.16.1 documentation

scikit-learn.org/stable/about.html ▾ Diese Seite übersetzen

Scikit-learn: **Machine Learning** in **Python**, Pedregosa et al., **JMLR** 12, pp. 2825- 2830, 2011. Bibtex entry: @article{**scikit-learn**, title={**Scikit-learn**: Machine ...

PART 2.2

Decision Trees

Decision Trees

> Concept

- a decision tree is a predictive modeling tool
- uses a tree structure to represent a number of possible decision paths
- *classification trees* predict class
- *regression trees* predict continuous (real) number
- decision trees map a *n*-dimensional input to a 1-dimensional output

Decision Trees

A general description

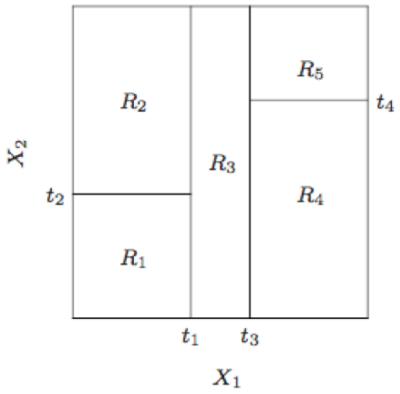
Consider inputs X_1 and X_2 mapped onto Y

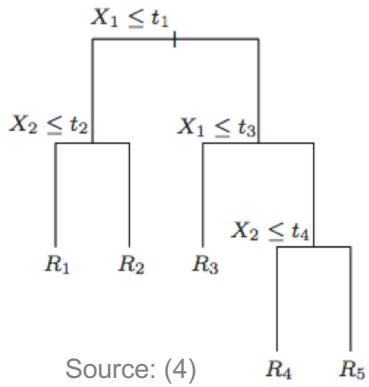
a) Feature space can be modeled by constants, but in different regions of parameter space

b) Described by a binary decision tree with cuts on input parameters at *nodes*

c) Terminal nodes declare class labels

→ Decision Trees split parameter space into rectangles and fit a simple model in each one (e.g. a constant)





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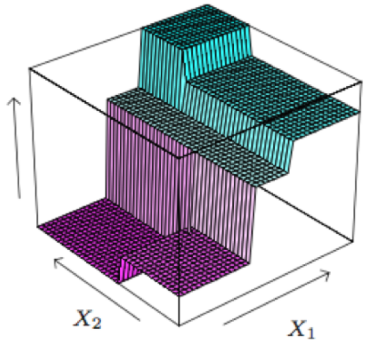
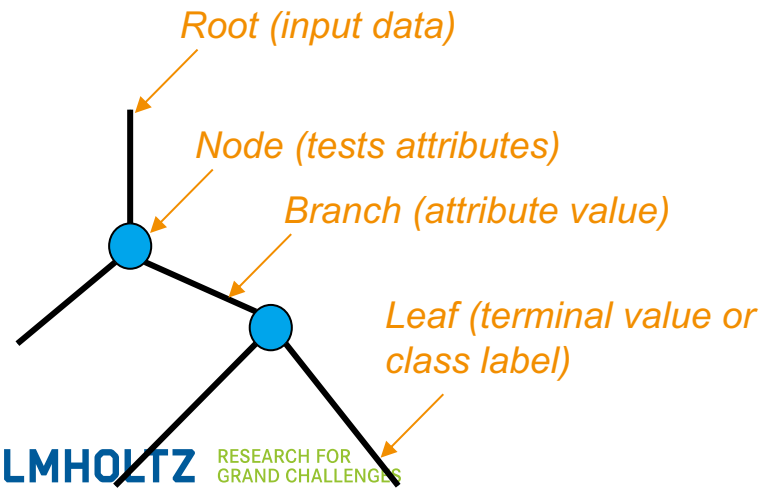


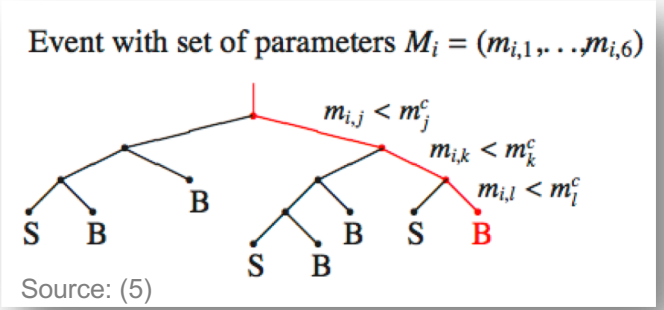


HELMHOLTZ RESEARCH FOR GRAND CHALLENGES

DESY.

Decision Trees

- Learning
  - using representative training data
  - identify variables/parameters with classification potential
  1. Split the source set (consisting of all classes) into subsets based on an attribute value test (binary decision or cut on continuous variable)
  2. Repeat process on subsets → grow decision tree
  3. Stop at a certain point (purity in leaves)



Source: (5)

- User input
  - Training set consisting of events of known classes
  - List of variables with classification potential
- Decision Tree output
  - Each leaf returns signal/background (classification mode)
  - Each leaf returns a specific value of the target variable

Decision Tree Learning

- Advantages
  - simple to understand and interpret
  - almost no data preparation
  - able to handle both, numerical and categorical data
  - ‘white box’, completely transparent
  - robust, even if the assumptions for the model do not perfectly describe the real data
  - performs well with large data sets
  - can classify data for which attributes are missing
- Limitations
  - decision trees learn to locally optimize
  - Overfitting and over-complex trees do not generalize well from training data
  - Some concepts are hard to learn by trees (e.g. parity, odd/even number classification)

Decision Tree: Ensemble Methods

- Single decision trees tend to overfit
  - i.e. instable to statistical fluctuations in the training sample

  → classifier response is altered compared to real data

  → lower performance in classification problems
- Ways out
  - train a forest of decision trees
  - classify events based on a majority vote of many trees
  - since same input training sample is used, we have to come up with different tree structures

  → Boosting (Boosted Decision Trees)
    - re-weighting of misclassified events, when building the next decision tree

  → Randomization (Random Forests)
    - randomly choose subset of events or classifying parameters for training of single tree

  → Pruning
    - grow trees to maximum extent, cut back insignificant leaves

Boosted Decision Trees

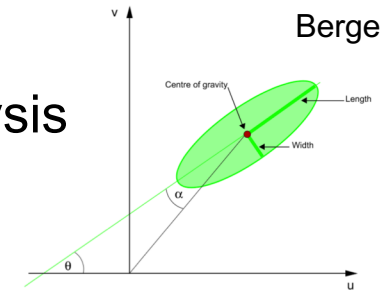
- Stabilizing and improving the decision tree response
  - Adaptive boost is the most common boosting algorithm (applicable to any MVA classifier)
  - Gradient boost (at least in TMVA only available for decision trees)
  - Bagging (resampling technique based on underlying PDFs)
- Adaptive Boosting
  - Imagine the building of the first tree, containing many leafs that contain signal and background events
  - first tree will have associated misclassification rate *err*
  - misclassified events will get a new weight when training the next tree:

$$\alpha = \frac{1 - \text{err}}{\text{err}}$$

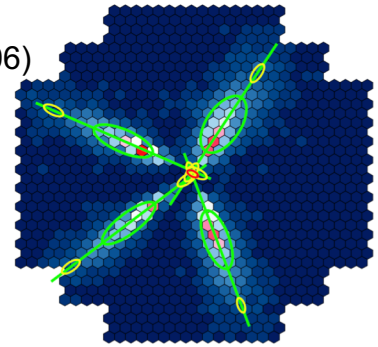
  - re-normalize such that the sum of weights is the same as the previous tree
  - if $h(\boldsymbol{x}_i)$ is the response of a single classifier and $\boldsymbol{x}$ the set of input parameters, the boosted event classification is $y_{Boost}(\boldsymbol{x})$ is given as

$$y_{\text{Boost}}(\mathbf{x}) = \frac{1}{N_{\text{collection}}} \cdot \sum_{i}^{N_{\text{collection}}} \ln(\alpha_i) \cdot h_i(\mathbf{x})$$

Example: BDTs in H.E.S.S. Data Analysis



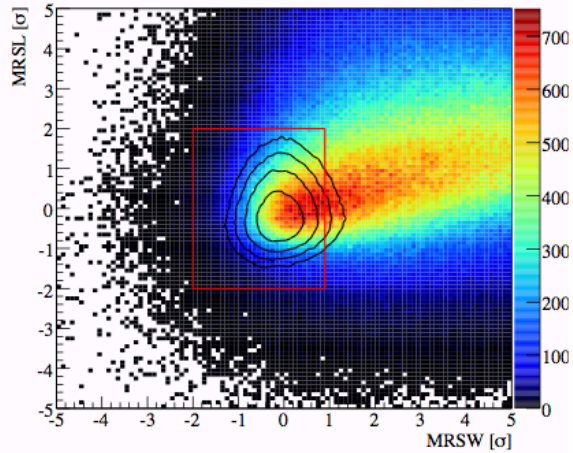
Berge (2006)

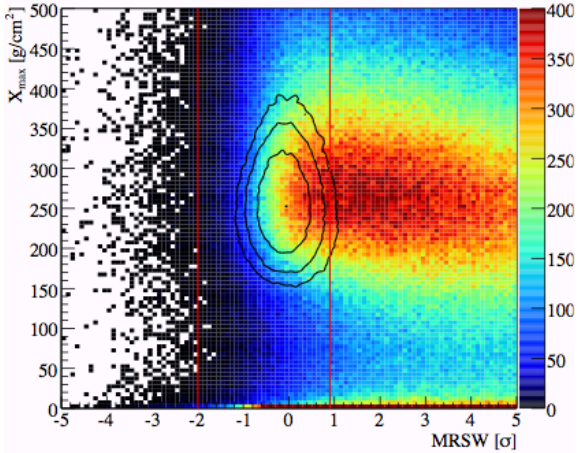


- Improve sensitivity of IACTs in the analysis
  - improve reconstruction of showers
  - two possibilities:
    - classification using MVAs and image shape parameters (e.g. neural networks, boosted decision trees)
    - use information in all pixels to do reconstruction (full-blown, CPU-intense likelihood fitting)
- Why cuts on scaled parameters are not sufficient
  - Cuts on shower shape (Width/Length) are box cuts
  - other parameters have separation potential as well (such as height of maximum Cherenkov light emission)
  - box cuts ignore correlations

→ MVAs can take care of this

Colour = CRs
Contours = γ rays

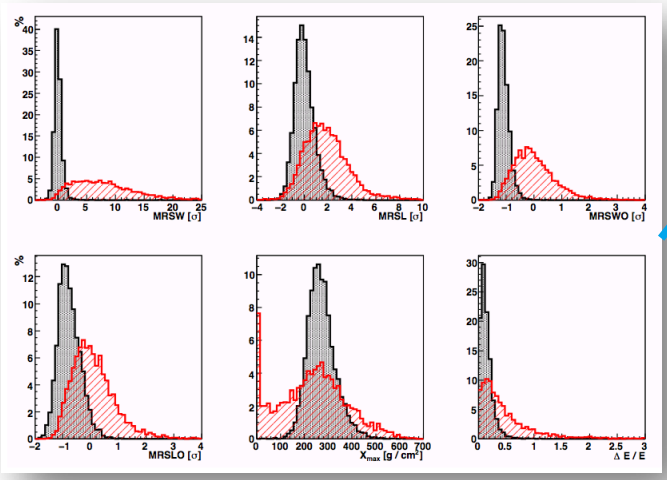


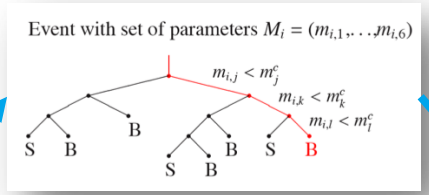


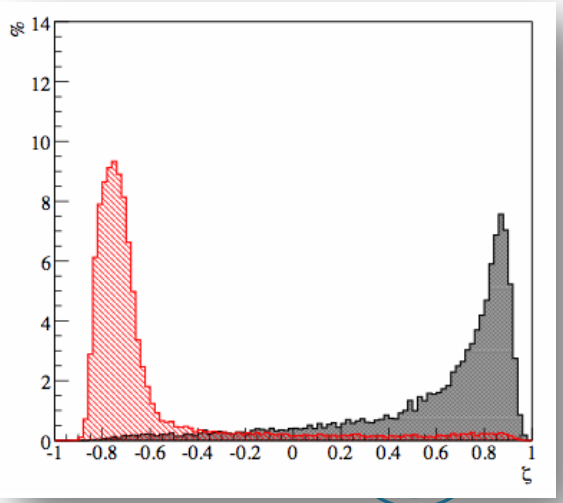
BDTs for γ/hadron classification

> BDT settings

- 200 trees trained (compromise between performance and processing)
- Gini index used to split at nodes, similar performance achieved with other techniques
- Stop splitting at $(N_1 + N_2) / (10 * N^2_{par})$ → taking into account the training statistics and number of training parameters
- Number of steps when scanning input parameters for best cut set to 100
- Input parameters (everything with classification potential)
  - MRSW, MRSL, MRSWO, MRSLO, σE/E, X_{max}
- Output is (cut) parameter that measures hadroness or γ-ray likeliness







Source: (5)

Some more details

- Training sample
  - classification should work for full dynamic range of instrument (energy, zenith angle)
  - if distribution of input parameters for signal and background change as a function of observation condition, the BDT response will change as well
  - Train in energy and zenith angle bands
  - Training statistics between 120k/240k events and 15k/25k events for γ/hadrons
  - Cut on BDT output alone not a good idea (would result in a signal efficiency that changes with observation conditions) → cut on signal efficiency instead
  - Note the range of BDT output distributions

Training statistics

Source: (5)

Zenith angle [°]	Reconstructed energy [TeV]					
	0.1–0.3	0.3–0.5	0.5–1.0	1.0–2.0	2.0–5.0	5.0–100.0
0.0–15.0	120k/240k	55k/110k	55k/115k	35k/70k	25k/45k	15k/25k
15.0–25.0	95k/190k	60k/120k	65k/125k	40k/85k/	30k/55k	15k/35k
25.0–35.0	60k/120k	65k/130k	70k/135k	50k/95k	35k/70k	20k/45k
35.0–42.5	–/–	75k/150k	75k/155k	55k/115k	45k/95k	35k/65k
42.5–47.5	–/–	55k/105k	95k/195k	75k/145k	60k/125k	50k/100k
47.5–52.5	–/–	–/–	140k/275k	100k/200k	95k/185k	80k/165k
52.5–60.0	–/–	–/–	50k/100k	70k/140k	70k/135k	70k/140k

Cut parameters for (ε_γ = 0.84/0.83)

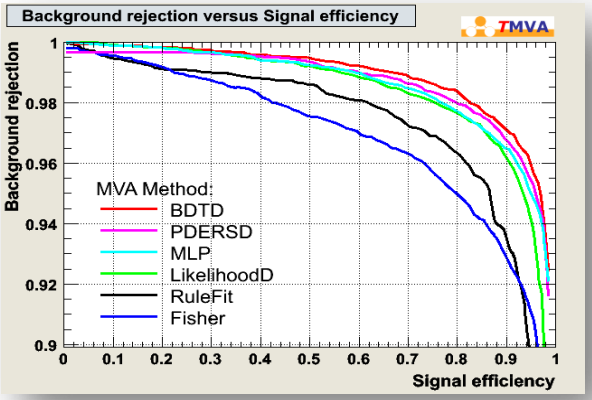
Zenith angle [°]	Reconstructed energy [TeV]					
	0.1–0.3	0.3–0.5	0.5–1.0	1.0–2.0	2.0–5.0	5.0–100.0
0.0–15.0	0.28/0.31	0.59/0.61	0.63/0.64	0.52/0.59	0.61/0.62	0.63/0.64
15.0–25.0	0.27/0.29	0.56/0.58	0.61/0.63	0.56/0.57	0.56/0.57	0.60/0.61
25.0–35.0	0.22/0.25	0.51/0.53	0.59/0.60	0.55/0.57	0.48/0.51	0.54/0.56
35.0–42.5	–/–	0.45/0.48	0.58/0.60	0.52/0.53	0.44/0.46	0.43/0.45
42.5–47.5	–/–	0.25/0.28	0.54/0.56	0.54/0.56	0.42/0.45	0.39/0.42
47.5–52.5	–/–	–/–	0.47/0.50	0.48/0.51	0.36/0.39	0.38/0.41
52.5–60.0	–/–	–/–	0.29/0.32	0.46/0.48	0.38/0.40	0.35/0.37

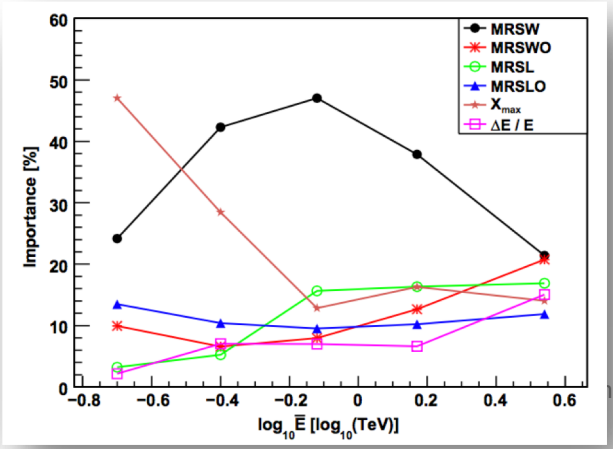
BDTs in H.E.S.S.

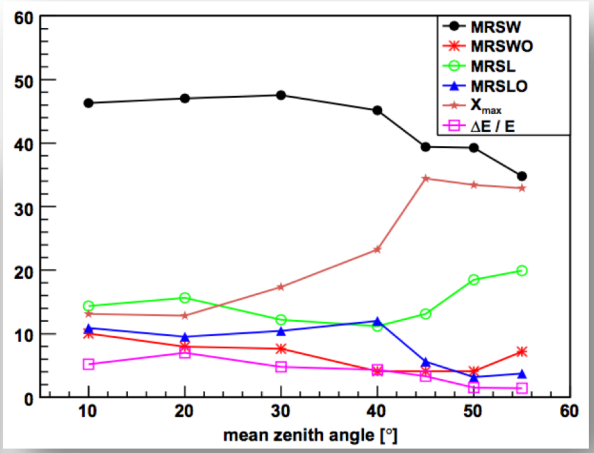
> Results

- BDTs are a robust, simple and sensitive analysis method (better than others)
- Training in energy and zenith angle bands can take out parameter dependencies
- Classifier response changes as a function of energy/zenith
- Parameter importance changes as a function of energy/zenith
  - X_{max} at low energies
  - MRSW at medium energies
  - all parameters at high energies

Source: (5)

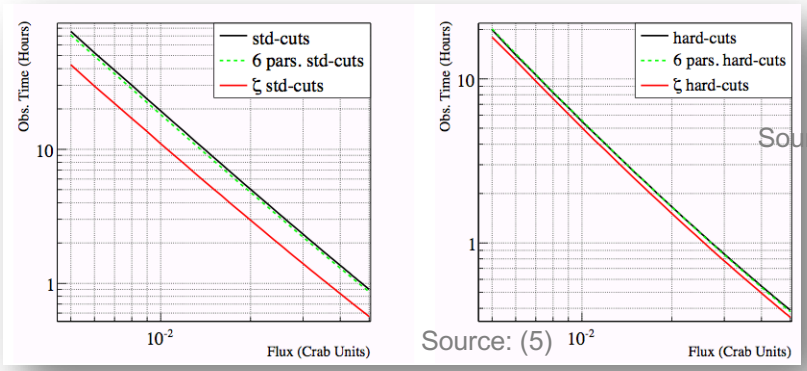






BDTs in H.E.S.S.

- Tests on real data
  - BDTs are much more sensitive than box cuts performed on individual parameters
  - for HESS and Hillas-based parameters, 45% less observation time for one cut set
  - Performance improvement across all energies
  - Very good agreement between Monte-Carlo simulations and real data
- Lessons learnt
  - Test different classifiers and settings other than default
  - Deep trees are good for complex problems
  - Easy to extend to other/more input parameters (Becherini et al. 2011, Naumann-Godo et al. 2009)



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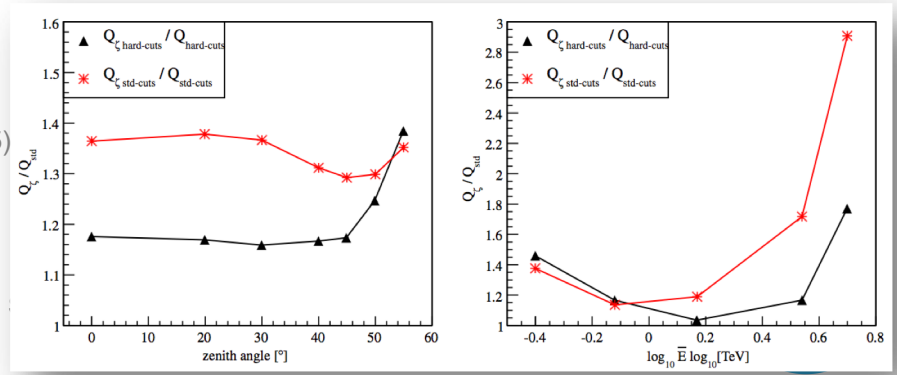
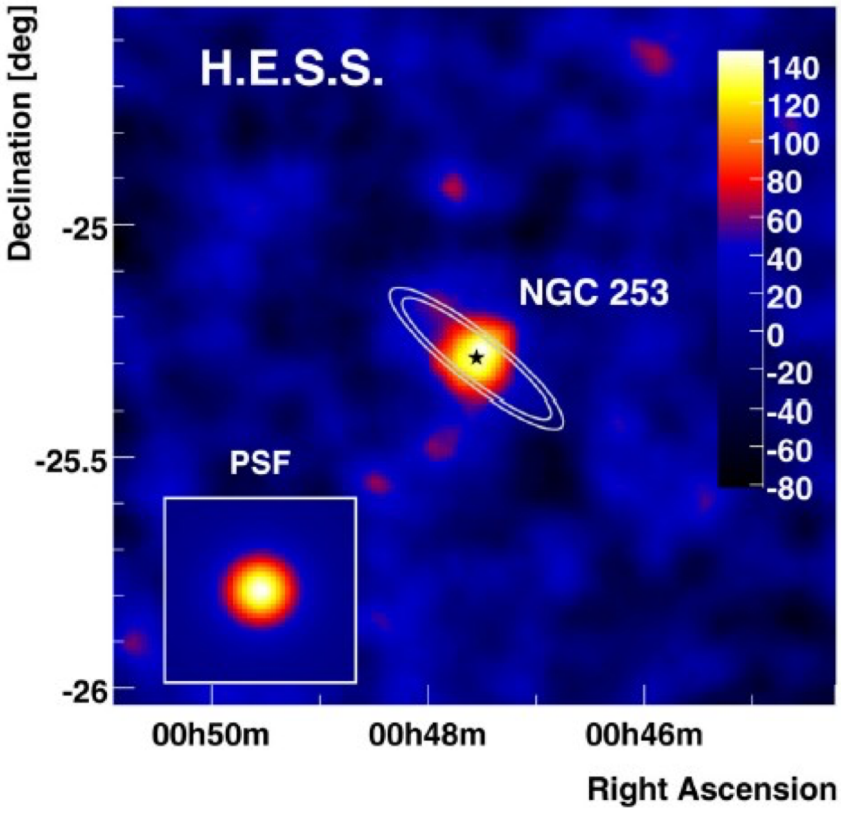
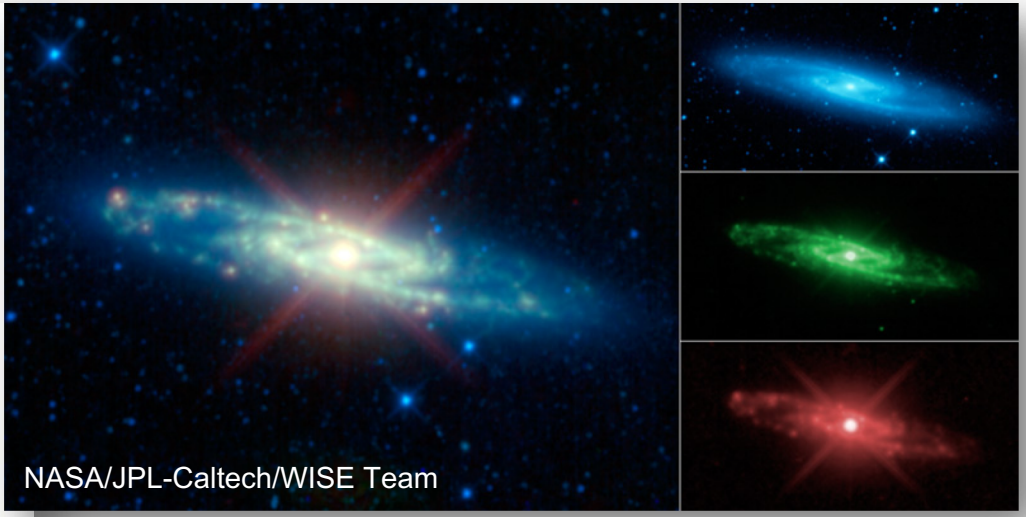


Major Achievement

- Hint of signal seen from NGC 253 after 50 hours of data taking with BDT analysis triggered deep observations

→ First detection of a Starburst Galaxy in TeV γ rays (Science, 2009)





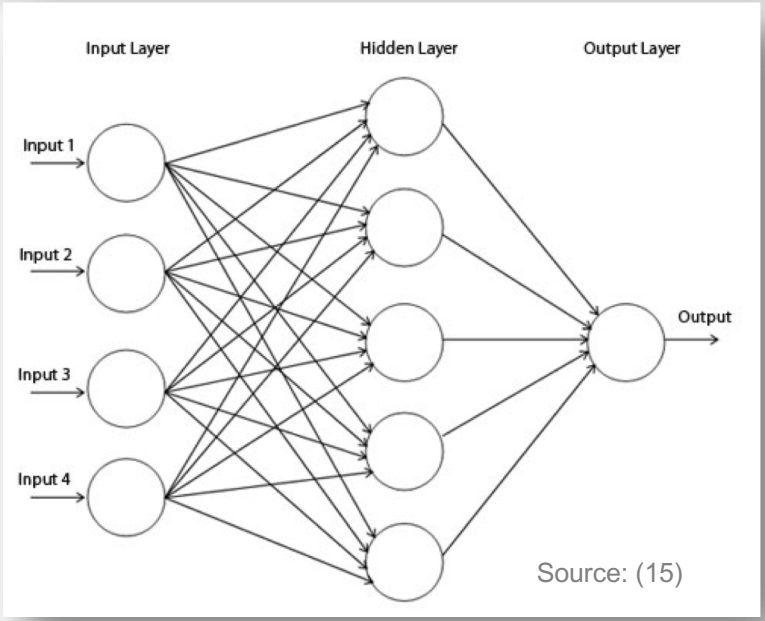
PART 2.3

Artificial Neural Networks

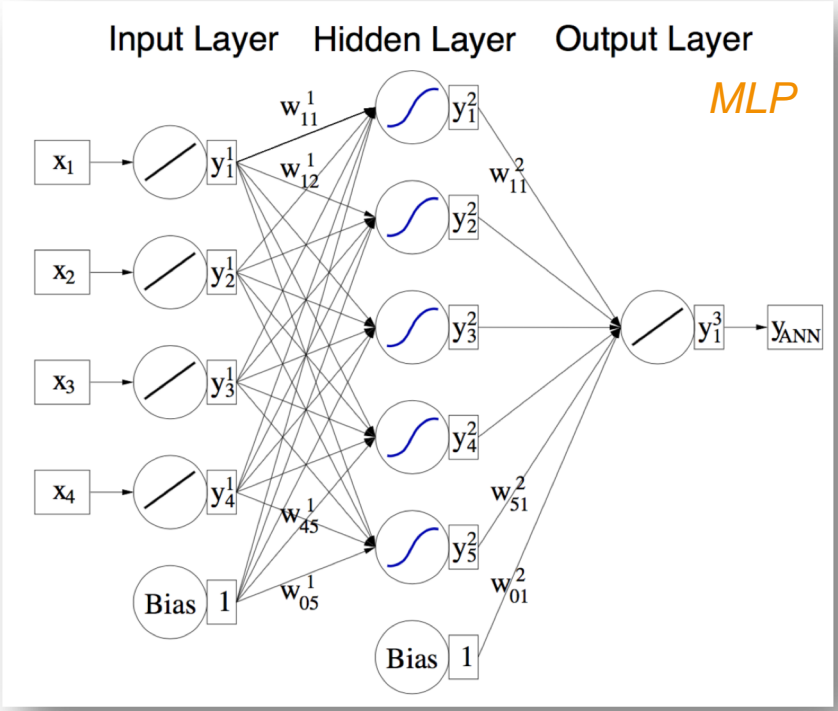
Neural Networks (NNs)

> Concept

- Inspired by humans' brain
- Is simulated collection of inter-connected "neurons"
- Each neuron returns certain response to set of input signals
- Neural net is put into defined state by applying external input signals that can be measured by the response of one (or multiple) output neurons
- Connections have numeric weights that determine importance of inputs



Working Principle



Source: (18)

> Artificial NNs

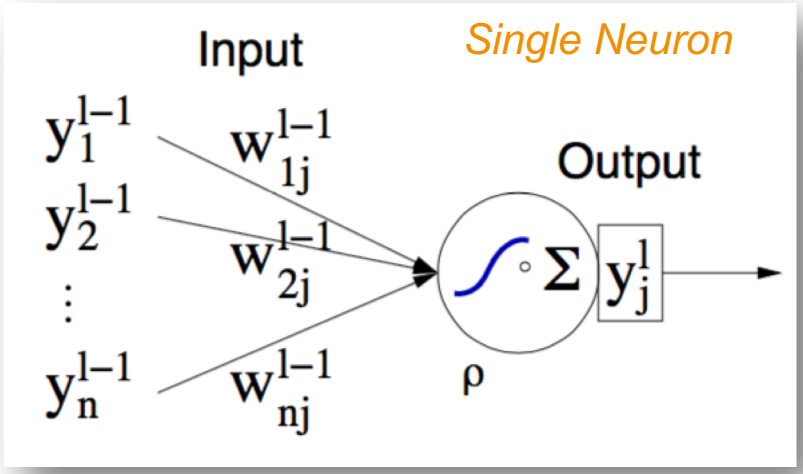
- ANN is a mapping of n-dimensional input parameter space $x_1, \ldots, x_n$ to m-dimensional output parameter space $y_1, \ldots y_m$
- $m = 1$ is classical classification problem
- mapping linear if all neurons have linear response; non-linear if response of one neuron is non-linear
- behavior is determined by
  - layout of neurons
  - weights of inter-neuron connections, w
  - and the neuron response function (activation function)
- Regression layout similar, but with one output neuron per target

Neuron response function

> Mathematical description

- neuron response function ρ maps $i_1, \ldots, i_n$ onto neuron output
- can often be separated into a synapse function κ and a neuron activation function α
- In e.g. TMVA, the functions are implemented as

$$\kappa: \ (y_1^{(\ell)}, .., y_n^{(\ell)} | w_{0j}^{(\ell)}, .., w_{nj}^{(\ell)}) \rightarrow \begin{cases} w_{0j}^{(\ell)} + \sum_{i=1}^{n} y_i^{(\ell)} w_{ij}^{(\ell)} & \textit{Sum}, \\ w_{0j}^{(\ell)} + \sum_{i=1}^{n} \left(y_i^{(\ell)} w_{ij}^{(\ell)} \right)^2 & \textit{Sum of squares}, \\ w_{0j}^{(\ell)} + \sum_{i=1}^{n} |y_i^{(\ell)} w_{ij}^{(\ell)}| & \textit{Sum of absolutes}, \end{cases}$$

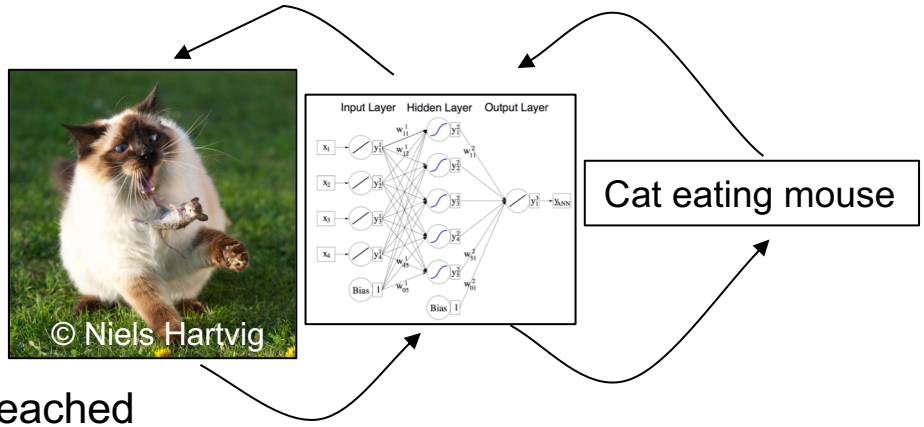


Source: (18)

$$\alpha: \ x \rightarrow \begin{cases} x & \textit{Linear}, \\ \frac{1}{1+e^{-kx}} & \textit{Sigmoid}, \\ \frac{e^x - e^{-x}}{e^x + e^{-x}} & \textit{Tanh}, \\ e^{-x^2/2} & \textit{Radial}. \end{cases}$$

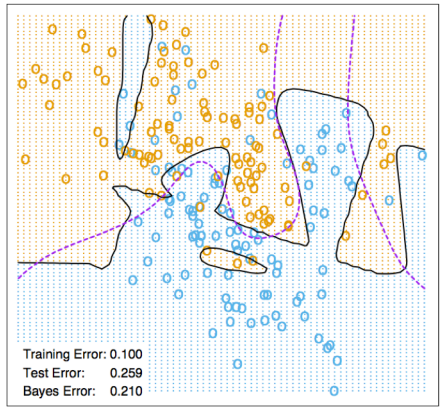
Feed-forward Networks and Learning

- Characteristics
  - ANNs are organized in layers: input, output and hidden layers
  - Each neuron in one layer is connected to all neurons in next layer → feed forward
  - No connection among neurons in same layer
- Multiple hidden layers possible
- Back-propagation and learning
  - Provide *N* training events of known type
  - Define set of input parameters
  - Let ANN classify event
  - Compare with expectation
  - Adjust weights, repeat until minimum is reached
  - Adjust weights by means of an error function (compare output with expectation)
  - change weights via gradient decent (differentiate functions)

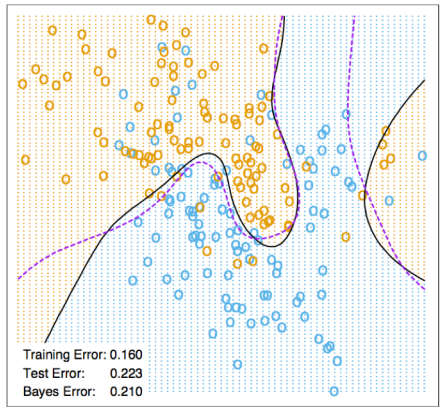


Practical training issues

- Generally
  - problem is overparametrized
  - optimisation is unstable
  - issues may appear depending on the non-linear function type used
  - Overfitting is an issue (add *weight decay* or *weight elimination* (i.e. adding penalty to the error function)
- Network architecture
  - influences the performance a lot
  - too many hidden layers is better than not enough
  - less hidden layers means worse response to non-linearities in data
  - Multiple layers allow for construction of hierarchy and search for different levels of detail (resolution) in data



Neural Network - 10 Units, Weight Decay=0.02



Source: (19)

Preliminary Summary

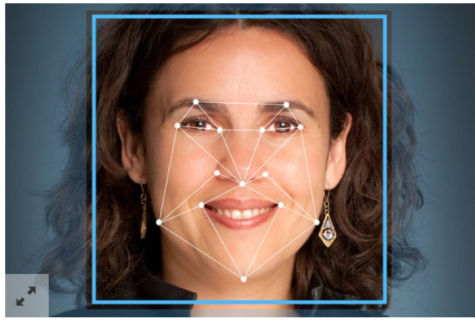
- NNs attracted a lot of attention, but
  - tend to overfit (there are ways out of it)
  - are computationally expensive
  - are black boxes
  - most applications could be realized with other, more transparent methods, achieving the same performance
  - good in cases where prediction without interpretation is required
  - less so if model interpretation is needed, or where physical quantities of inputs and their inter-relation is required
- Mid 2000's
  - Feature extraction in big data
  - renewed interest in neural networks, especially in the context of deep learning
  - industry entered the game

Deep Learning

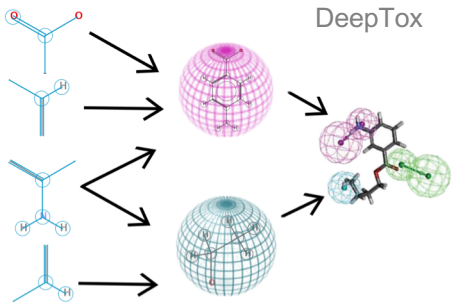
- Is the (reasonably) new kid on the block
- Most popular approach to tackle artificial intelligence (AI) problems
- Used to describe the world (i.e. data) with networks of hierarchical non-linear functions (i.e. NNs or NNs combined with other classifiers)
- Used by biggest (i.e. data-intense) internet companies in the world

Adobe facebook twitter flickr Google IBM Microsoft

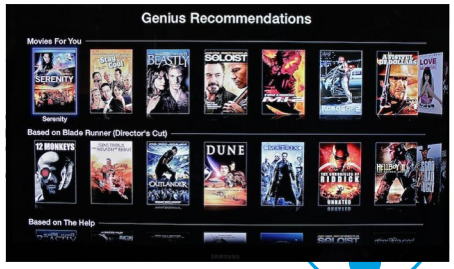
- Very successful in performing specific tasks
  - Social media (e.g. image recognition)
  - Consumer electronics (smartphones, wearables)
  - Entertainment and media (“users who bought this,…”)
  - Medicine, Defense & Intelligence



Shutterstock



DeepTox



Acknowledgement

- We are now entering the part of the lecture, Stefan didn't know much about two years ago. Hence, it is strongly influenced by recent computer science papers, blog posts, presentations, conference proceedings, and NVIDIA developer courses ☺
  - [HS1997], Hochreiter, S., and Schmidhuber, J., *"Long Short-Term Memory"*, Neural Computation, 9(8), 1735, 1997
  - [K2012] Krizhevsky, A., Sutskever, I., and Hinton, G.E., *"ImageNET Classification with Deep Convolutional Neural Networks"*, Advances in Neural Information Processing Systems 23 (NUPS 2012), 2012
  - [Z2013] Zeiler, M.D., and Fergus, R., *"Visualizing and understanding convolutional networks."*, CORR, abs/1311.2901, 2013
  - [K2015] Andrej Karpathy blog, *"The unreasonable effectiveness of recurrent neural networks",* 21.05.2015, http://karpathy.github.io/2015/05/21/rnn-effectiveness/
  - [D2014] Sander Dieleman blog, *"Recommending music on Spotify with deep learning"*, 05.08.2014, http://benanne.github.io/2014/08/05/spotify-cnns.html
  - [S2015] Schmidhuber, J., *"Deep learning in neural networks: An overview"*, Neural Networks, 61, (2015), 85 – 117
  - [M2015] Mnih, V. et al., *"Human-level control through deep reinforcement learning"*, Nature, 518, 529, 2015
  - [N2015] NVIDIA webinars/presentations on deep learning, https://developer.nvidia.com/deep-learning
  - and Wikipedia of course

Convolutional Neural Network (CNN)

- Widely used for image and video recognition
- Were very popular in the 1990's for hand-written digit classification and face detection
- Recently renewed interest thanks to
  - much larger data sets of e.g. images that are labeled (millions)
  - better model generalization strategies (see dropout method)
  - powerful GPU implementations allowing for very large models to be trained
- Utilize
  - Backpropagation (see before)
  - Receptive fields
    - multiple layers of small collections of neurons that learn about a part of an image
    - connected to better describe the boundaries
    - performed for every layer
  - Rectified Linear Units (ReLU)
    - model neuron response as f(x) = max(0,x), rather than tanh or sigmoid function

Convolutional Neural Network (CNN)

- Typical layers
  - Convolutional layers
    - convolves input image with set of learnable filters
    - reproduces one feature in the output image
    - weights are shared, i.e. same filter is used for all pixels in a receptive field
  - Pooling layer
    - compute max/average value of certain feature per sub-image

    → increase robustness to translations in images
  - Dropout method
    - prevents overtraining by leaving out nodes with probability 0.5 at each training step → new network architecture every round reduces susceptibility to rely on a few significant nodes
  - Loss layer
    - employs different loss functions for different applications (single class, probability, real values)

K2012 approach

- Idea
  - map 2D color input image to probability vector over different classes via series of layers
- Each layer consists of
  1. Convolution of previous layer output with set of learned filters
  2. Passing response through ReLU functions
  3. optionally max-pooling over neighbouring kernels
  4. optionally renormalization through contrast operation

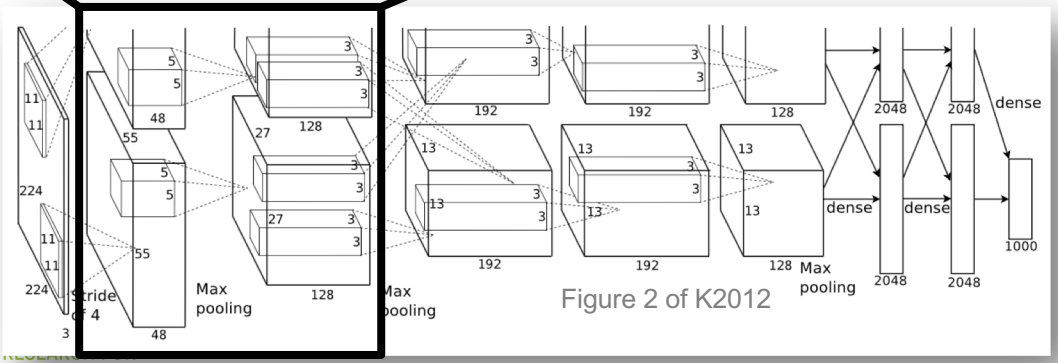


Figure 2 of K2012

Visualizing the K2012 network architecture (Z2013)

- In general hard to interpret or even to understand why certain layouts perform well
- Hence also hard to guide for future improvements
- Z2013 developed visualization technique that
  - is based on a multi-layered deconvolution network (Zeiler et al. 2011)
  - features are far from random or un-interpretable
  - reveal intuitive properties such as compositionality
  - minimum depth of network is vital to performance

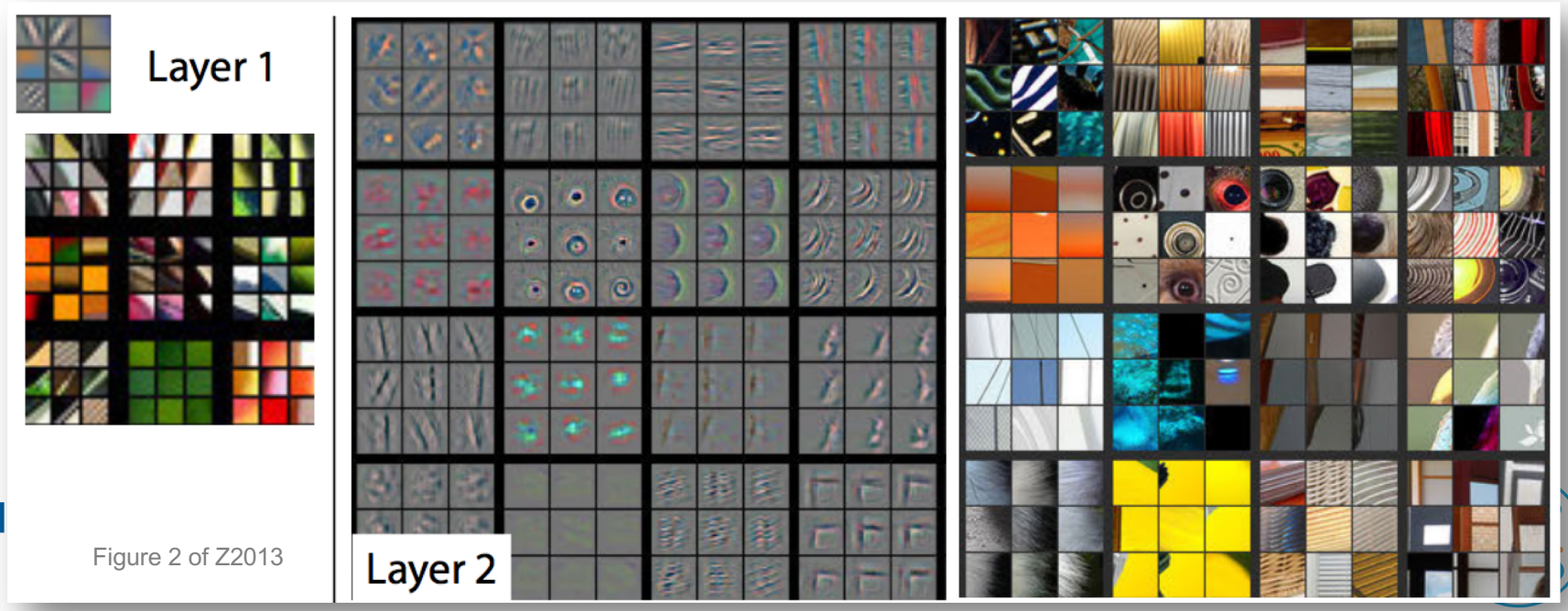
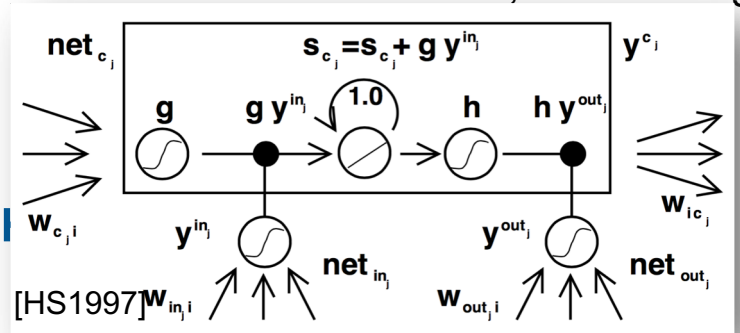


Figure 2 of Z2013

Recurrent Neural Network (RNN)

- Properties
  - have feedback connections that can ‘remember’ information about previous training events
  - put NN into internal state, allowing for dynamic behavior
- Application
  - handwriting/speech recognition
  - learning syntax from any input (latex, code, wikipedia)
- Back-propagation through time (BPTT)
  - error signals ‘flow back in time’, by connecting units to previous layers
- Reinforcement learning
  - inspired by behavioral psychology: NN interacts with environment through observation → action → reward
  - use fitness or reward function, where the goal of the NN is to maximize future reward



[HS1997]

Applications (K2015)

- How is it learning
  - Use Leo Tolstoys “War and Peace” as training input, sample every x training cycles
  - 100 cycles: jibberish, but note words separated by spaces

```
tyntd-iafhatawiaoihrdemot  lytdws  e ,tfti, astai f ogoh eoase rrranbyne 'nhthnee e
plia tklrgd t o idoe ns,smtt   h ne etie h,hregtrs nigtike,aoaenns lng
```

  - 300 cycles: learns periods at end are followed by spaces

```
"Tmont thithey" fomesscerliund
Keushey. Thom here
sheulke, anmerenith ol sivh I lalterthend Bleipile shuwy fil on aseterlome
coaniogennc Phe lism thond hon at. MeiDimorotion in ther thize."
```

  - 500 cycles: shortest and most common words

```
we counter. He stutn co des. His stanted out one ofler that concossions and was
to gearang reay Jotrets and with fre colt otf paitt thin wall. Which das stimn
```

  - 700 cycles: more and longer words appearing

```
Aftair fall unsuch that the hall for Prince Velzonski's that me of
her hearly, and behs to so arwage fiving were to it beloge, pavu say falling misfort
how, and Gogition is so overelical and ofter.
```

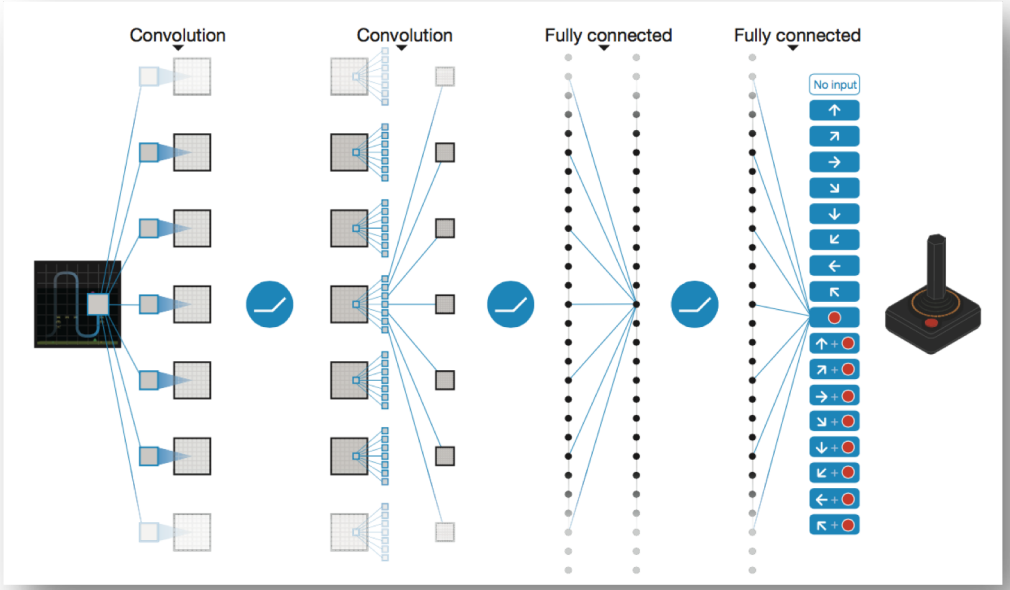
  - 2000 cycles: quotations, questions, exclamation marks, names, words

```
"Why do what that day," replied Natasha, and wishing to himself the fact the
princess, Princess Mary was easier, fed in had oftened him.
Pierre aking his soul came to the packs and drove up his father-in-law women.
```

Learning NNs to play ATARI 2600 games (M2015)

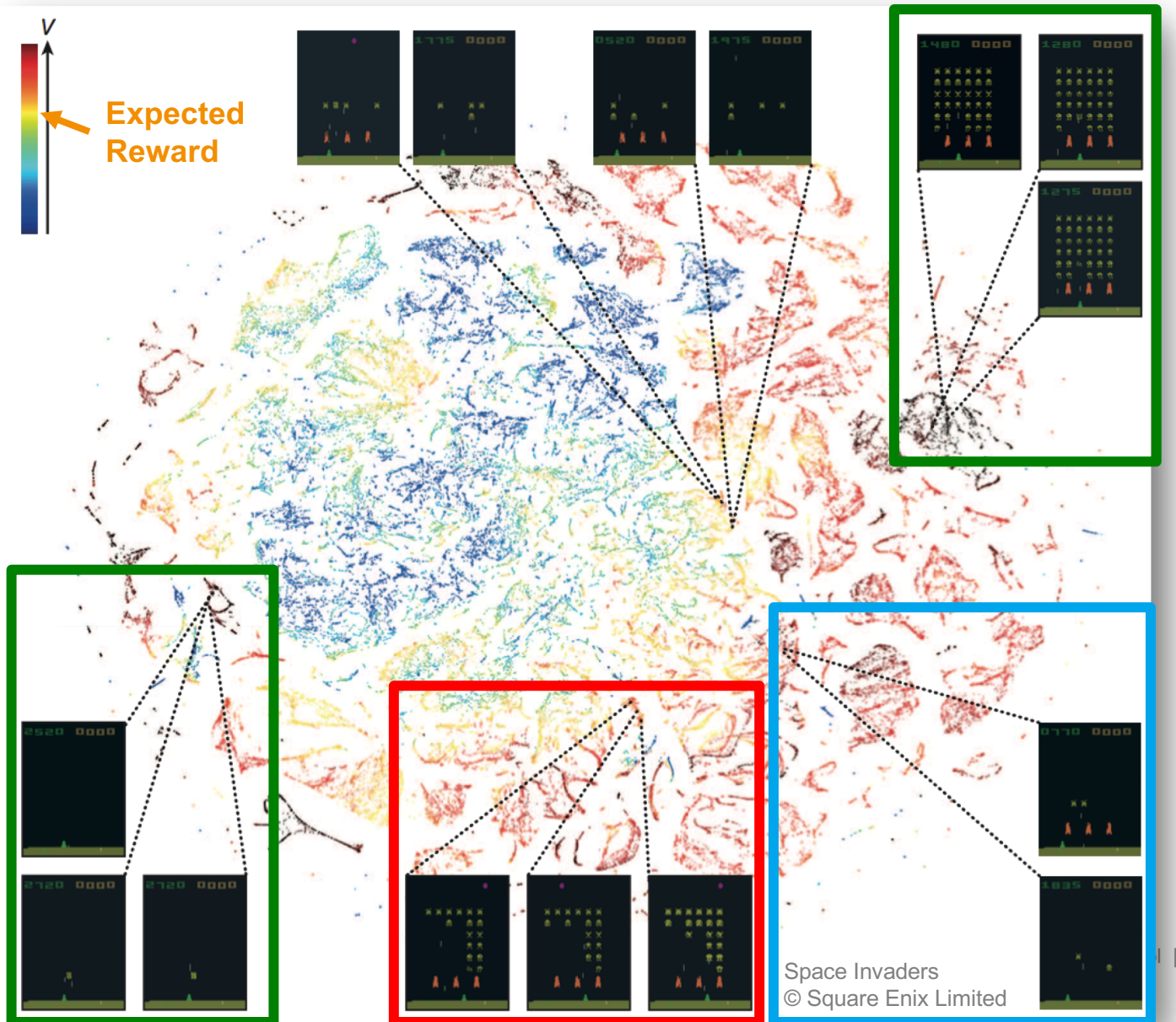
- Layout
  - combines reinforcement learning (LSTMs) with convolutional NNs
  - 84 x 84 x 4 image followed by 3 convolutional layers, and 2 fully connected layers
  - output is action with joystick
  - hidden layers are followed by ReLUs
- Training
  - each game is one set of trained NN
  - via a reward function
  - agent selects from set of allowed actions, changing internal state → modifying the emulator → reward

  → NN learns based on sequences of actions and observations



Learning NNs to play ATARI 2600 games (M2015)

Visualizing game states of last hidden layer



- High reward scenes
  - completing a screen leads to a new screen
- Medium reward scenes
  - in the middle of a level, where rewards are less imminent
  - orange bunkers not that significant towards end of level

DESY.

How come there is so much fuzz about that now? (N2015)

- Answer is simple
  - Big Data to learn deep neural networks
  - New deep learning techniques, and (most importantly)
  - computing power via CPUs and GPUs
- Why GPUs
  - Neural Networks explore functions, matrices, vector operations, connections
  - Requires many cores to perform calculations (cloud-like CPU computing infrastructure)
  - GPUs are designed for these kind of operations (e.g. *"Deep learning with COTS HPC systems"*, Coates, et al. ICML 2013)
  - GPUs make deep learning accessible when organized in servers with interconnections

Google datacenter

1000 CPU servers
2000 CPUs
16,000 cores

600kWatts, $5M

3 GPU-acc. servers
12 GPUs
18,432 cores

4kWatts, $33k

Stanford AI labs

That's the game changer

Summary and outlook

- Big Data
  - we are drowning in data, but
  - we have tools to crawl data for relevant information
- Machine Learning
  - is the way to go
  - just have to be smart about the methods and decide what tools to use when/how
- Deep Neural Networks
  - are widely used in industry nowadays
  - if things are industry standard, good to think about how to use them in science
  - GPUs have revolutionized the field
  - Application to scientific data only starting in the last few years.

Literature and References

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